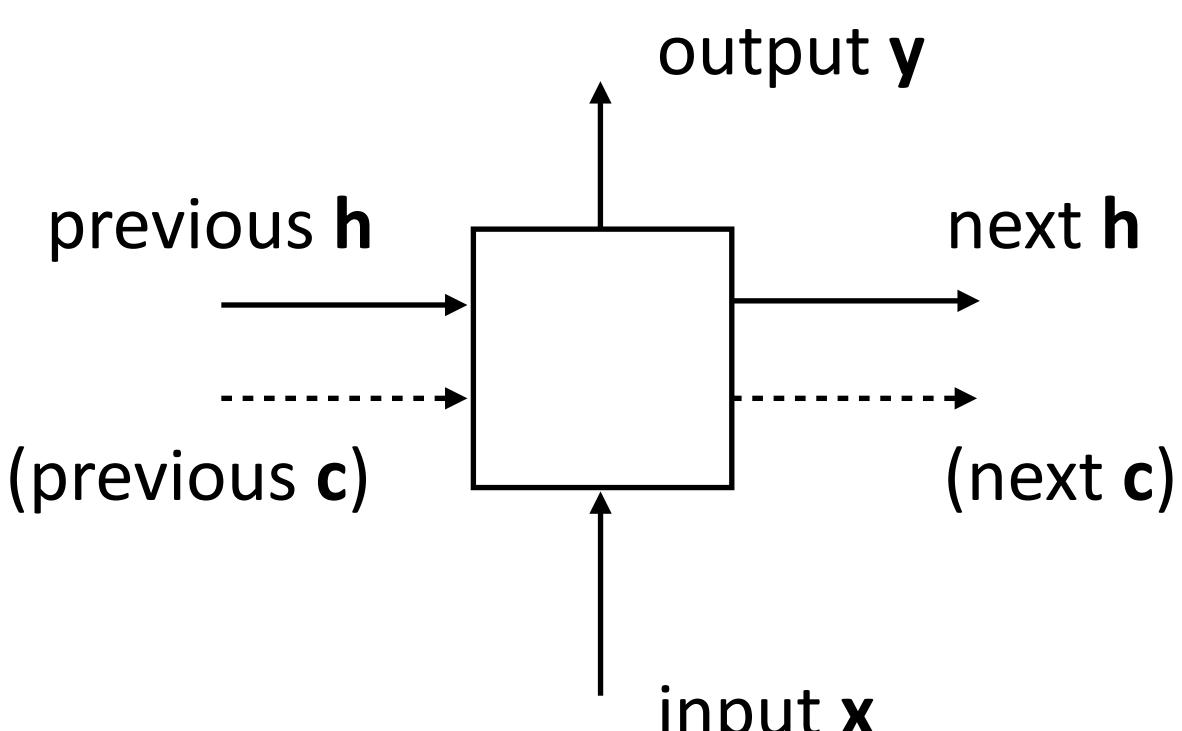
# Lecture 9: CNNs, Neural CRFs

### Alan Ritter

(many slides from Greg Durrett)

## **Recall: RNNs**

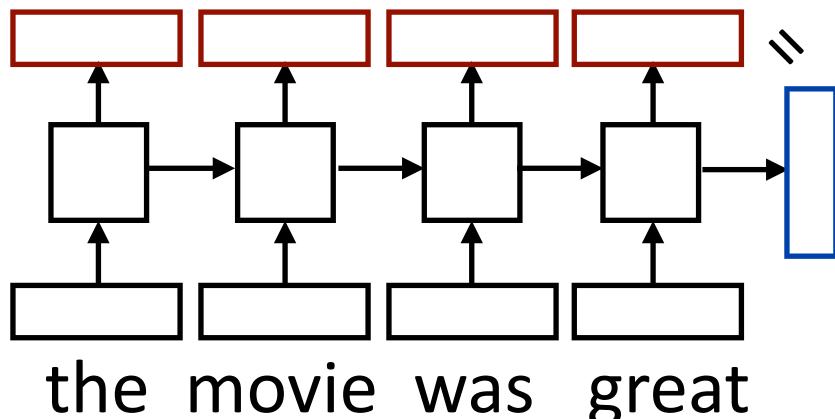
hidden state and produces output y (all vector-valued)



Cell that takes some input x, has some hidden state h, and updates that

input **x** 

# **Recall: RNN Abstraction**



- Encoding of the sentence can pass this a decoder or make a classification decision about the sentence
- Encoding of each word can pass this to another layer to make a prediction (can also pool these to get a different sentence encoding) RNN can be viewed as a transformation of a sequence of vectors into a sequence of context-dependent vectors

# What can LSTMs model?

- Sentiment
  - Encode one sentence, predict
- Language models
  - Move left-to-right, per-token prediction
- Translation
  - Encode sentence + then decode, use token predictions for attention weights (next lecture)

# What can LSTMs model?

- Sentiment
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- Textual entailment

# What can LSTMs model?

- Sentiment
  - Encode one sentence, predict
- Language models
  - Move left-to-right, per-token prediction
- Translation
  - Encode sentence + then decode, use token predictions for attention weights (next lecture)
- Textual entailment
  - Encode two sentences, predict

### Premise

### A boy plays in the snow

### Hypothesis

A boy is outside

### Premise

### A boy plays in the snow

### Hypothesis

### A boy is outside

entails

entails

### Premise

### A boy plays in the snow

A man inspects the uniform of a figure

### Hypothesis

### A boy is outside

The man is sleeping

### Premise

### A boy plays in the snow

A man inspects the uniform of a figure

### Hypothesis

### *entails* A boy is outside

contradicts

The man is sleeping

### Premise

### A boy plays in the snow

A man inspects the uniform of a figure

An older and younger man smiling

### Hypothesis

entails

A boy is outside

contradicts

The man is sleeping Two men are smiling and laughing at cats playing



### Premise

### A boy plays in the snow

A man inspects the uniform of a figure

An older and younger man smiling

### Hypothesis

A boy is outside entails

contradicts

neutral

The man is sleeping Two men are smiling and laughing at cats playing



### Premise

### A boy plays in the snow

A man inspects the uniform of a figure

An older and younger man smiling

Long history of this task: "Recognizing Textual Entailment" challenge in 2006 (Dagan, Glickman, Magnini)

### Hypothesis

A boy is outside entails

contradicts The man is sleeping Two men are smiling and neutral laughing at cats playing



### Premise

### A boy plays in the snow

A man inspects the uniform of a figure

An older and younger man smiling

- 2006 (Dagan, Glickman, Magnini)
- knowledge, temporal reasoning, etc.)

### Hypothesis

A boy is outside entails

contradicts The man is sleeping Two men are smiling and neutral laughing at cats playing

Long history of this task: "Recognizing Textual Entailment" challenge in

Early datasets: small (hundreds of pairs), very ambitious (lots of world



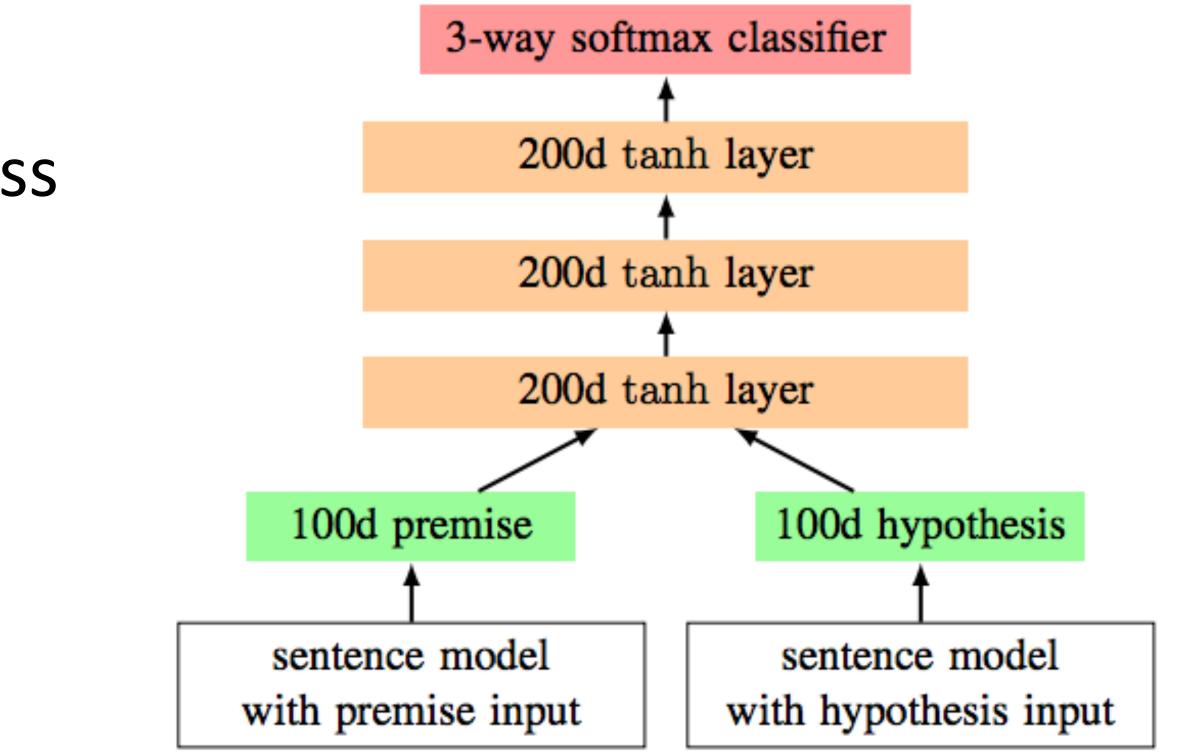
- contradictory statements
- >500,000 sentence pairs

Show people captions for (unseen) images and solicit entailed / neural /



- contradictory statements
- >500,000 sentence pairs
- Encode each sentence and process

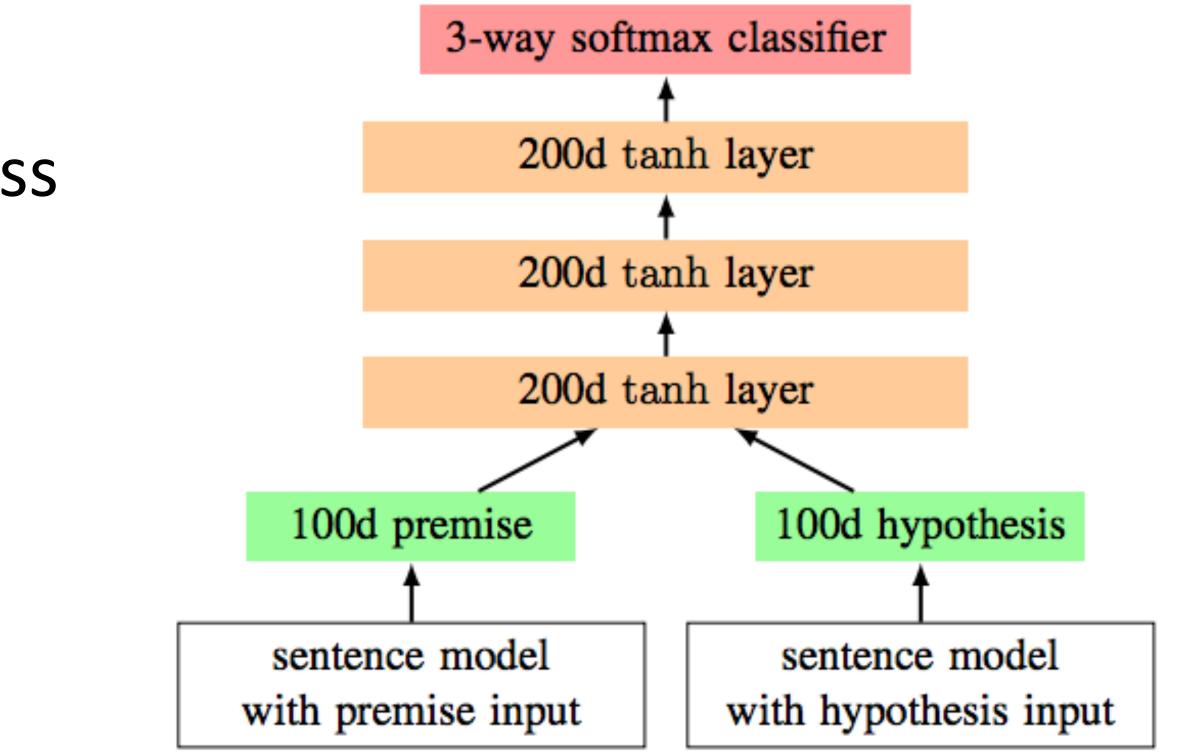
Show people captions for (unseen) images and solicit entailed / neural /





- contradictory statements
- >500,000 sentence pairs
- Encode each sentence and process 100D LSTM: 78% accuracy

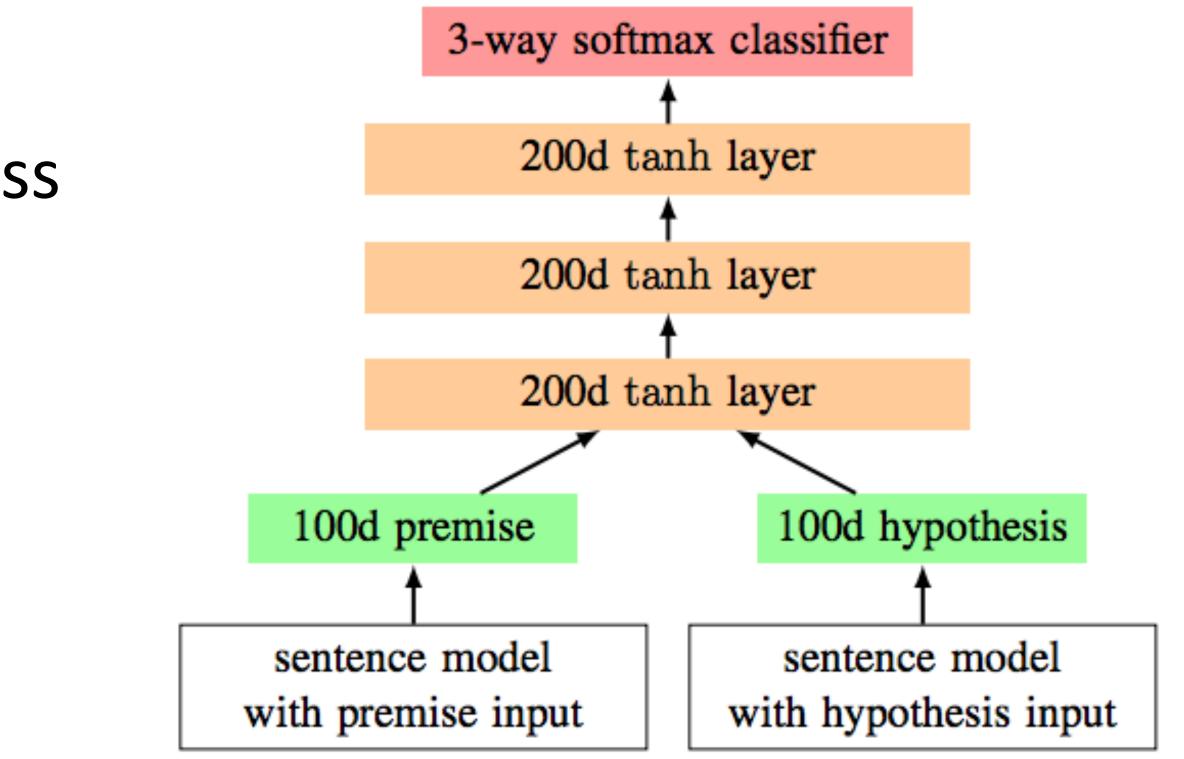
Show people captions for (unseen) images and solicit entailed / neural /





- contradictory statements
- >500,000 sentence pairs
- Encode each sentence and process 100D LSTM: 78% accuracy 300D LSTM: 80% accuracy (Bowman et al., 2016)

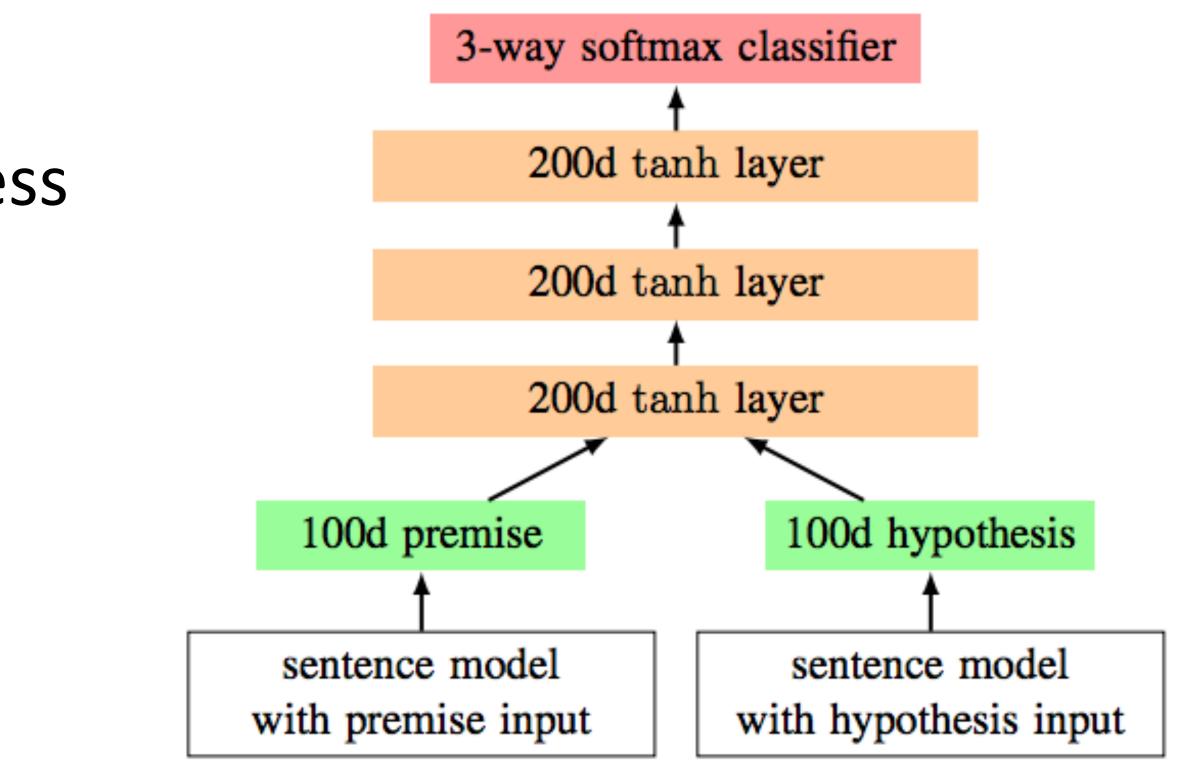
Show people captions for (unseen) images and solicit entailed / neural /





- contradictory statements
- >500,000 sentence pairs
- Encode each sentence and process 100D LSTM: 78% accuracy 300D LSTM: 80% accuracy (Bowman et al., 2016) 300D BiLSTM: 83% accuracy (Liu et al., 2016)

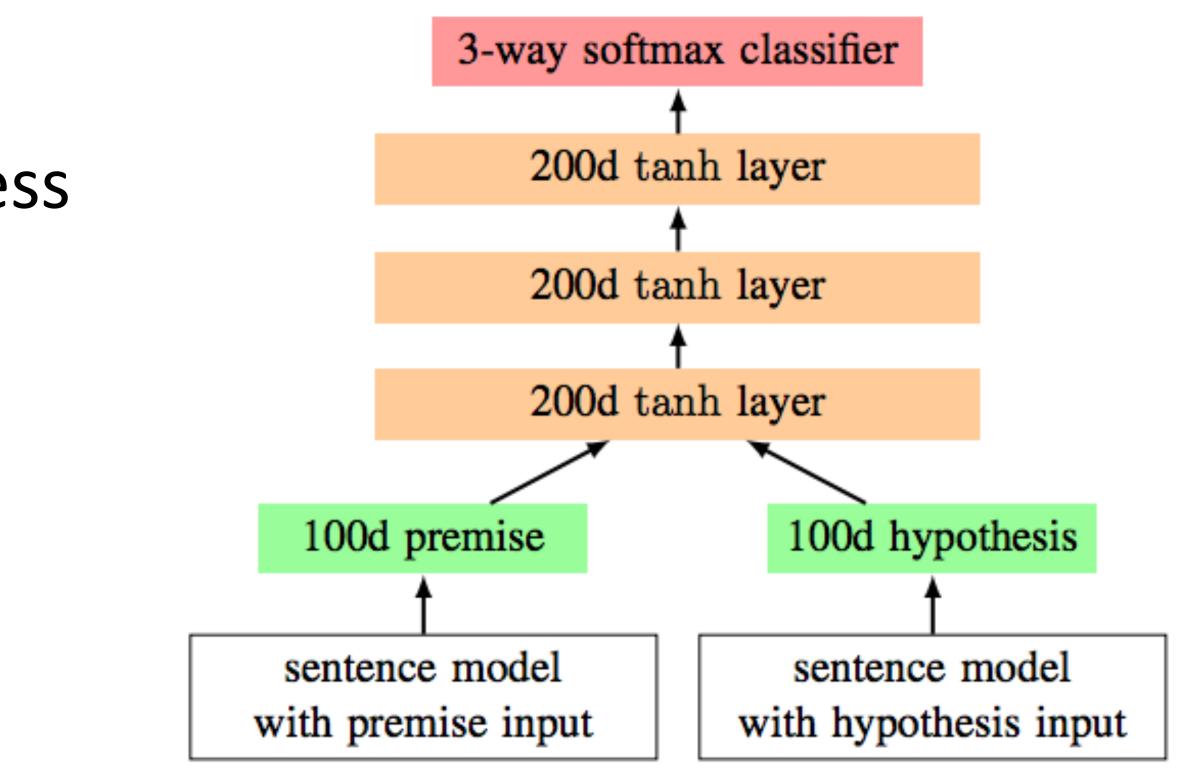
Show people captions for (unseen) images and solicit entailed / neural /





- contradictory statements
- >500,000 sentence pairs
- Encode each sentence and process 100D LSTM: 78% accuracy 300D LSTM: 80% accuracy (Bowman et al., 2016) 300D BiLSTM: 83% accuracy (Liu et al., 2016) Later: better models for this

Show people captions for (unseen) images and solicit entailed / neural /





### CNNs

### CNNs for Sentiment

Neural CRFs

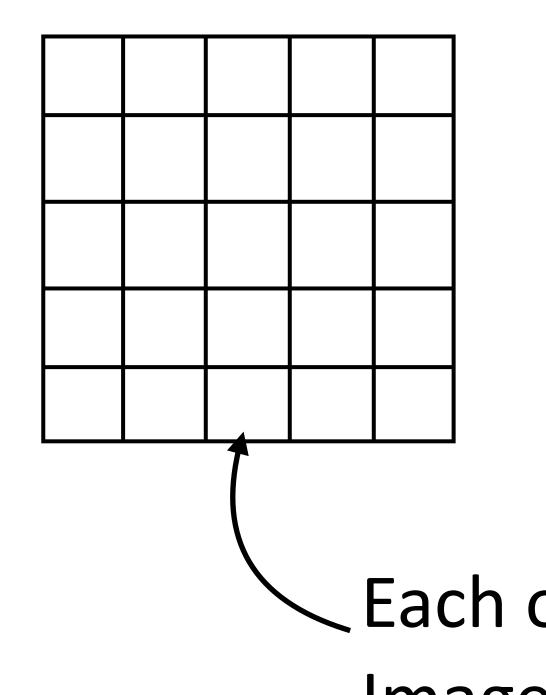
### This Lecture

# CNNS

- Applies a *filter* over patches of the input and returns that filter's activations
- Convolution: take dot product of filter with a patch of the input



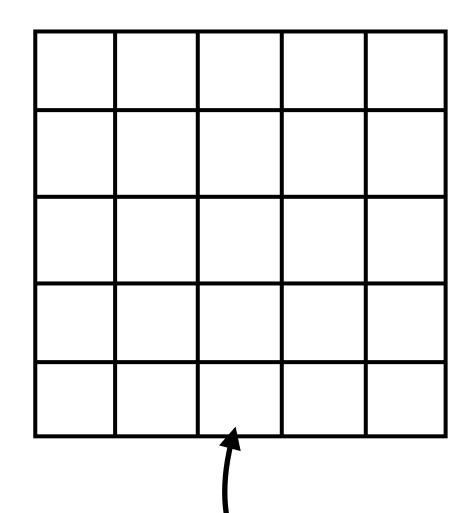
- Applies a *filter* over patches of the input and returns that filter's activations
- Convolution: take dot product of filter with a patch of the input
- image: n x n x k

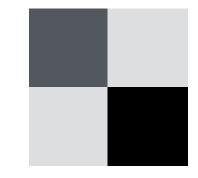


Each of these cells is a vector with multiple values Images: RGB values (3 dim)



- Applies a *filter* over patches of the input and returns that filter's activations
- Convolution: take dot product of filter with a patch of the input
- image: n x n x k filter: m x m x k



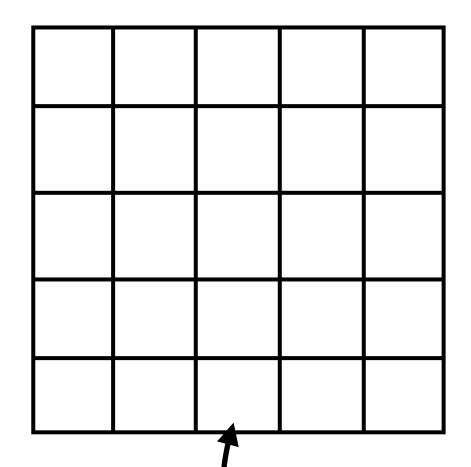


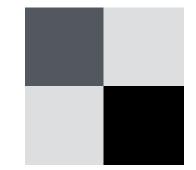
Each of these cells is a vector with multiple values Images: RGB values (3 dim)



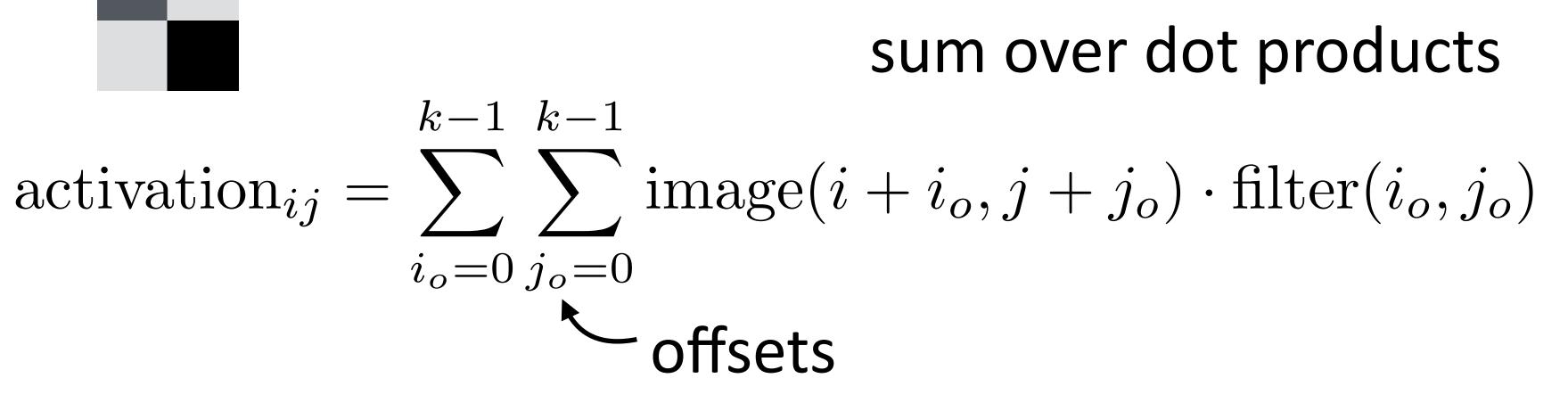
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Images: RGB values (3 dim)



Each of these cells is a vector with multiple values



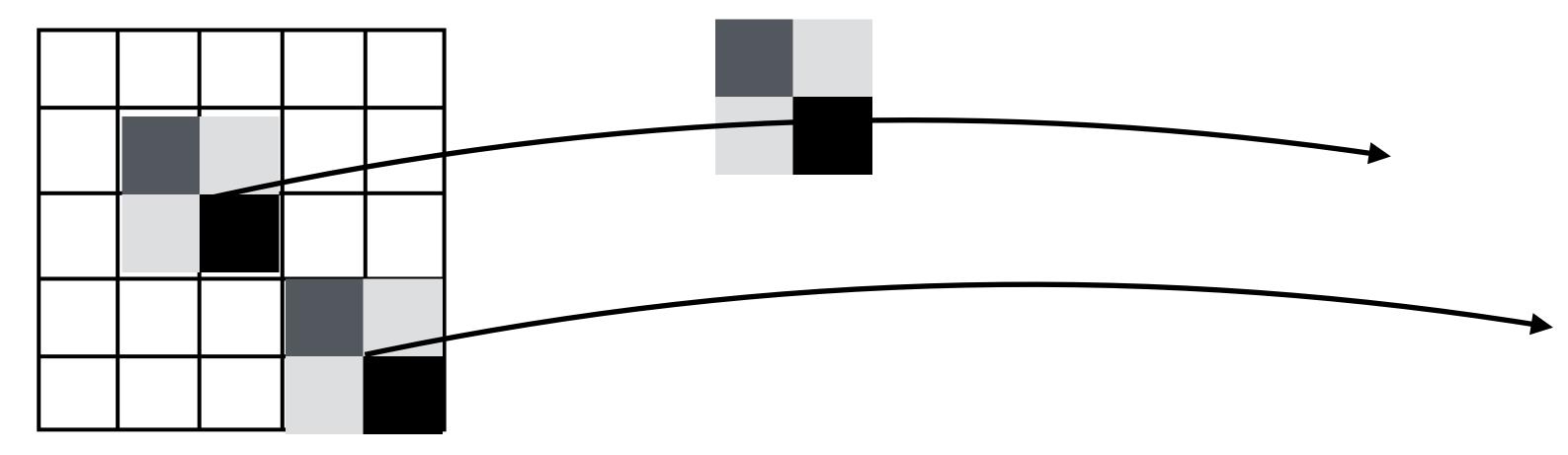
- Applies a *filter* over patches of the input and returns that filter's activations
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- image: n x n x k filter: m x m x k





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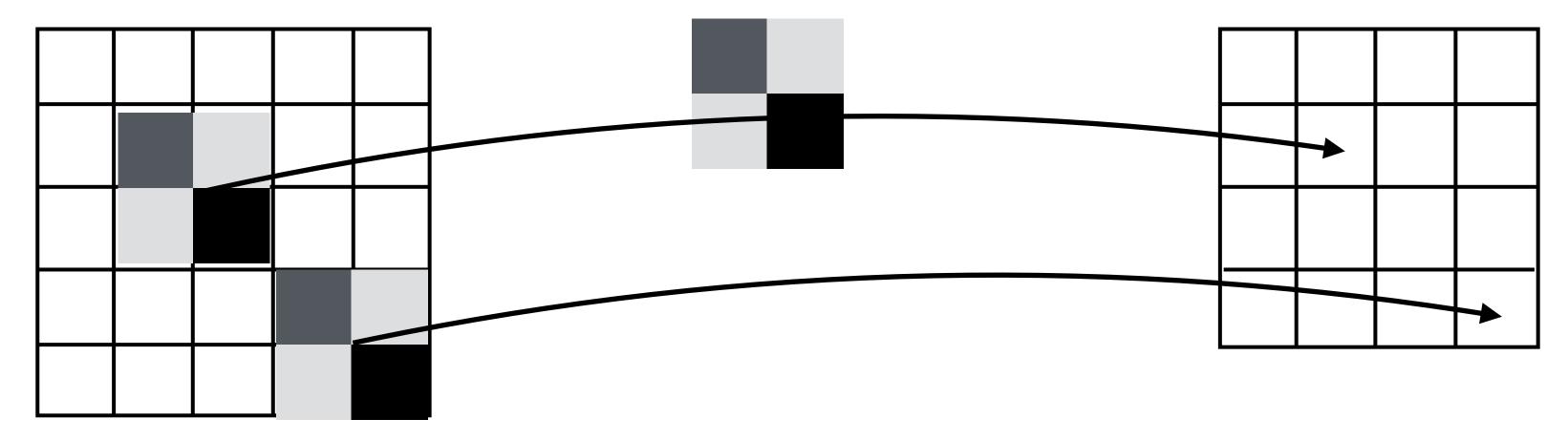


image:  $n \times n \times k$  filter:  $m \times m \times k$  activations:  $(n - m + 1) \times (n - m + 1) \times 1$ 

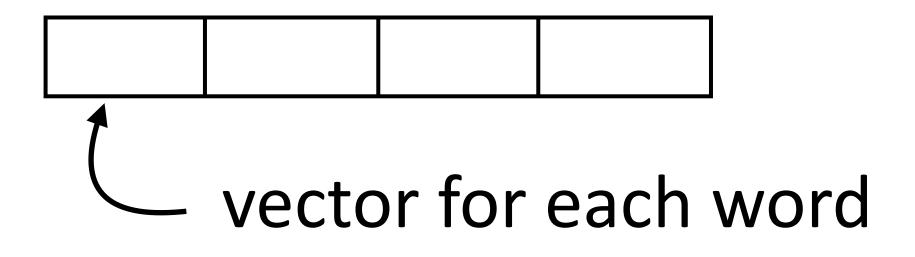


Input and filter are 2-dimensional instead of 3-dimensional

Input and filter are 2-dimensional instead of 3-dimensional

sentence: n words x k vec dim

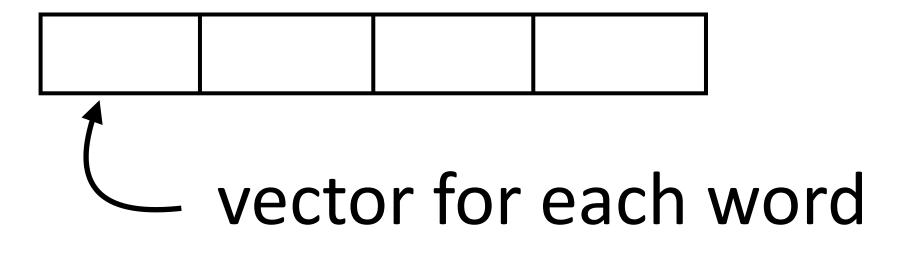
the movie was good



Input and filter are 2-dimensional instead of 3-dimensional

sentence: n words x k vec dim

the movie was good



### filter: m x k



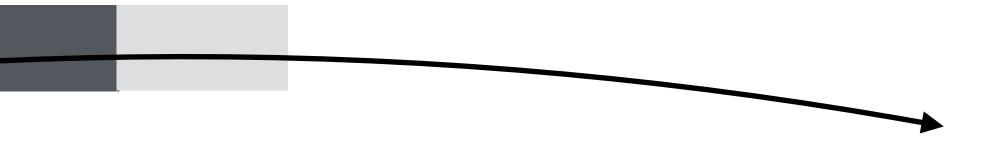
Input and filter are 2-dimensional instead of 3-dimensional

sentence: n words x k vec dim

the movie was good

vector for each word

### filter: m x k



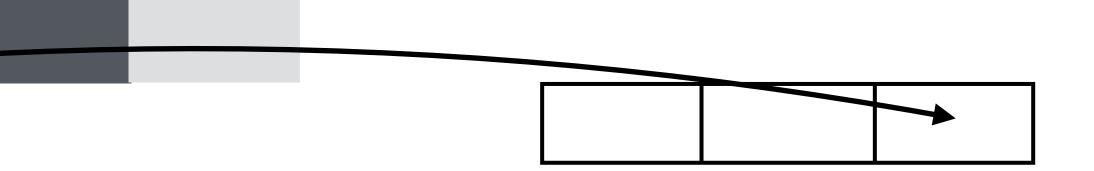
Input and filter are 2-dimensional instead of 3-dimensional

sentence: n words x k vec dim

the movie was good

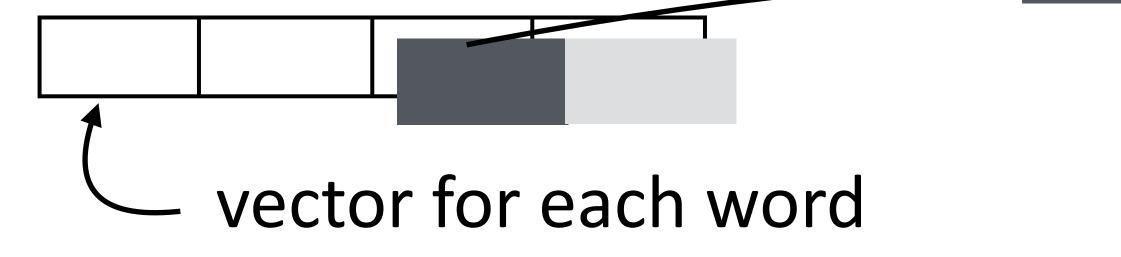
vector for each word

filter: m x k activations:  $(n - m + 1) \times 1$ 



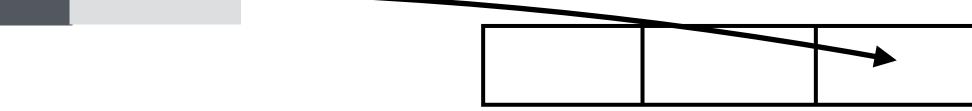
- Input and filter are 2-dimensional instead of 3-dimensional
- sentence: n words x k vec dim

the movie was good



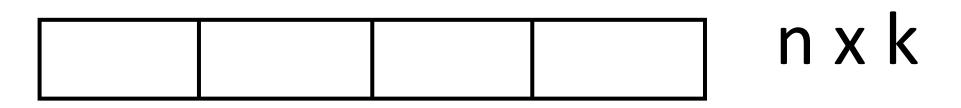
variable-length) representation





Combines evidence locally in a sentence and produces a new (but still

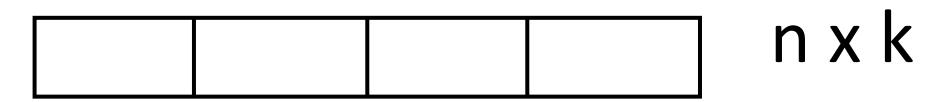
# Compare: CNNs vs. LSTMs

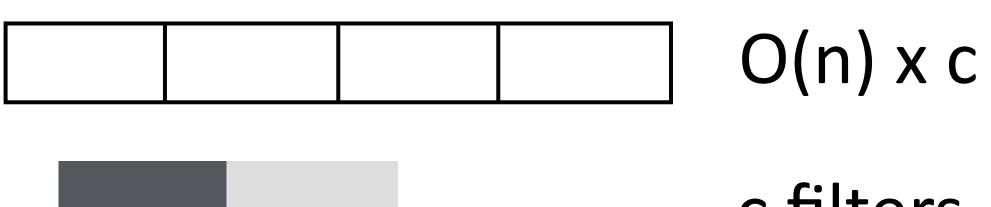


### the movie was good

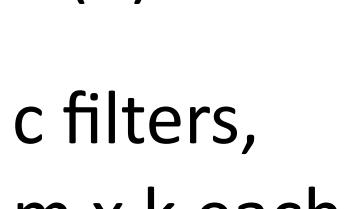


c filters, m x k each

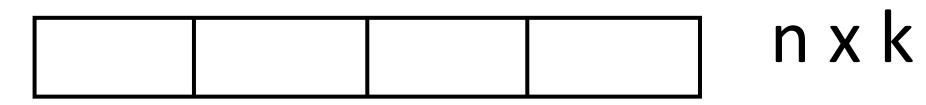


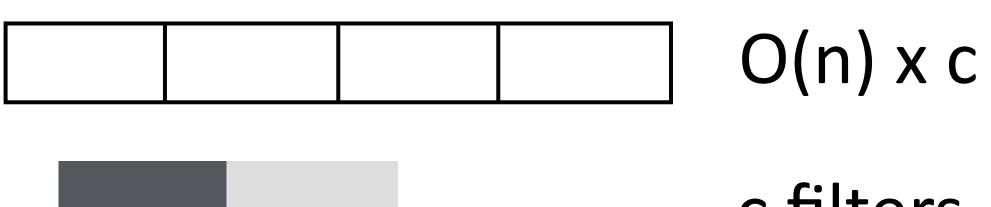




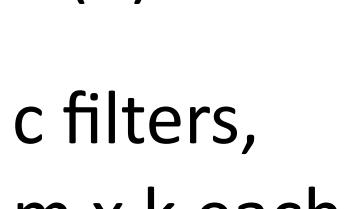




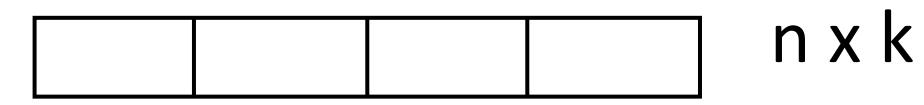






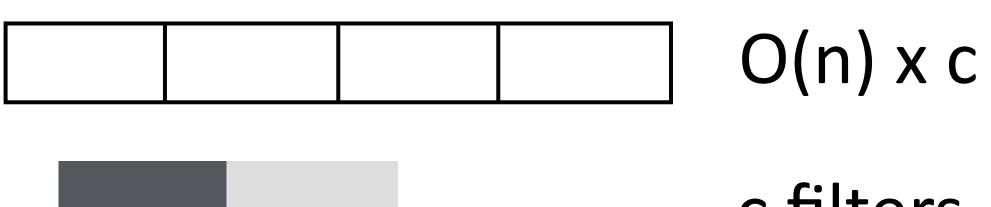




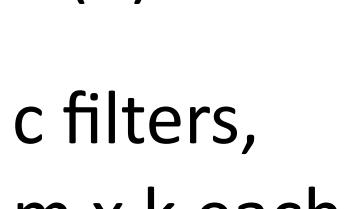


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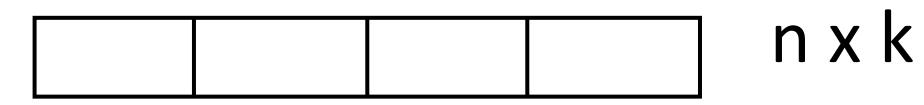
### n x k



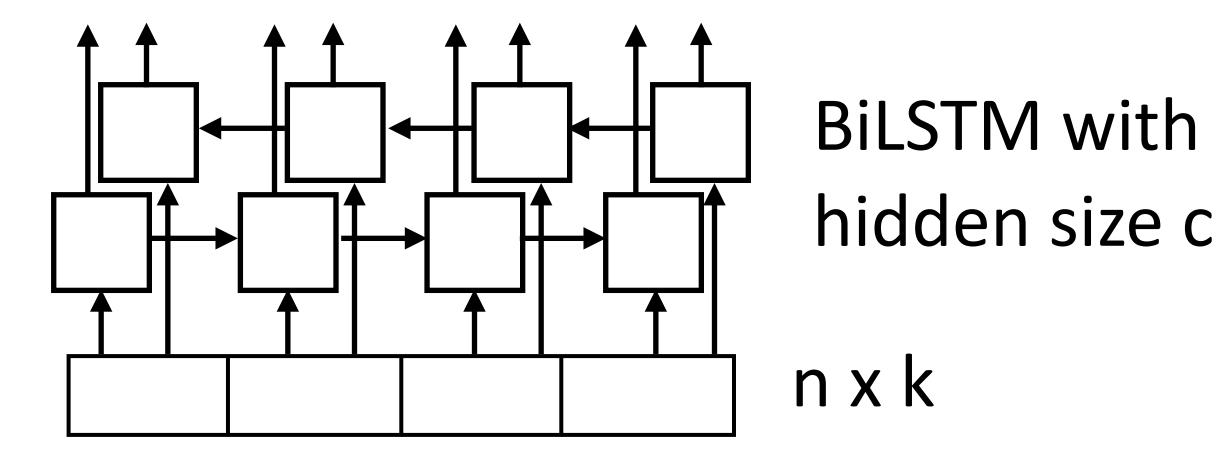


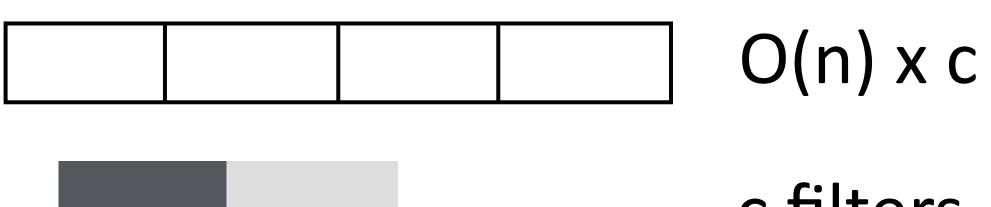




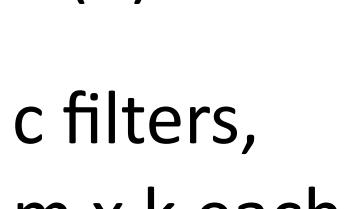


the movie was good

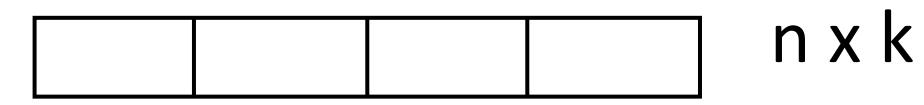




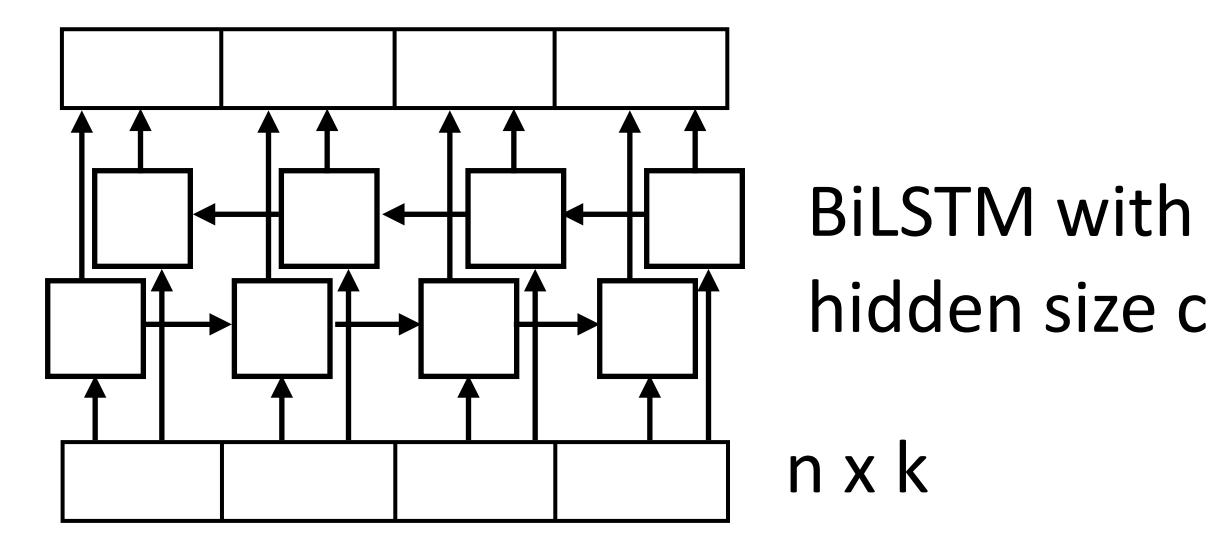


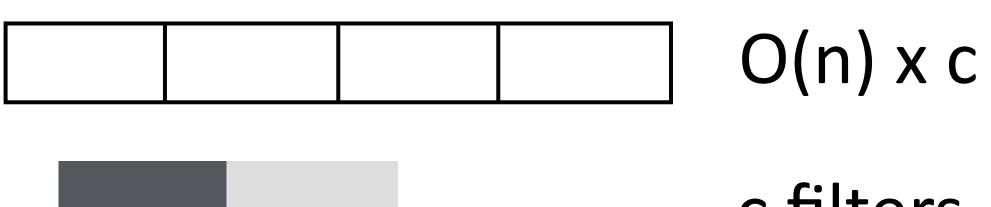




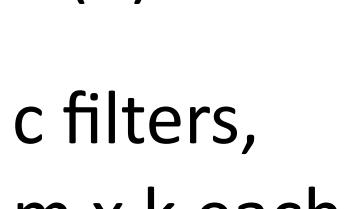


the movie was good

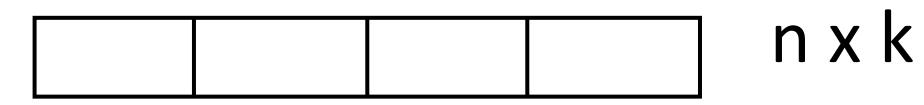




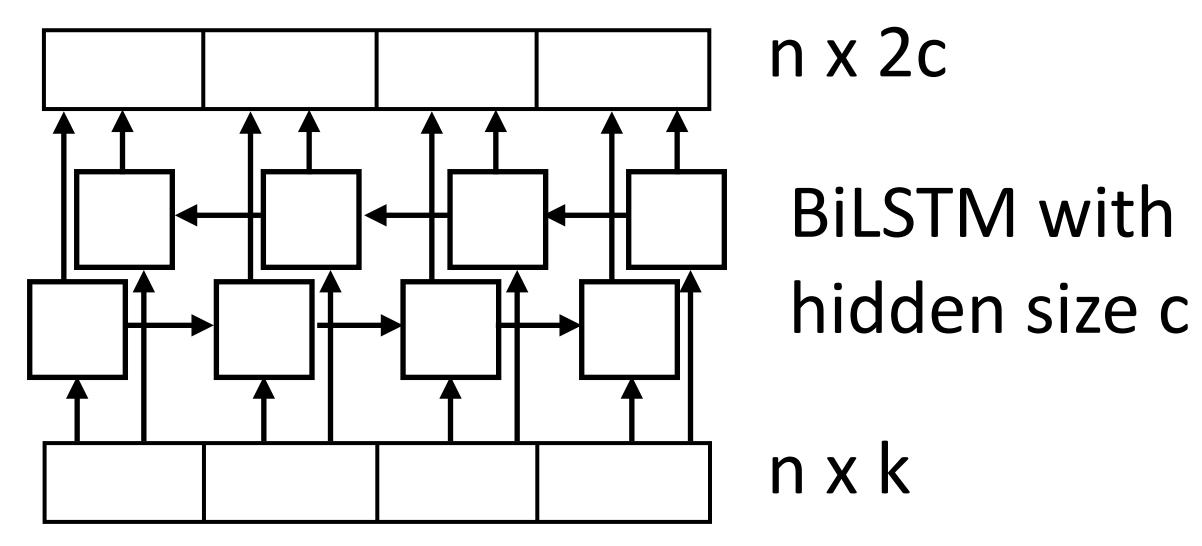


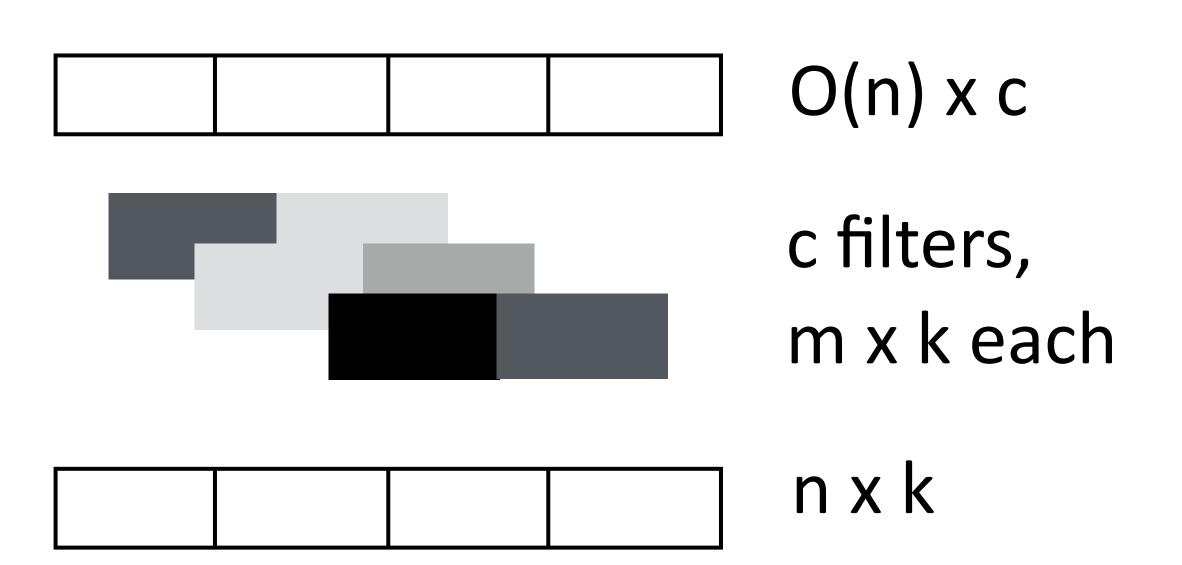




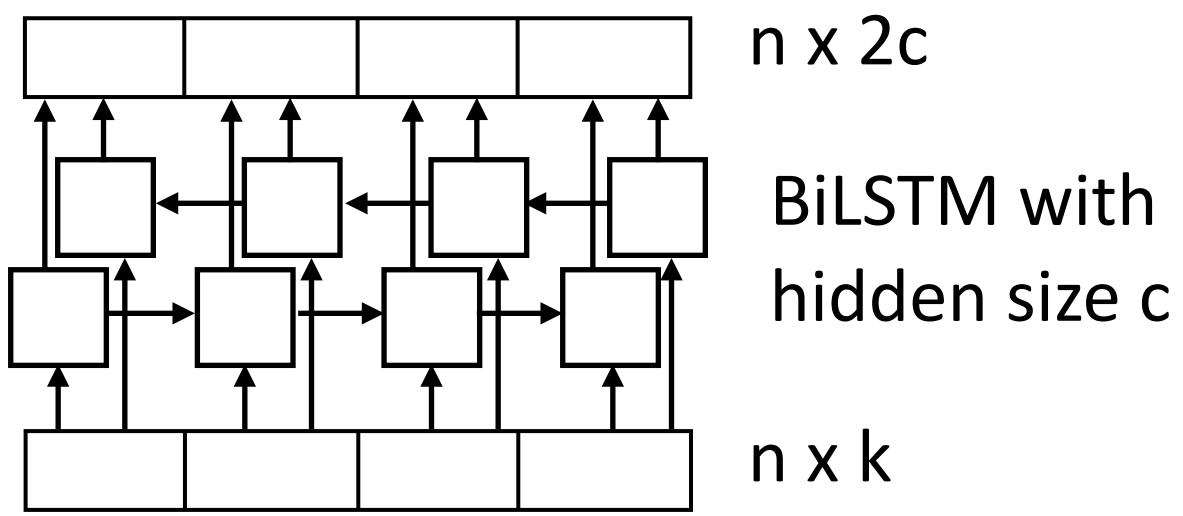


the movie was good





#### the movie was good

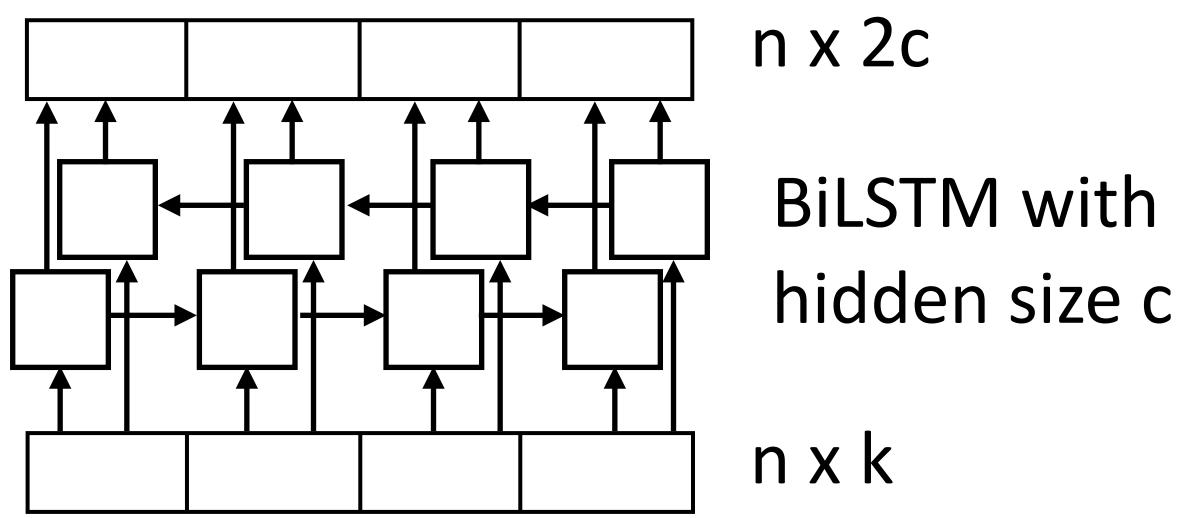


#### the movie was good

Both LSTMs and convolutional layers transform the input using context



#### the movie was good



the movie was good

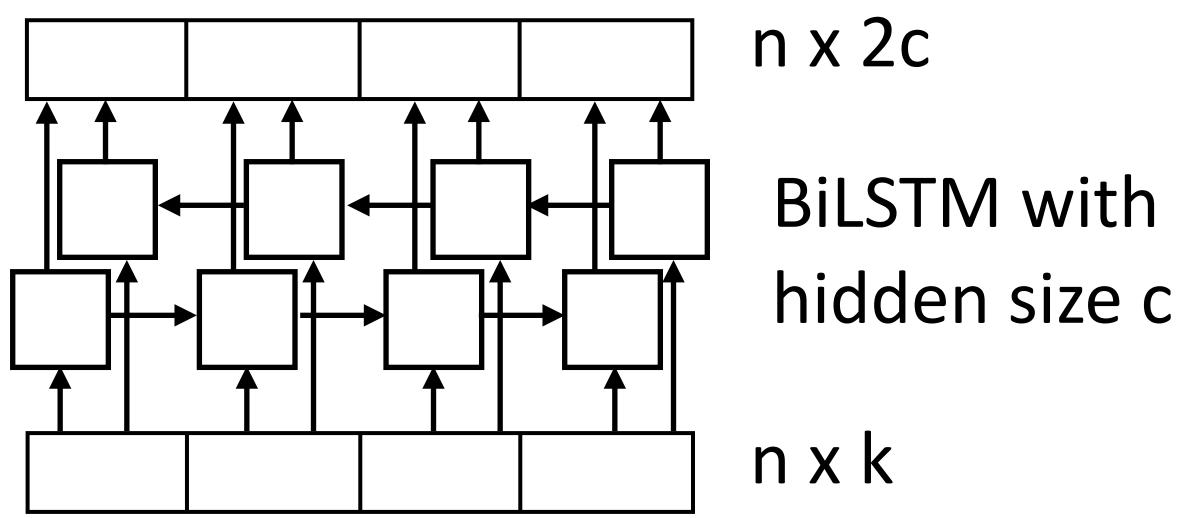
Both LSTMs and convolutional layers transform the input using context LSTM: "globally" looks at the entire sentence (but local for many problems)





### the movie was good

- LSTM: "globally" looks at the entire sentence (but local for many problems)
- CNN: local depending on filter width + number of layers



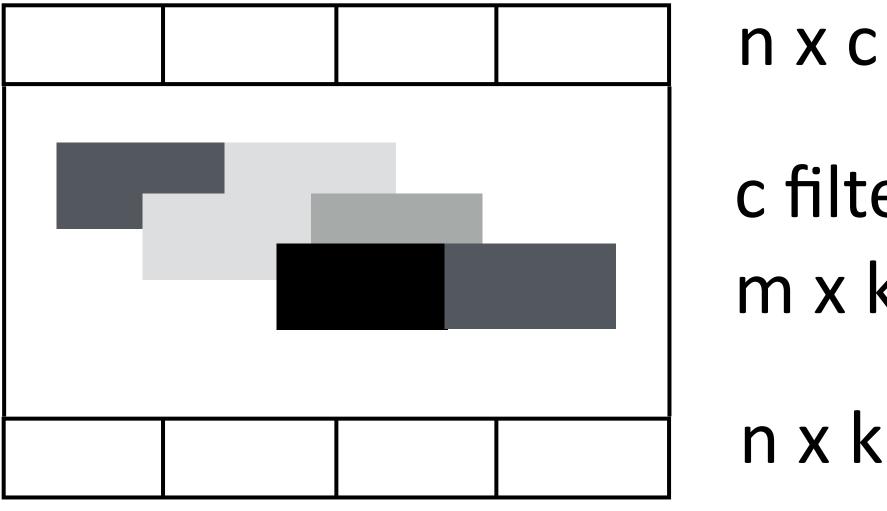
the movie was good

Both LSTMs and convolutional layers transform the input using context



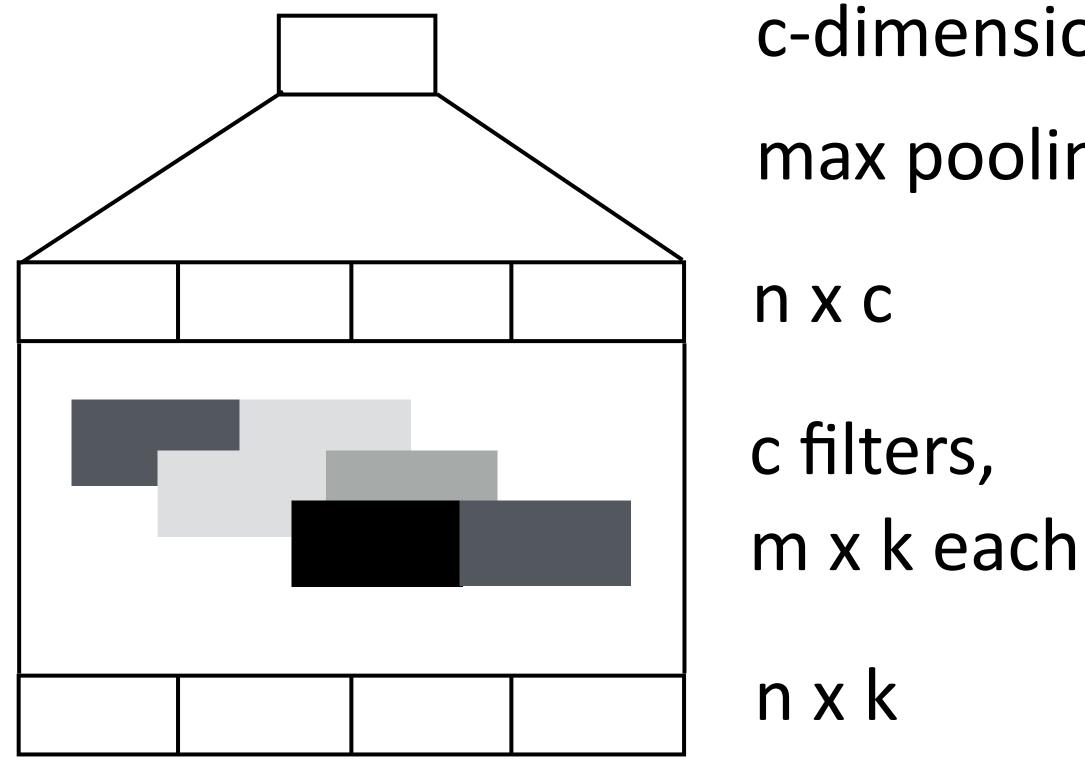
### CNNs for Sentiment

### **CNNs for Sentiment Analysis**



n x c n x k each n x k

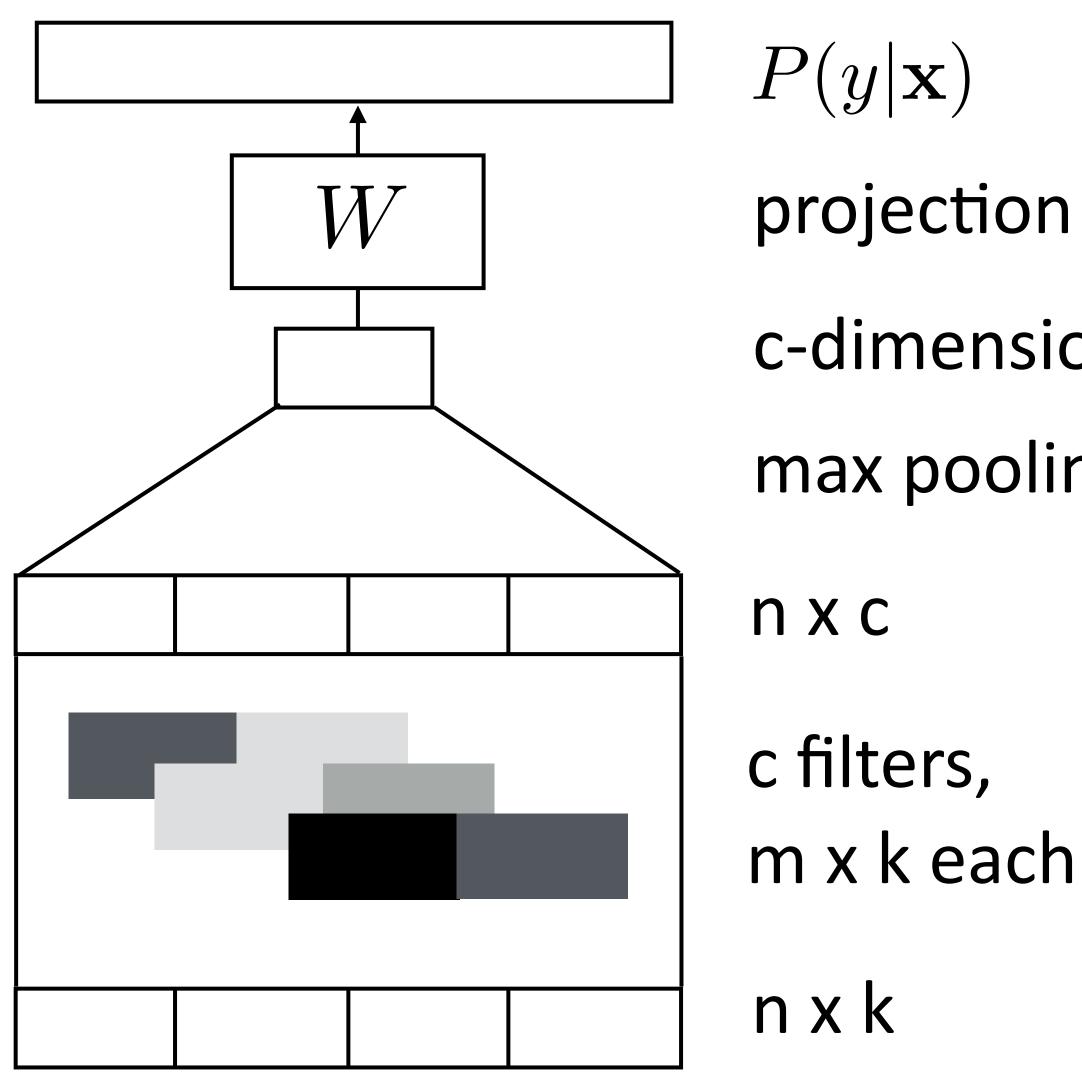
### **CNNs for Sentiment Analysis**



- c-dimensional vector
- max pooling over the sentence
  - Max pooling: return the max activation of a given filter over the entire sentence; like a logical OR (sum pooling is like logical AND)

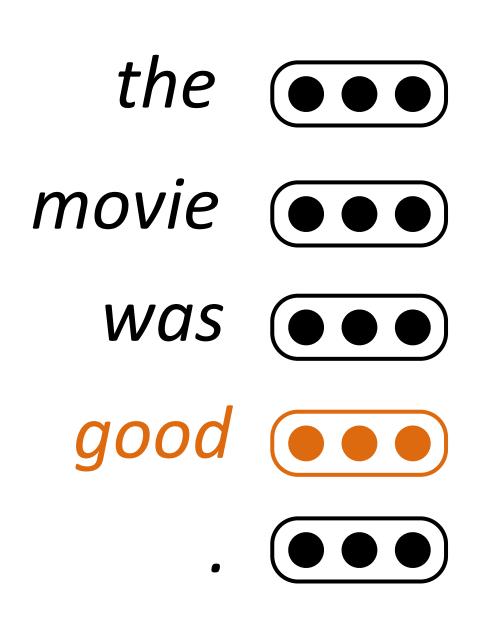


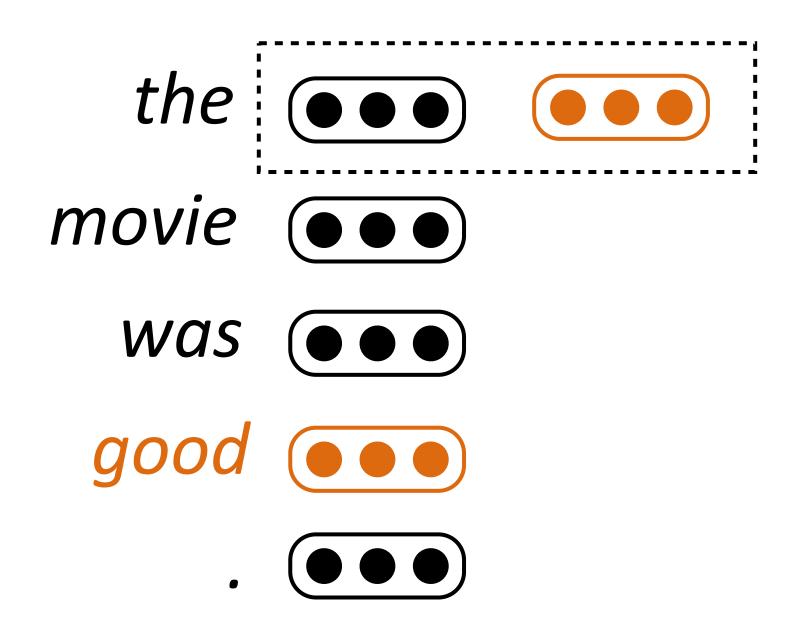
# **CNNs for Sentiment Analysis**

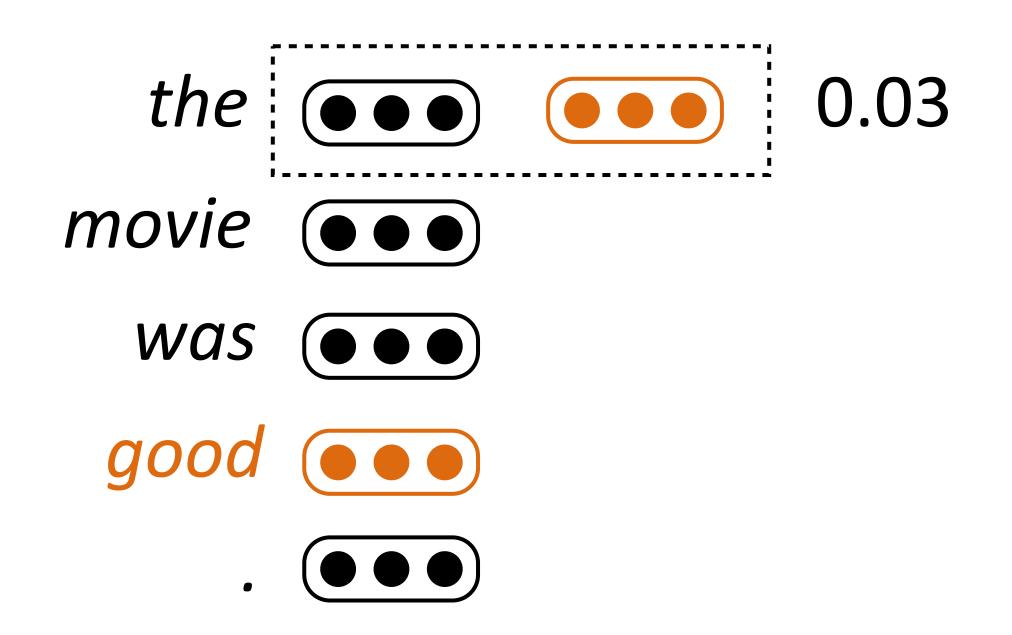


- projection + softmax
- c-dimensional vector
- max pooling over the sentence
  - Max pooling: return the max activation of a given filter over the entire sentence; like a logical OR (sum pooling is like logical AND)

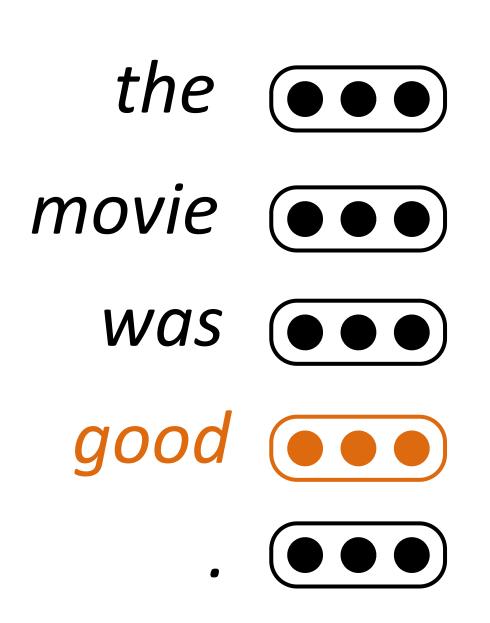


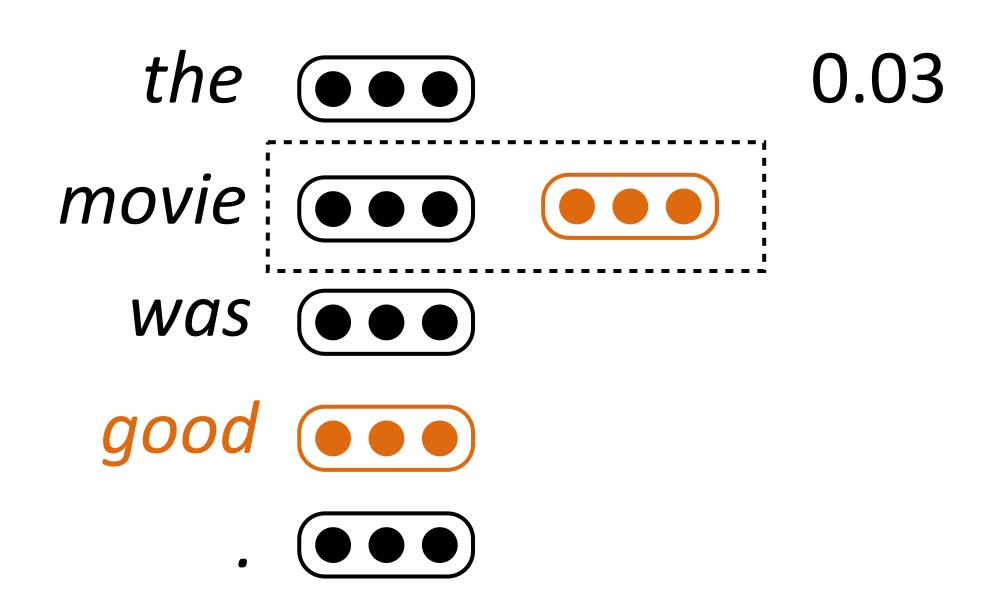


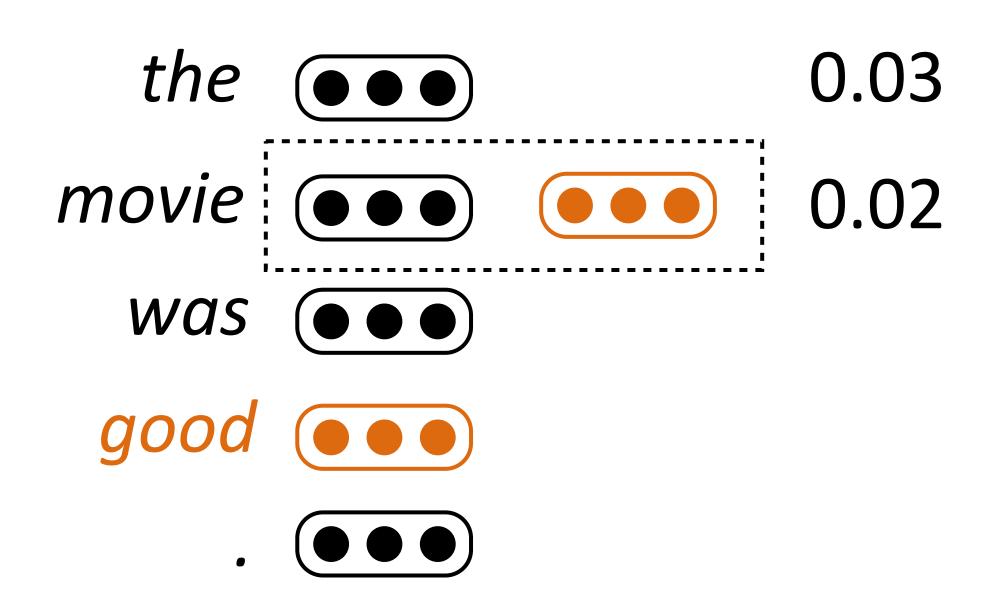




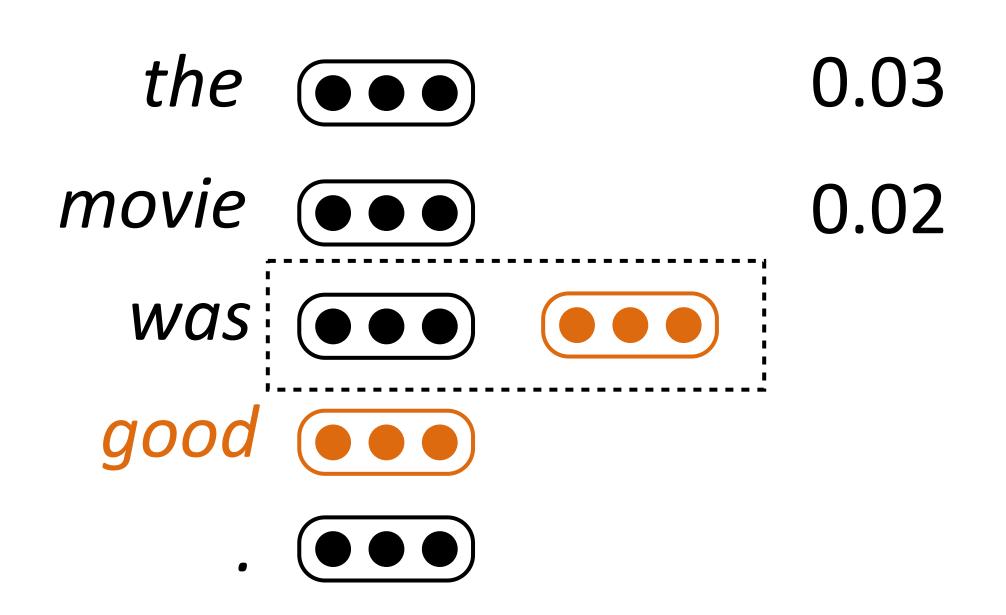
0.03

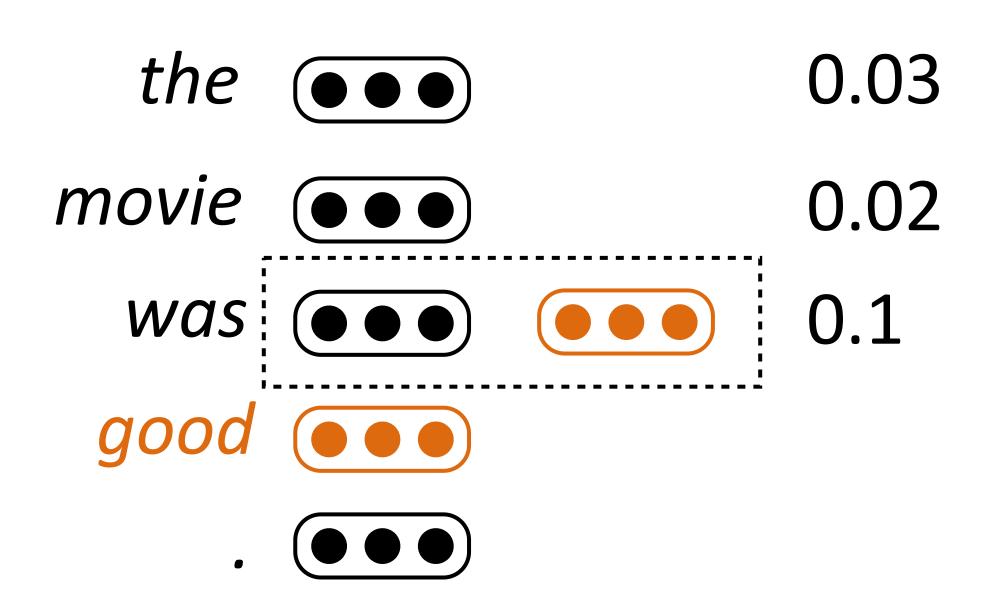




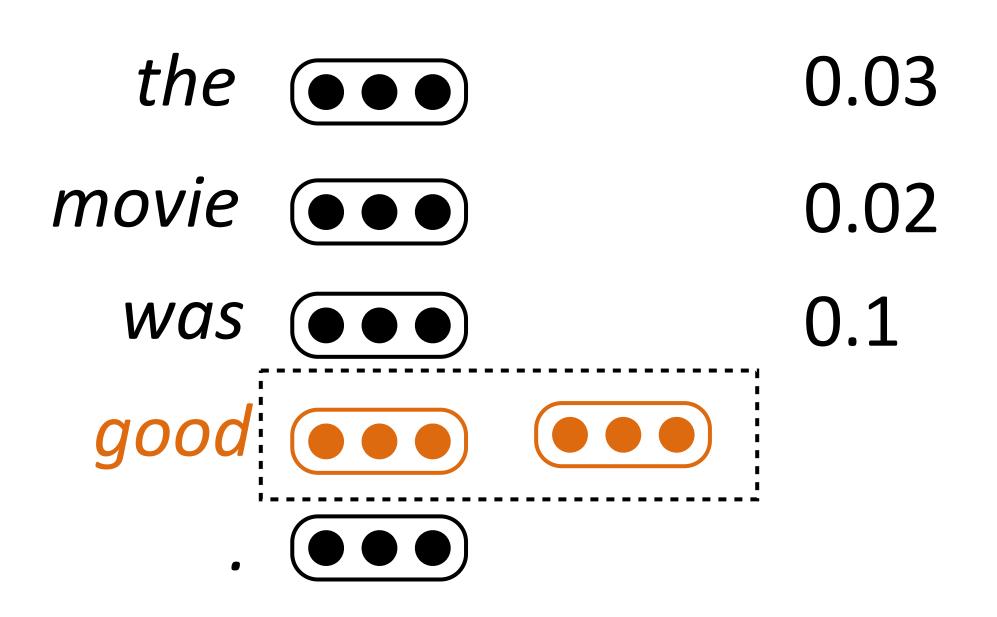


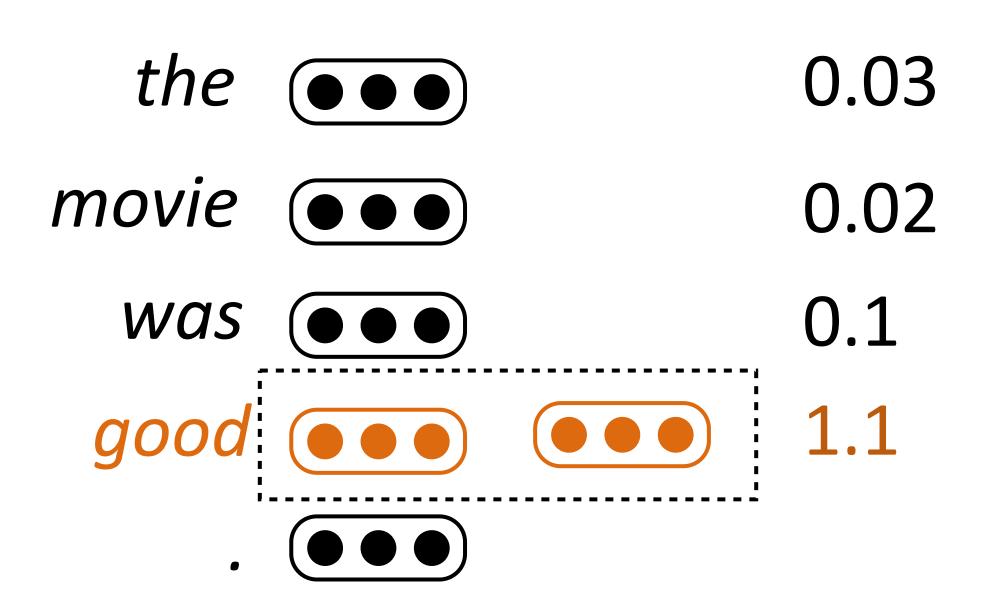




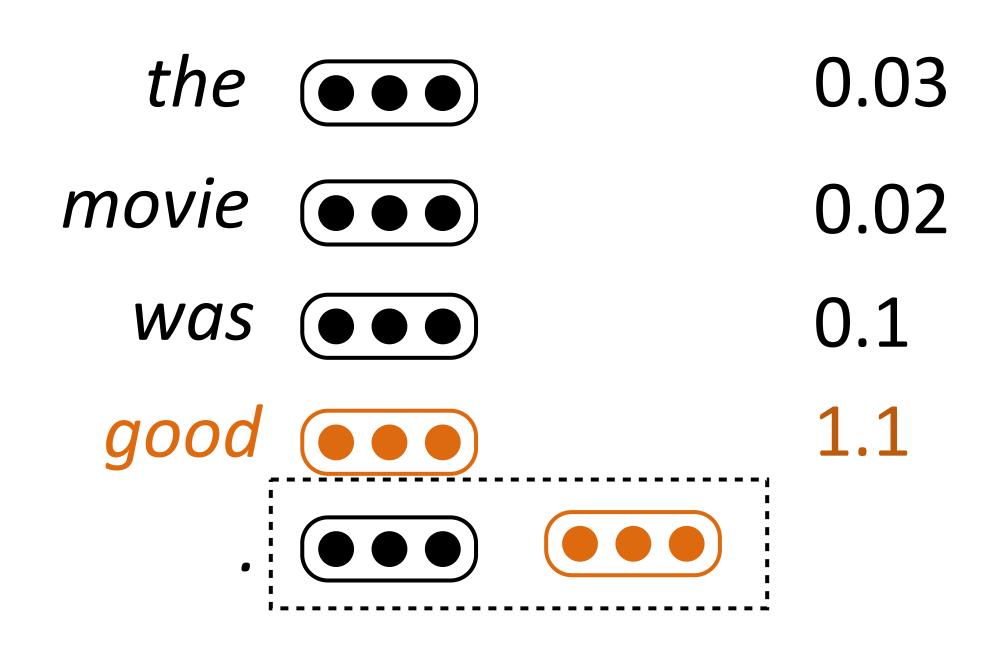


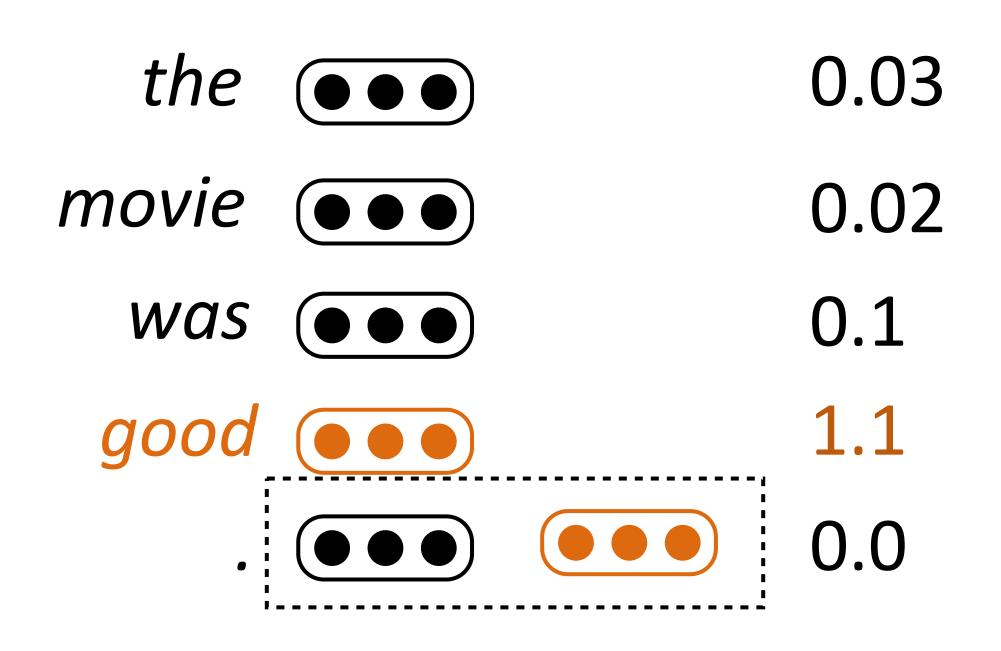


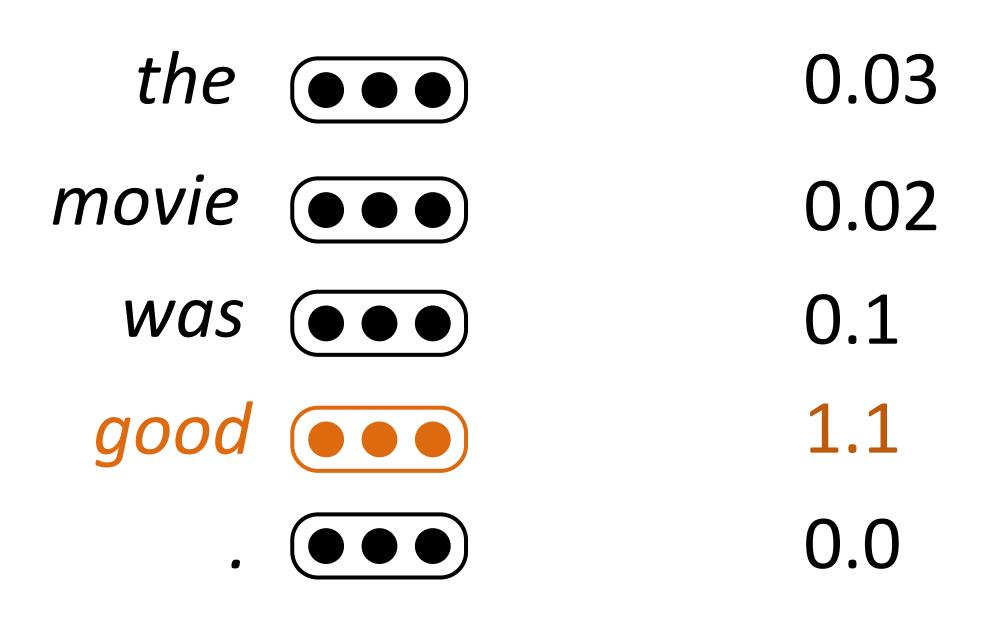


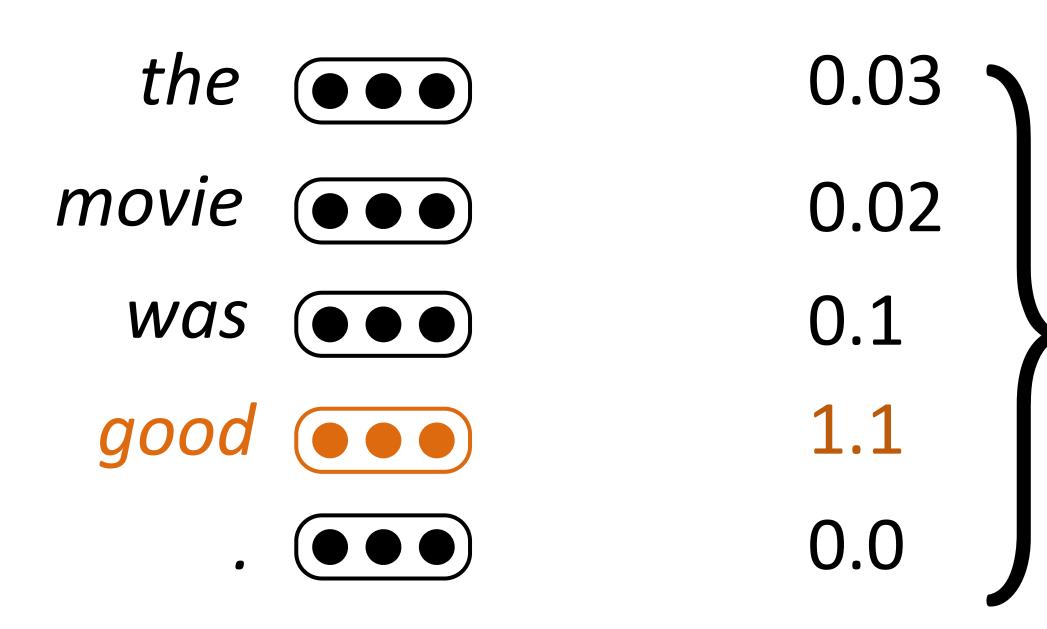




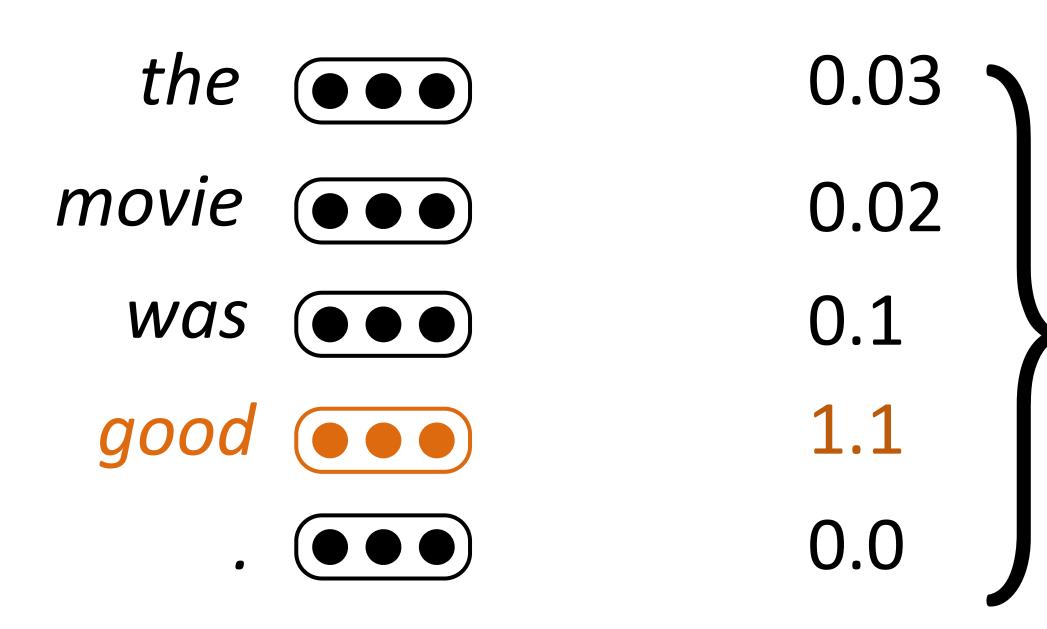




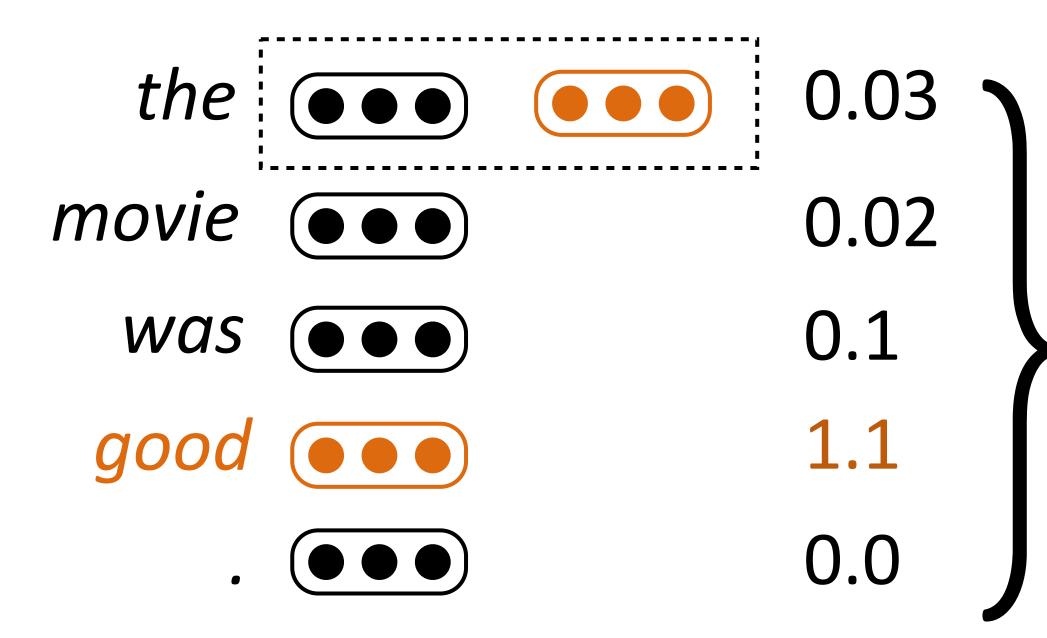




#### max = 1.1



0.02 *"good" filter output*0.1 max = 1.1

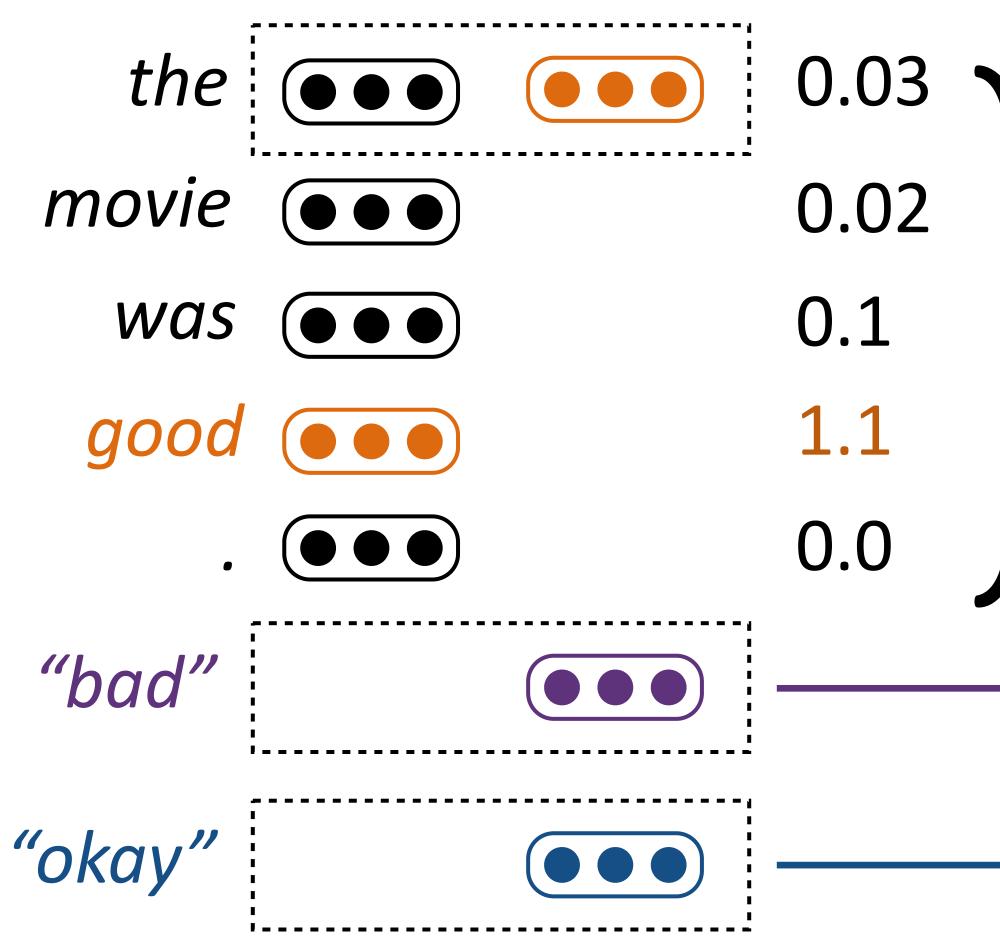


#### max = 1.1



#### max = 1.1

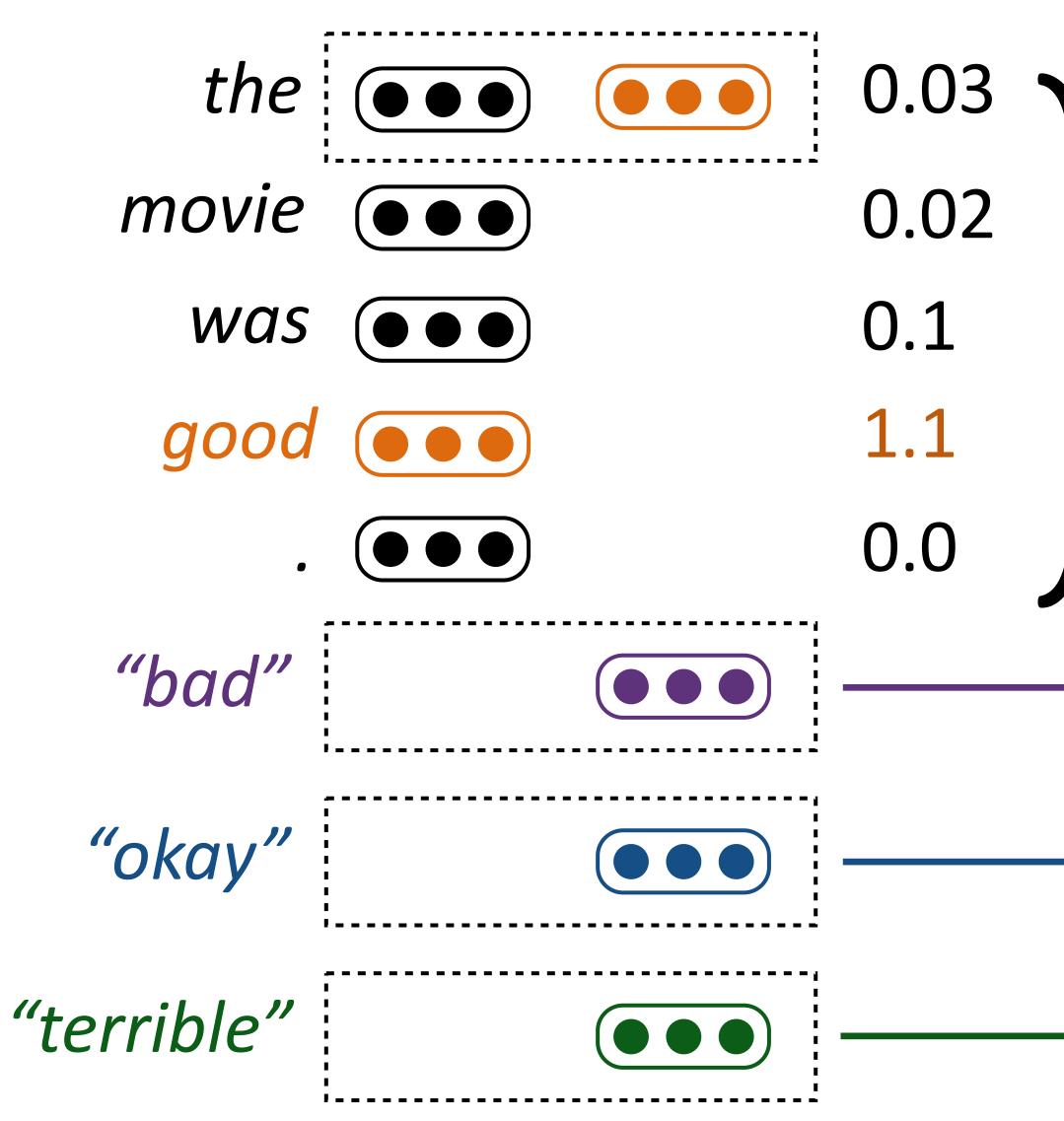
▶ 0.1



max = 1.1

▶ 0.1

► 0.3



max = 1.1

▶ 0.1

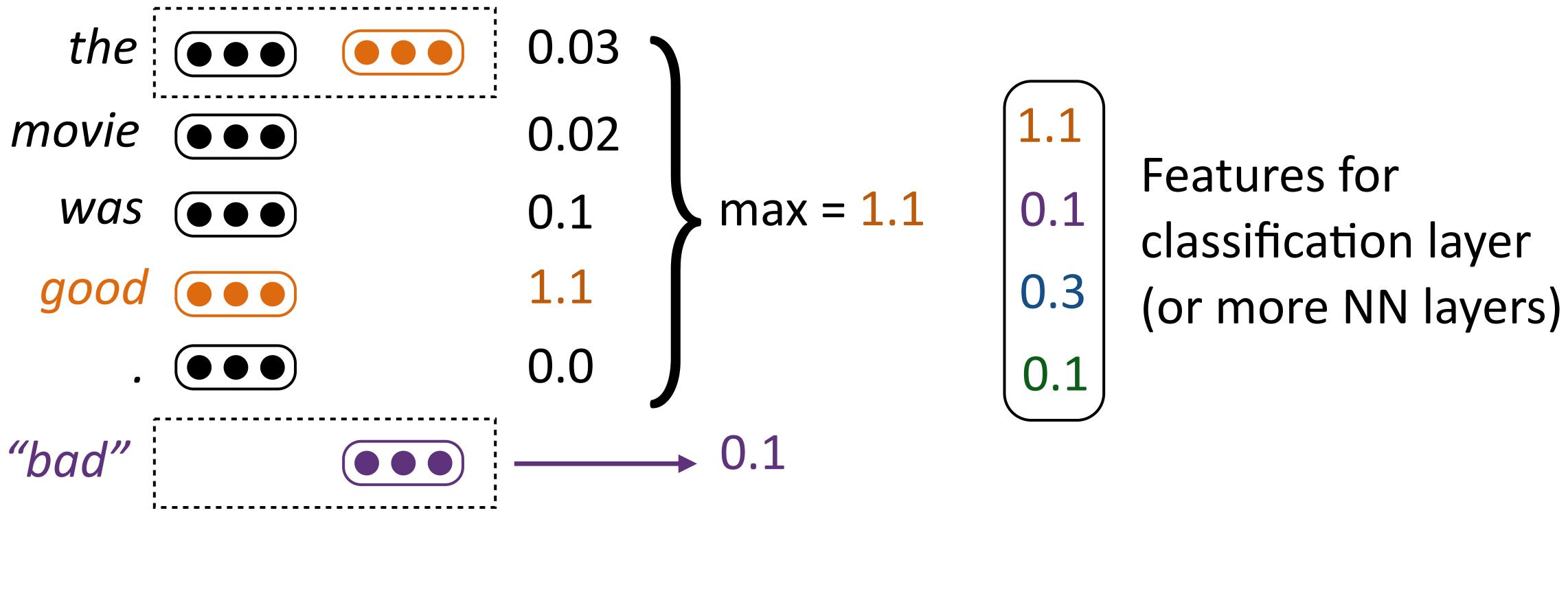
► 0.3

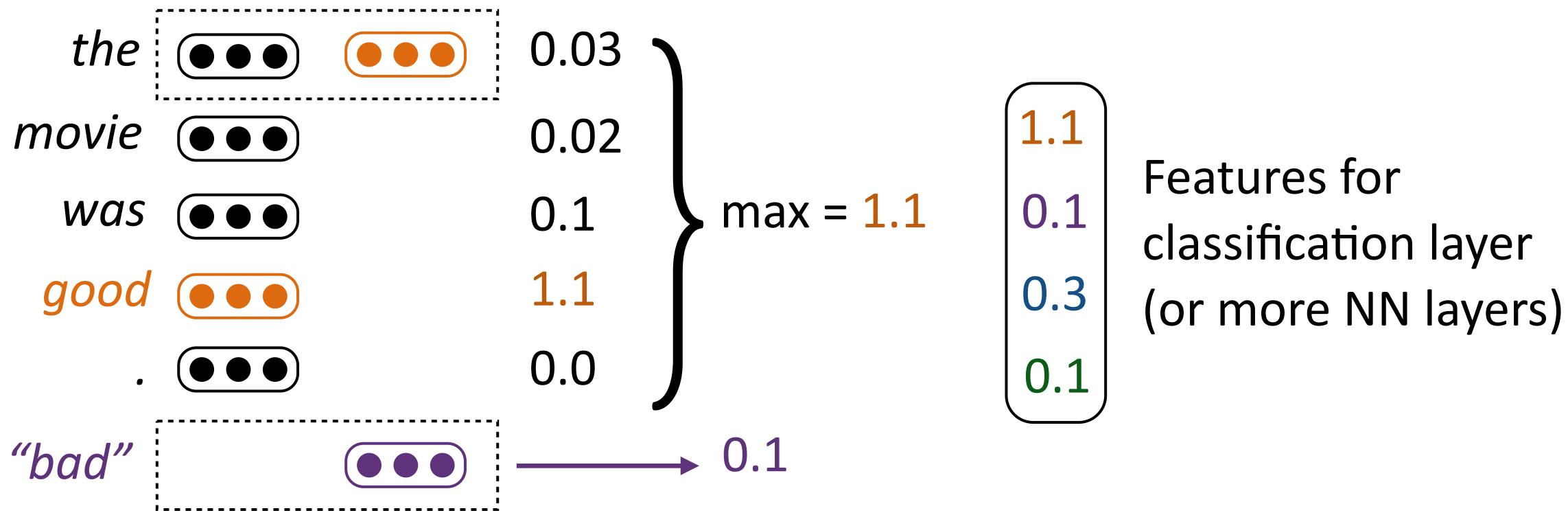
► 0.1



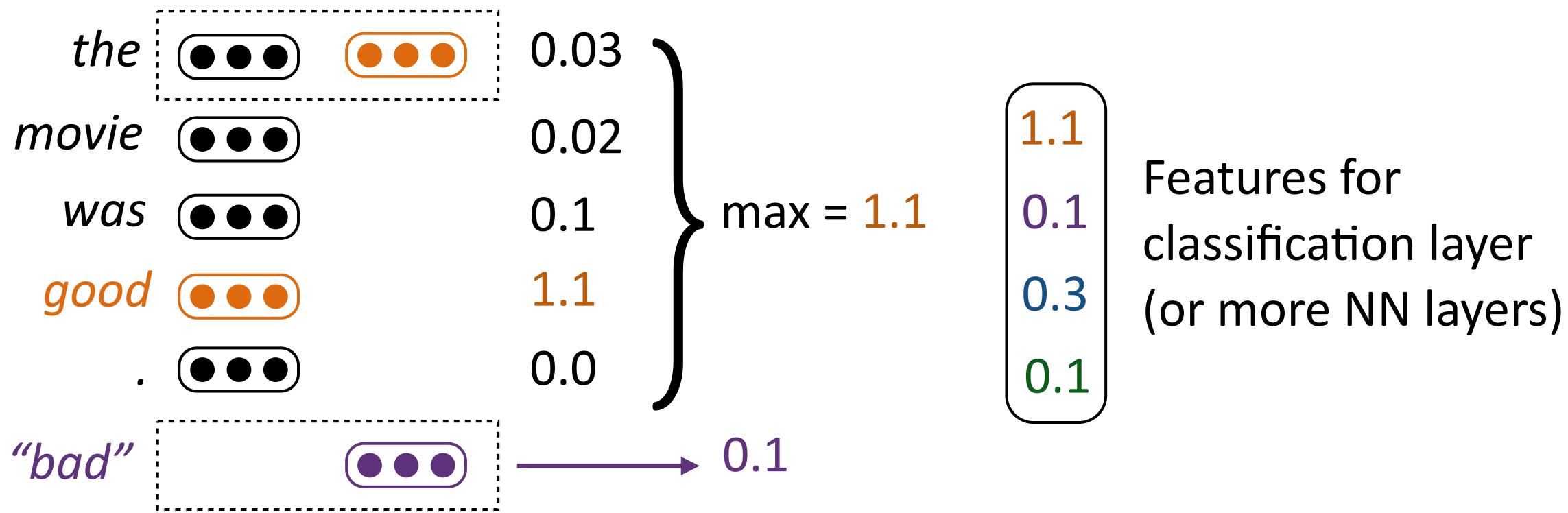
#### max = 1.1

▶ 0.1

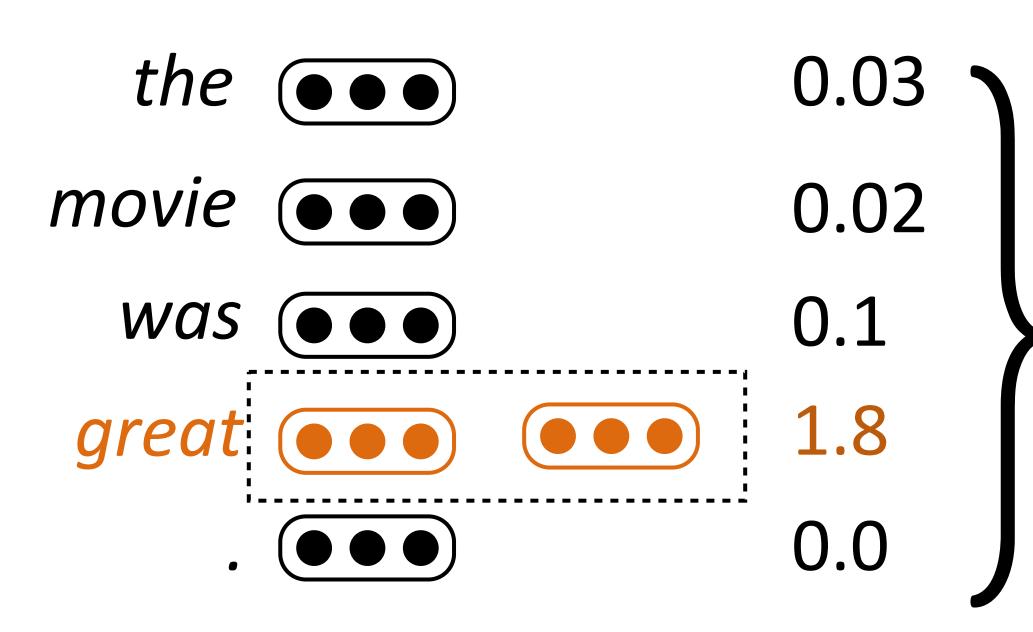




Takes variable-length input and turns it into fixed-length output



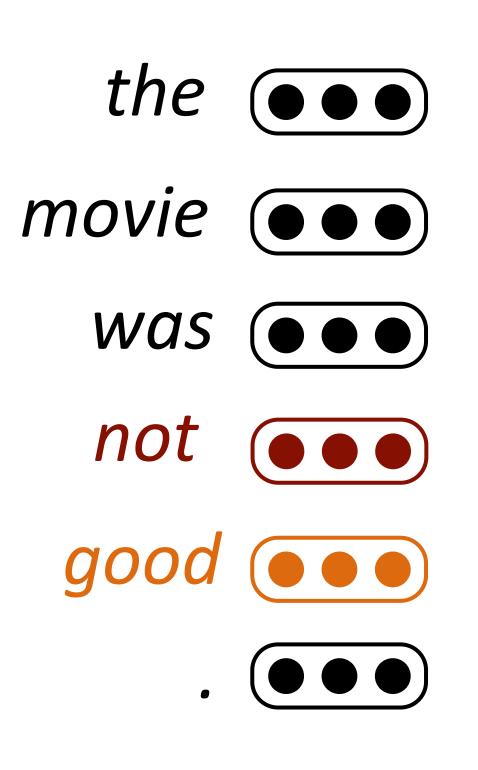
- Takes variable-length input and turns it into fixed-length output
- Filters are initialized randomly and then learned

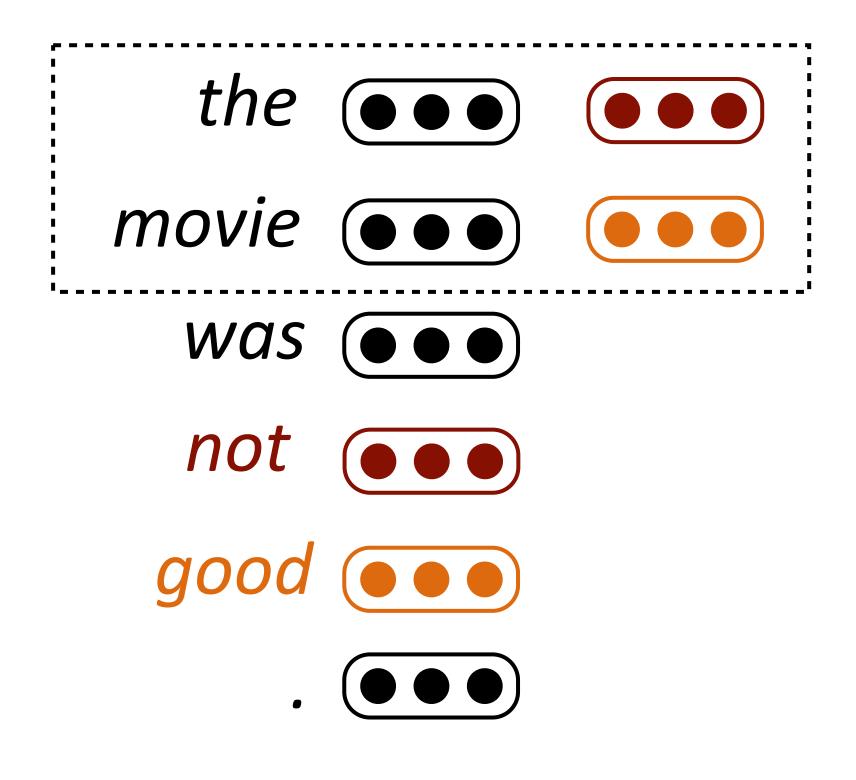


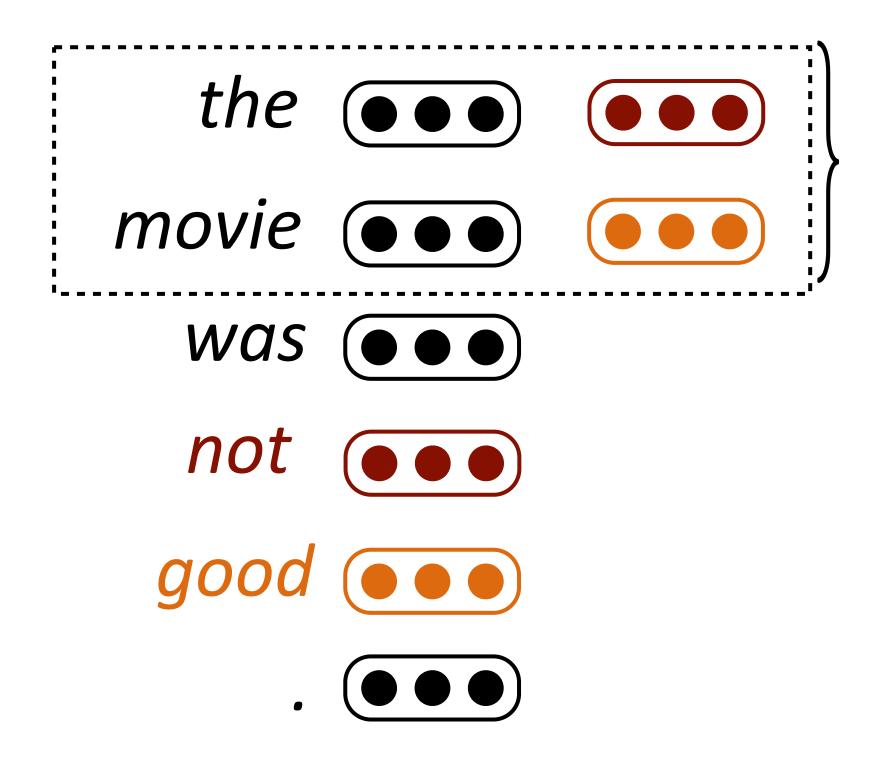
 Word vectors for similar words a have similar outputs

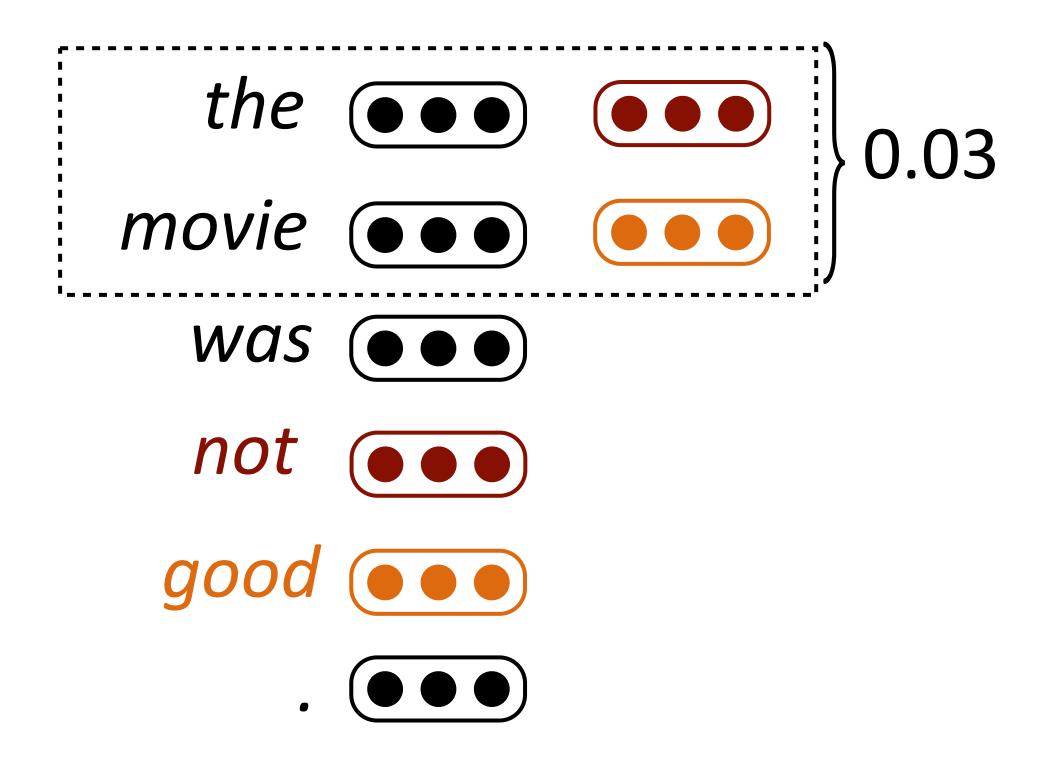
### max = 1.8

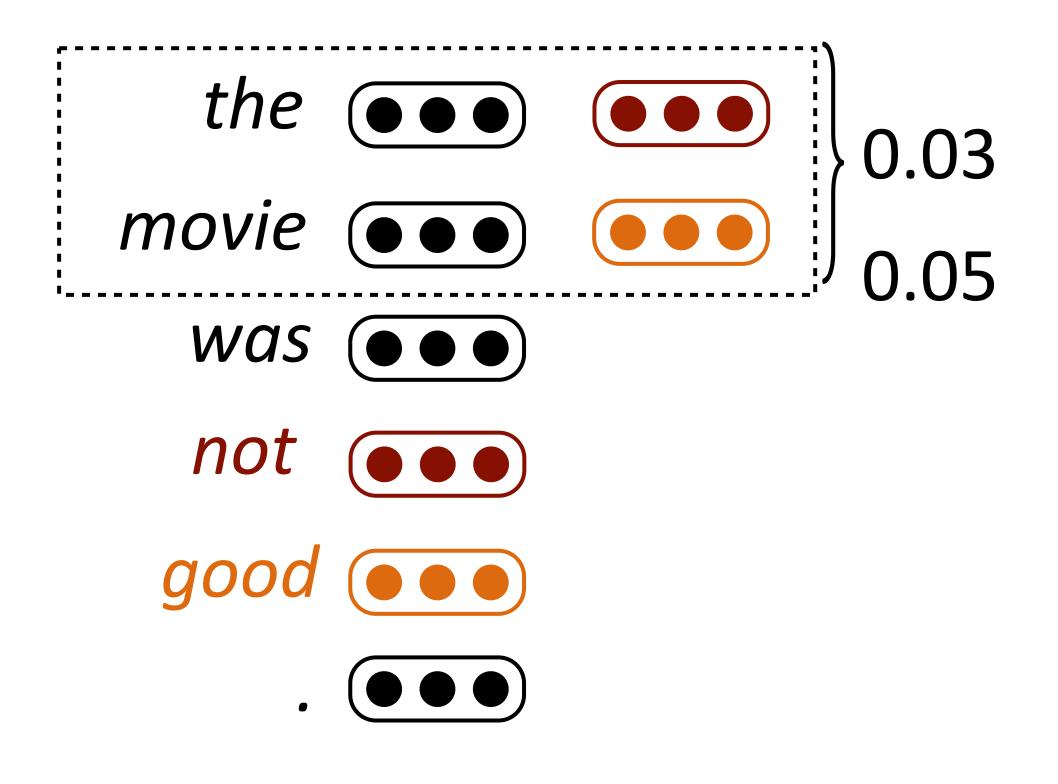
### Word vectors for similar words are similar, so convolutional filters will

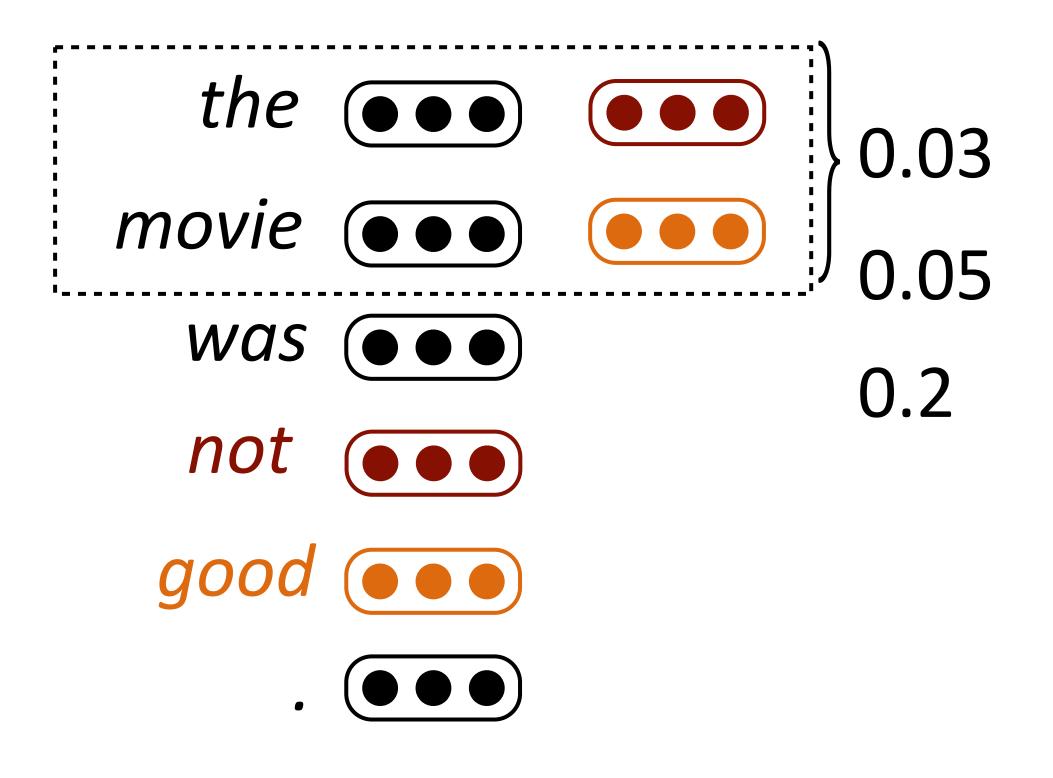


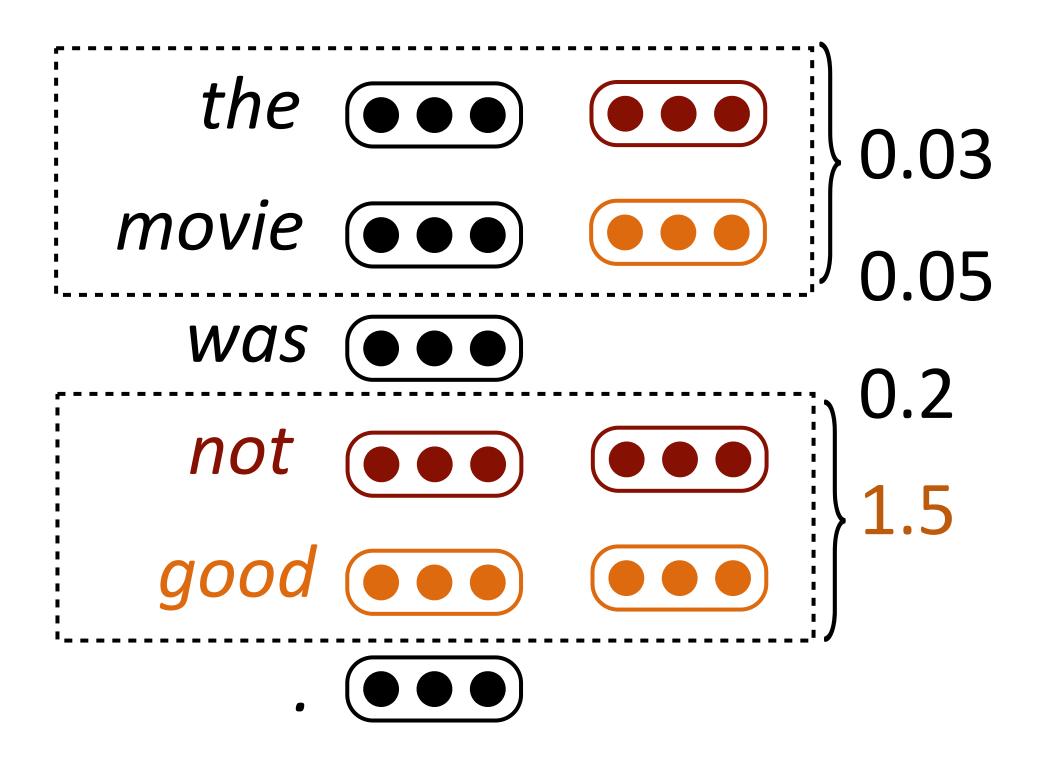


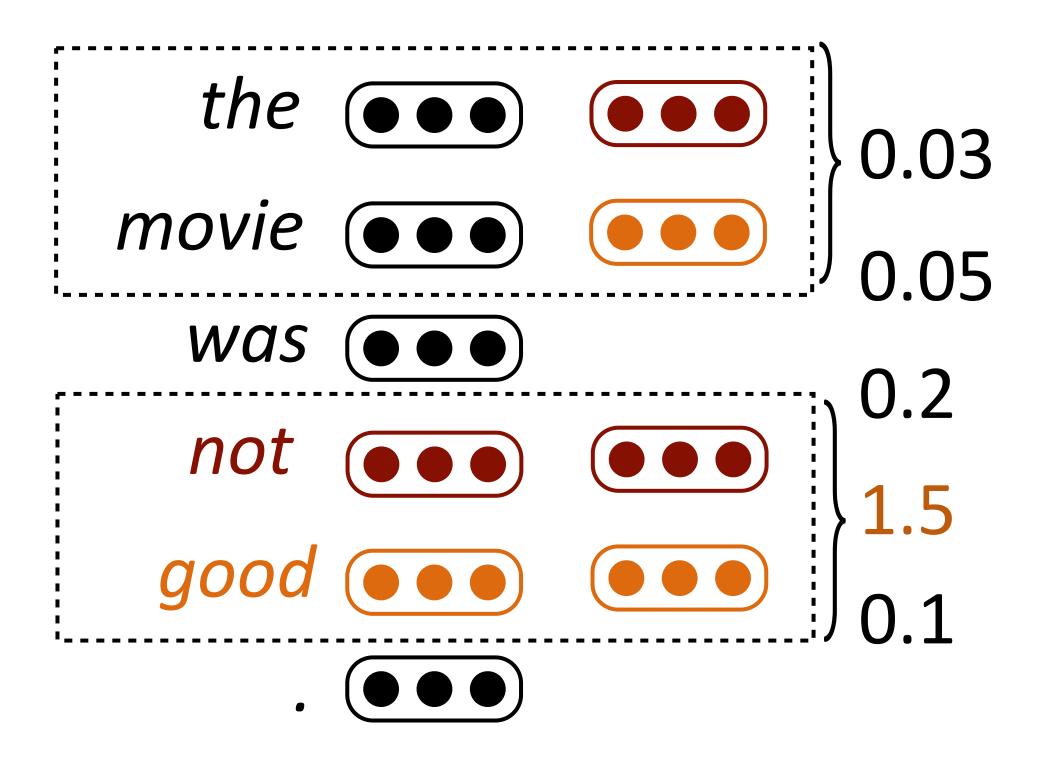


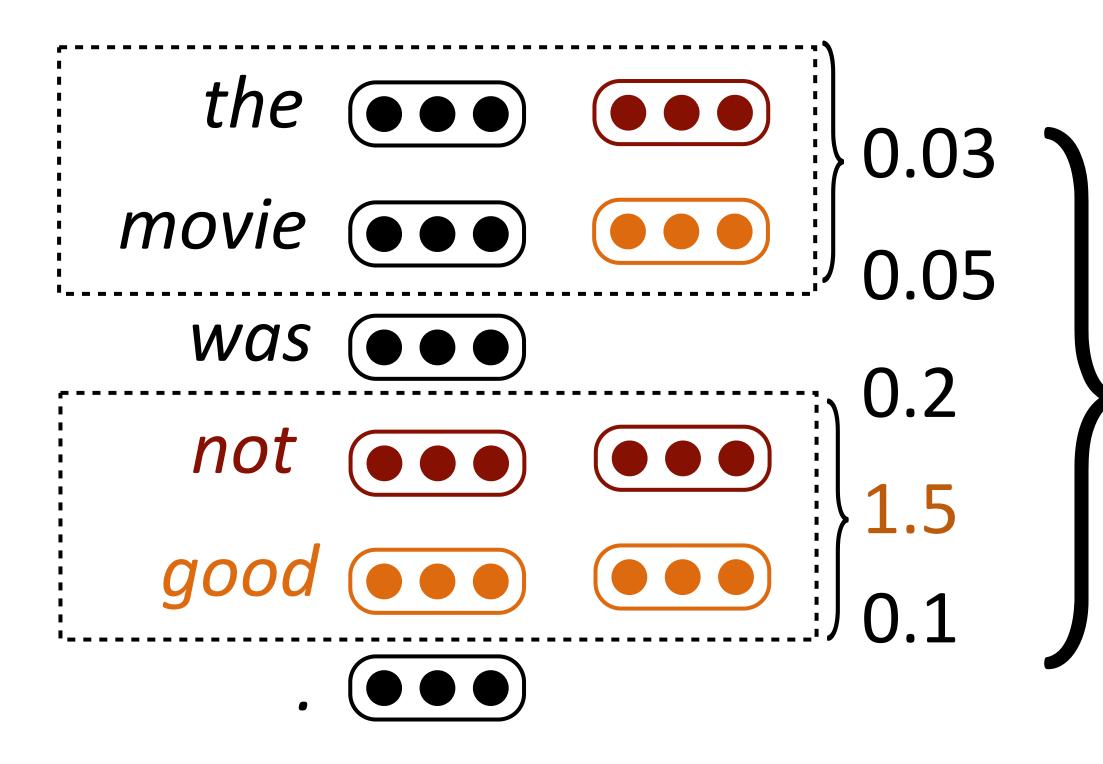






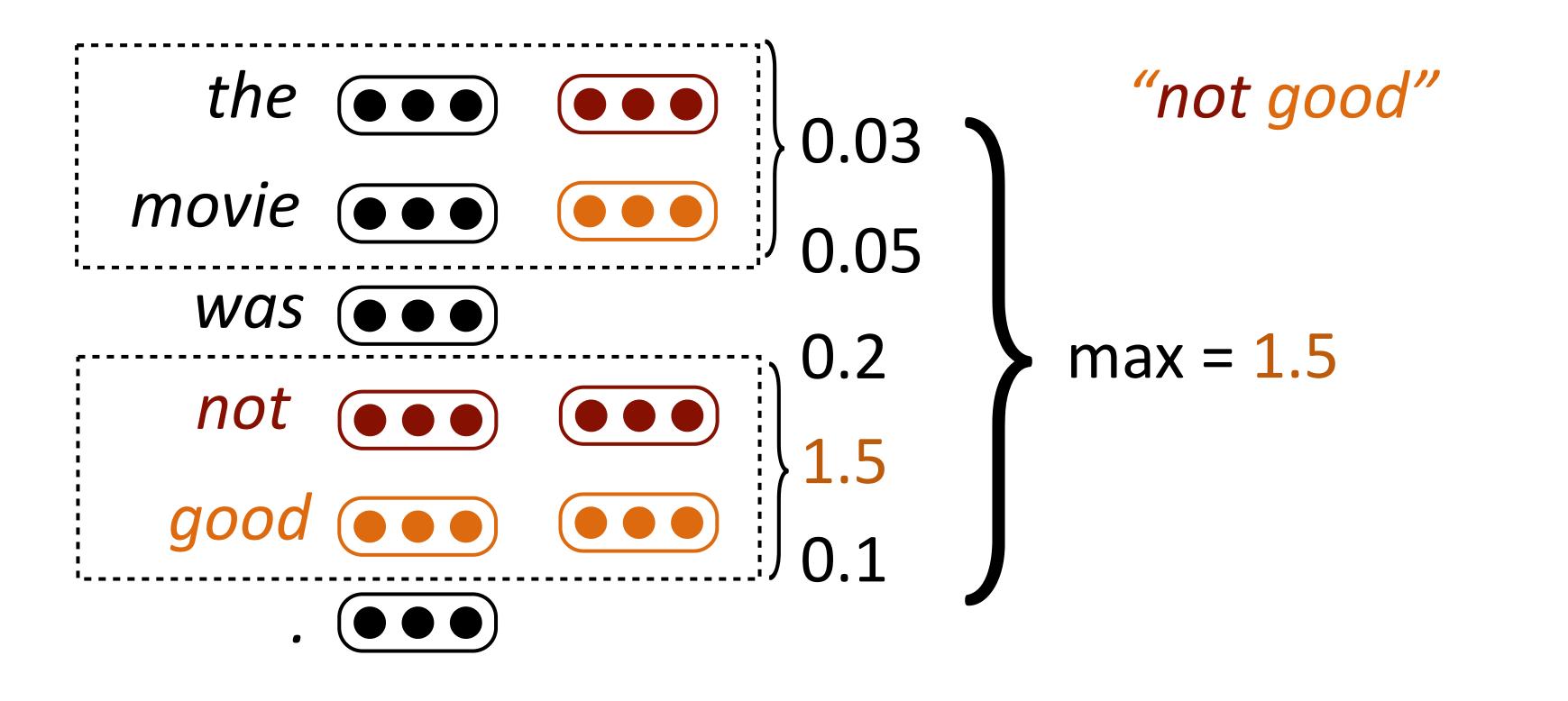




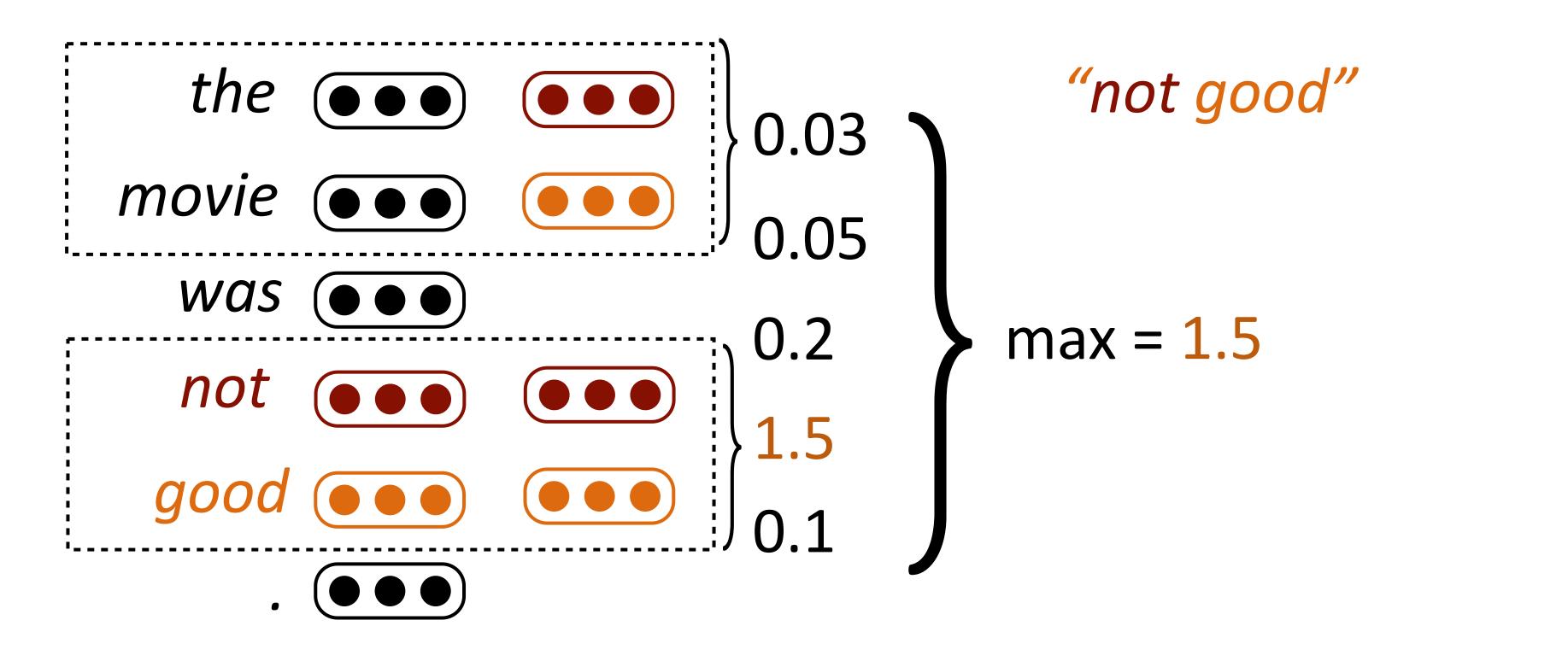


"not good"

### • max = 1.5



Analogous to bigram features in bag-of-words models



- Analogous to bigram features in bag-of-words models
- matches that bigram

Indicator feature of text containing bigram <-> max pooling of a filter that



the movie was not really all that good

the cinematography was good, the music great, but the movie was bad

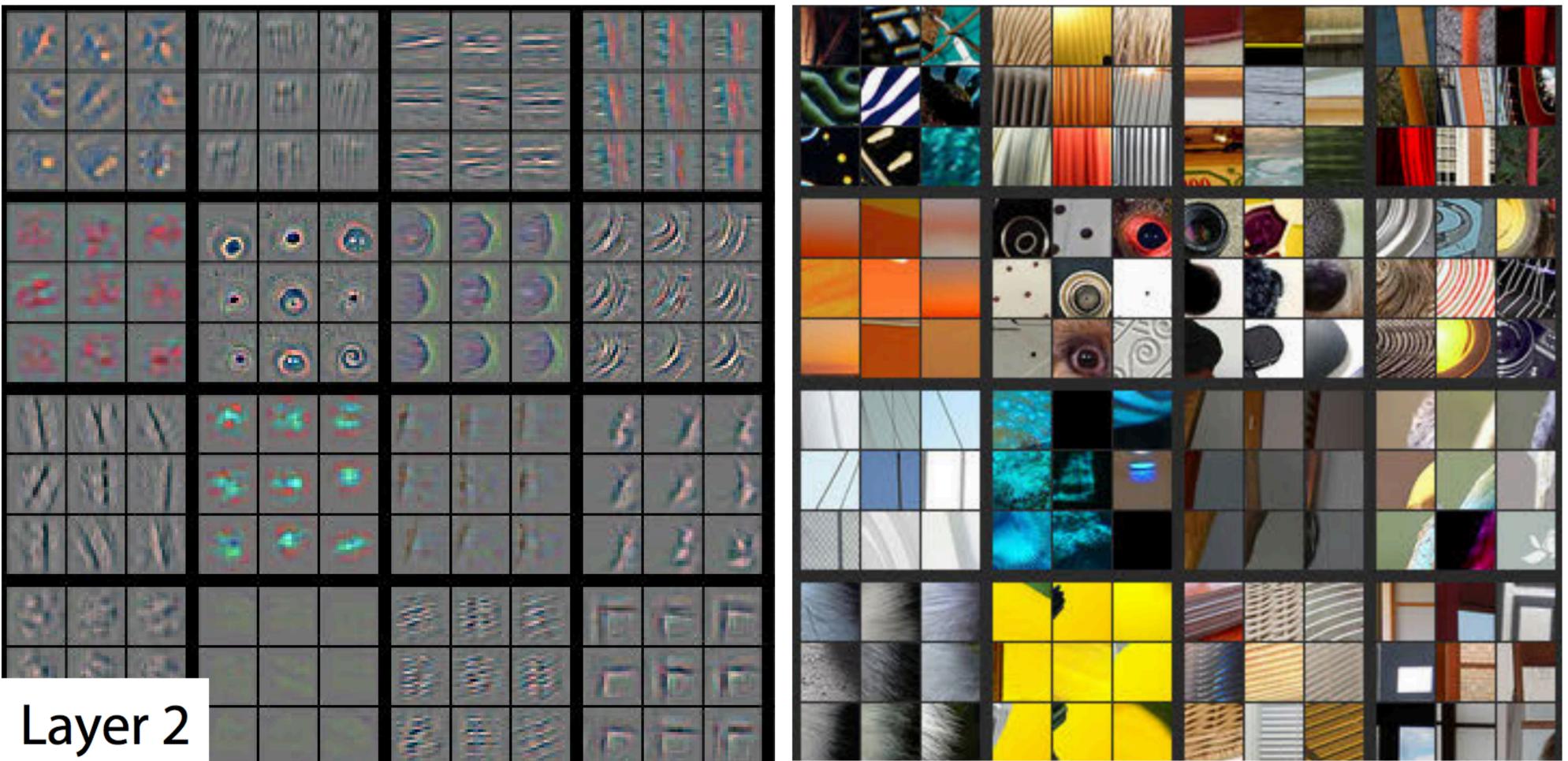
I entered the theater in the bloom of youth and left as an old man

### What can CNNs learn?

the movie was not good

# Deep Convolutional Networks

### Low-level filters: extract low-level features from the data

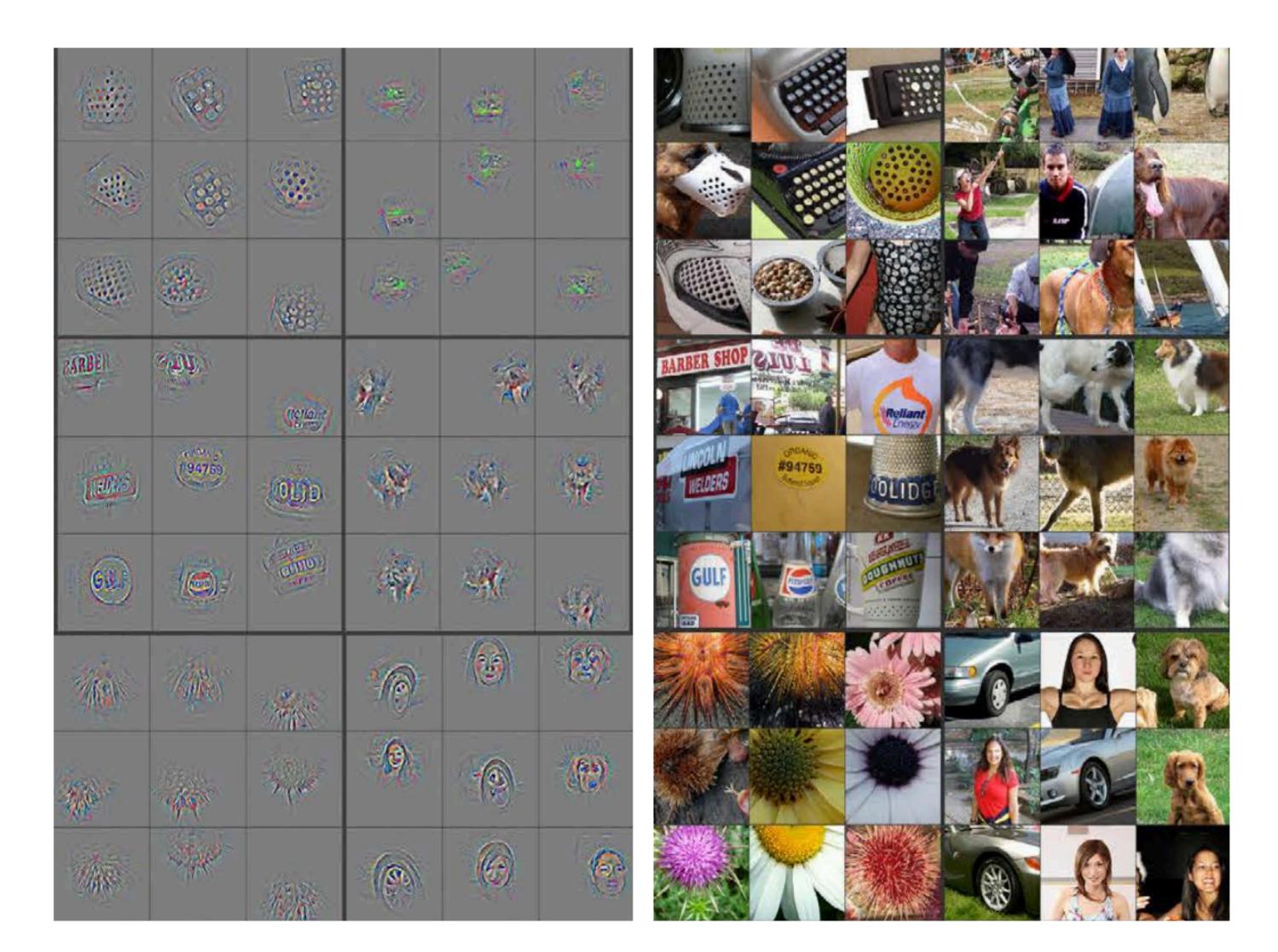


### Zeiler and Fergus (2014)



# Deep Convolutional Networks

### High-level filters: match larger and more "semantic patterns"



### Zeiler and Fergus (2014)



## **CNNs: Implementation**

Input is batch\_size x n x k matrix, filters are c x m x k matrix (c filters)

# **CNNs: Implementation**

- Typically use filters with m ranging from 1 to 5 or so (multiple filter) widths in a single convnet)

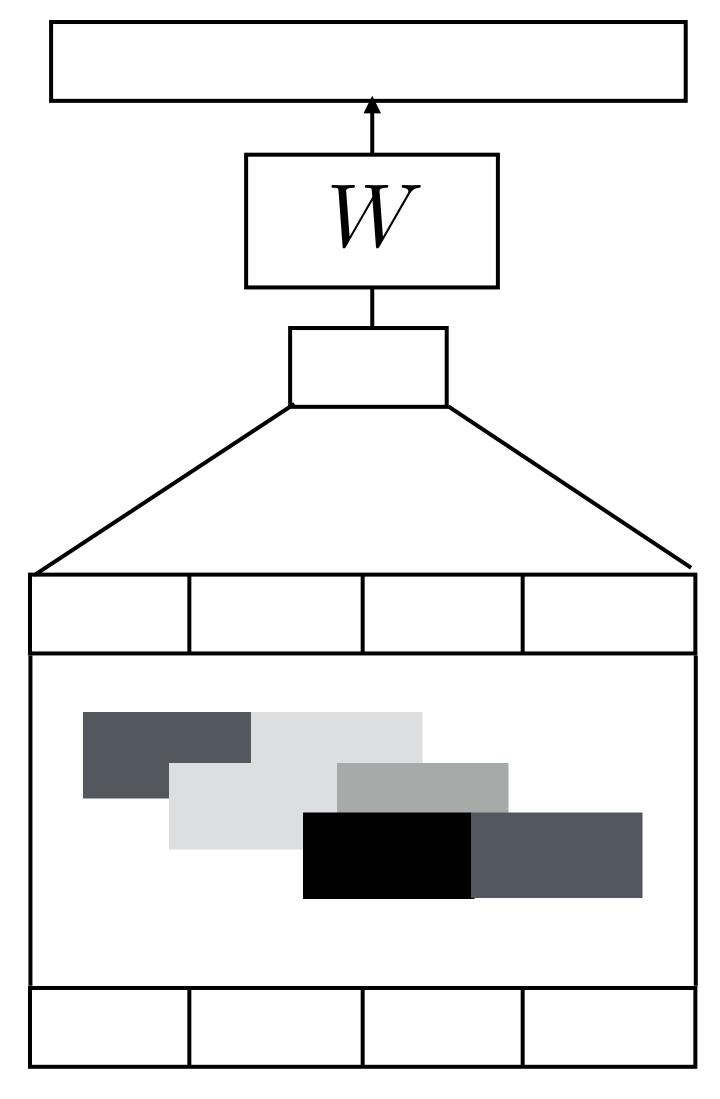
Input is batch\_size x n x k matrix, filters are c x m x k matrix (c filters)

# **CNNs: Implementation**

- Input is batch\_size x n x k matrix, filters are c x m x k matrix (c filters)
- Typically use filters with m ranging from 1 to 5 or so (multiple filter widths in a single convnet)
- All computation graph libraries support efficient convolution operations

### **CNNs for Sentence Classification**

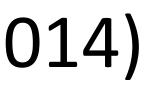
- Question classification, sentiment, etc.
- Conv+pool, then use feedforward layers to classify
- Can use multiple types of input vectors (fixed initializer and learned)



### the movie was good

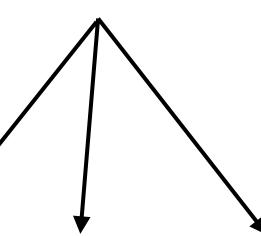


Model	MR	SST-1	SST-2	Subj	TREC	CR	MPQA
CNN-multichannel	81.1	47.4	88.1	93.2	92.2	85.0	89.4
NBSVM (Wang and Manning, 2012)	79.4	_	_	93.2	-	81.8	86.3



	¥		*				
Model	MR	SST-1	SST-2	Subj	TREC	CR	MPQA
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### movie review sentiment

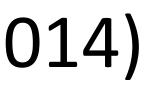




	×		4	₩			
Model	MR	SST-1	SST-2	Subj	TREC	CR	MPQA
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NBSVM (Wang and Manning, 2012)	79.4	_	_	93.2	_	81.8	86.3

### movie review sentiment

### subjectivity/objectivity detection

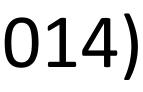


	×		*	₩			
Model	MR	SST-1	SST-2	Subj	TREC	CR	MPQA
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NBSVM (Wang and Manning, 2012)	79.4	_	_	93.2	_	81.8	86.3

### movie review sentiment

subjectivity/objectivity detection

### question type classification



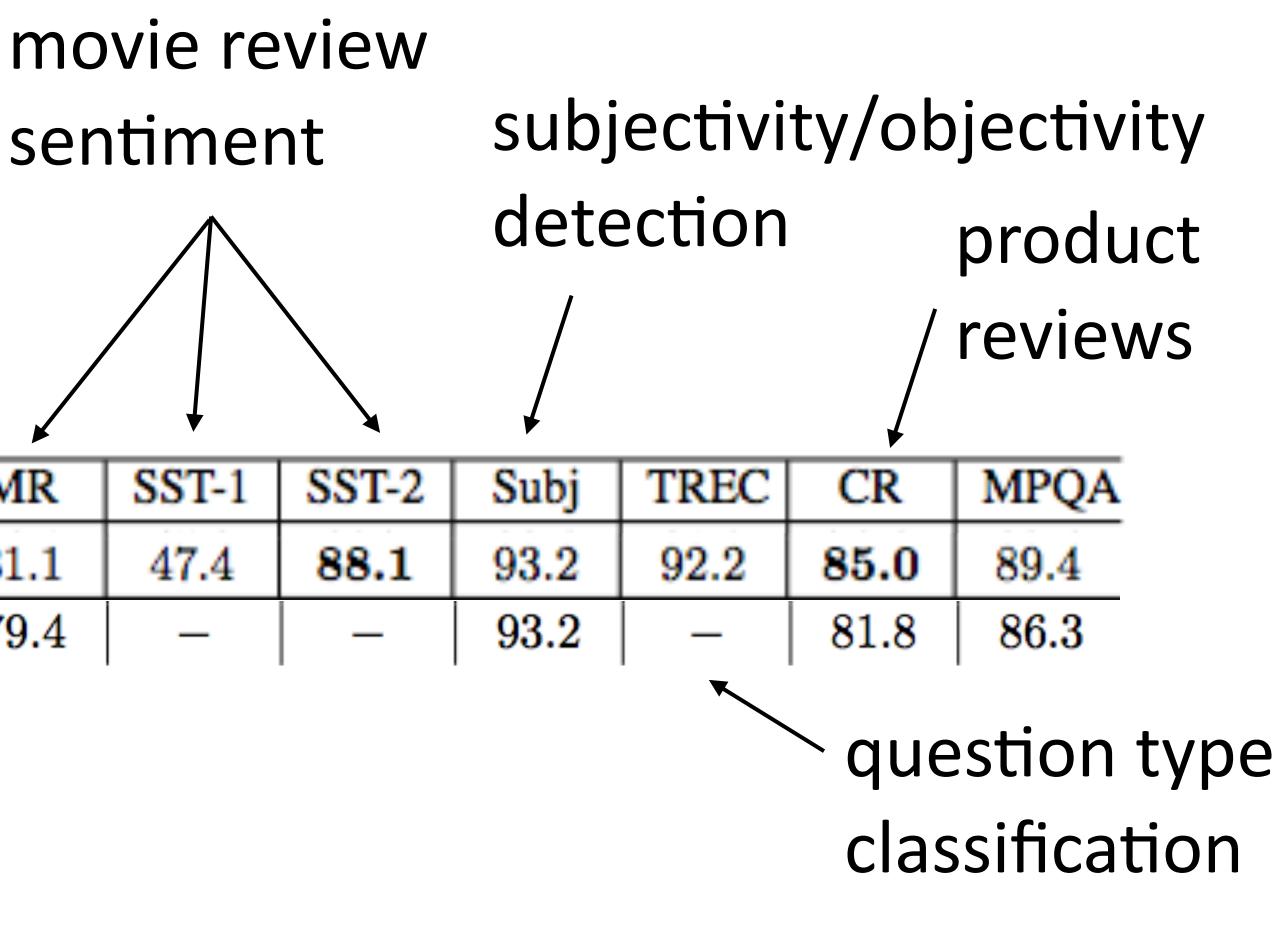
	movie review sentiment				ojectivity			
					ection		product	
							reviews	
Model	MR	SST-1	SST-2	Subj	TREC	CR	MPQA	
CNN-multichannel	81.1	47.4	88.1	93.2	92.2	85.0	89.4	
NBSVM (Wang and Manning, 2012)	79.4	_	-	93.2	-	81.8	86.3	
						•	estion type ssification	



Model	MR
CNN-multichannel	81.1
NBSVM (Wang and Manning, 2012)	79.4

Also effective at document-level text classification

# Sentence Classification





Neural CRF Basics

### **NER Revisited** 0 LOC ORG

### O O B-LOC O O B-ORG O 0 B-PER I-PER **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. PERSON

O O B-LOC O O B-ORG OB-PER I-PER O 0 **Barack Obama** will travel to Hangzhou today for the G20 meeting. PERSON ORG LOC

Features in CRFs: I[tag=B-LOC & curr\_word=Hangzhou], I[tag=B-LOC & prev\_word=to], I[tag=B-LOC & curr\_prefix=Han]

B-PER I-PER O O O B-ORG O 0 **Barack Obama** will travel to Hangzhou today for the G20 meeting. PERSON ORG 

- Features in CRFs: I[tag=B-LOC & curr\_word=Hangzhou], I[tag=B-LOC & prev\_word=to], I[tag=B-LOC & curr\_prefix=Han]
- Linear model over features

B-PER I-PER O O O B-ORG O 0 **Barack Obama** will travel to Hangzhou today for the G20 meeting. PERSON ORG 

- Features in CRFs: I[tag=B-LOC & curr\_word=Hangzhou], I[tag=B-LOC & prev\_word=to], I[tag=B-LOC & curr\_prefix=Han]
- Linear model over features
- Downsides:

B-PER I-PER O O O B-ORG O 0 **Barack Obama** will travel to Hangzhou today for the G20 meeting. PERSON ORG 

- Features in CRFs: I[tag=B-LOC & curr\_word=Hangzhou], I[tag=B-LOC & prev\_word=to], I[tag=B-LOC & curr\_prefix=Han]
- Linear model over features
- Downsides:

Lexical features mean that words need to be seen in the training data

B-PER I-PER O O O B-ORG O 0 **Barack Obama** will travel to Hangzhou today for the G20 meeting. PERSON ORG 

- Features in CRFs: I[tag=B-LOC & curr\_word=Hangzhou], I[tag=B-LOC & prev\_word=to], I[tag=B-LOC & curr\_prefix=Han]
- Linear model over features
- Downsides:

  - work well to look at more than 2 words with a single feature)

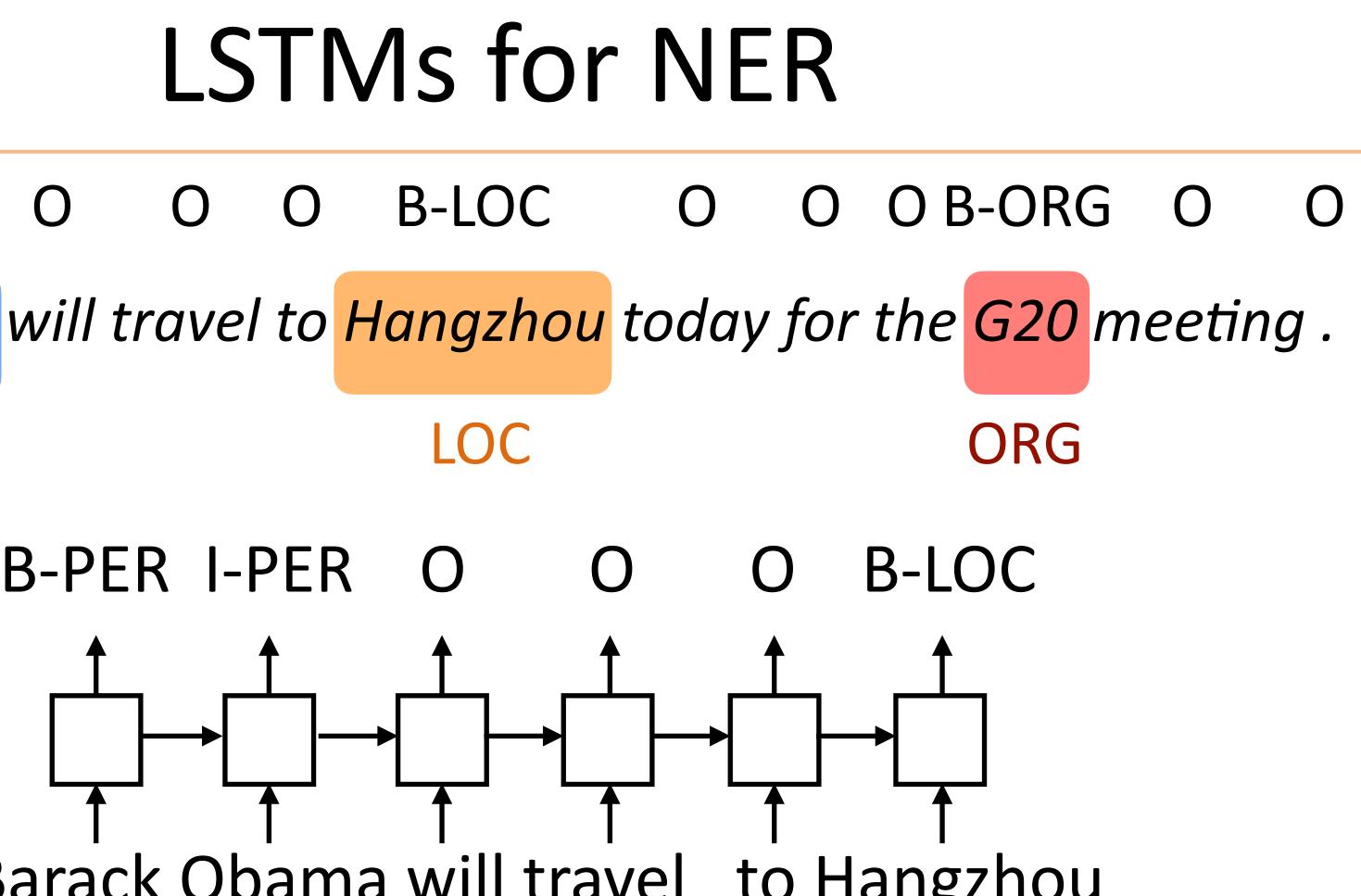
Lexical features mean that words need to be seen in the training data

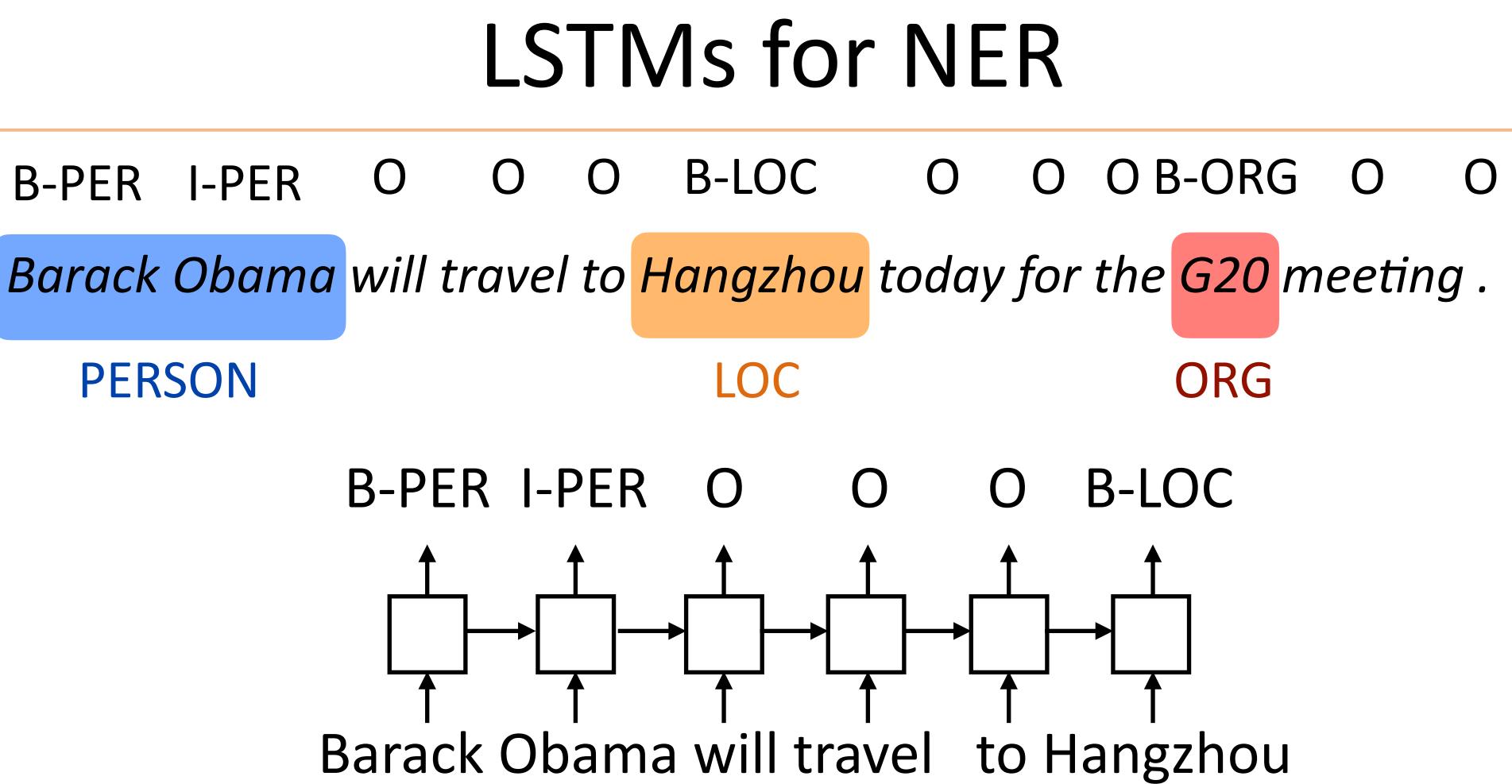
Linear model can't capture feature conjunctions as effectively (doesn't



### I-PER **B-PER**

### PERSON





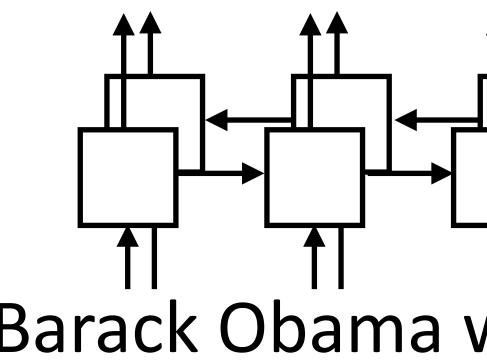
- Transducer (LM-like model)

What are the strengths and weaknesses of this model compared to CRFs?



# 0 LOC ORG

### LSTMs for NER O O B-LOC O O B-ORG O I-PER **B-PER Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. PERSON B-PER I-PER O O B-LOC Barack Obama will travel to Hangzhou

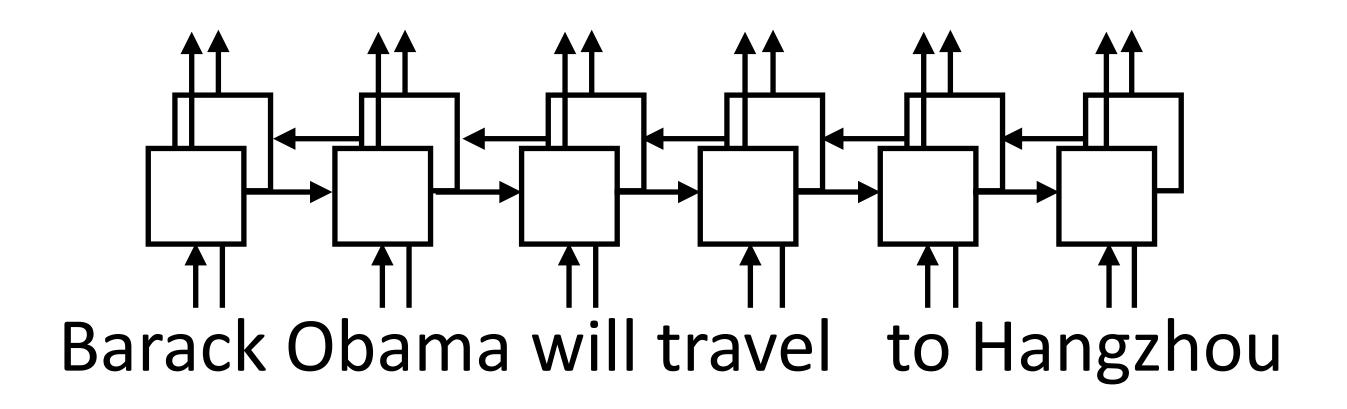


- Bidirectional transducer model

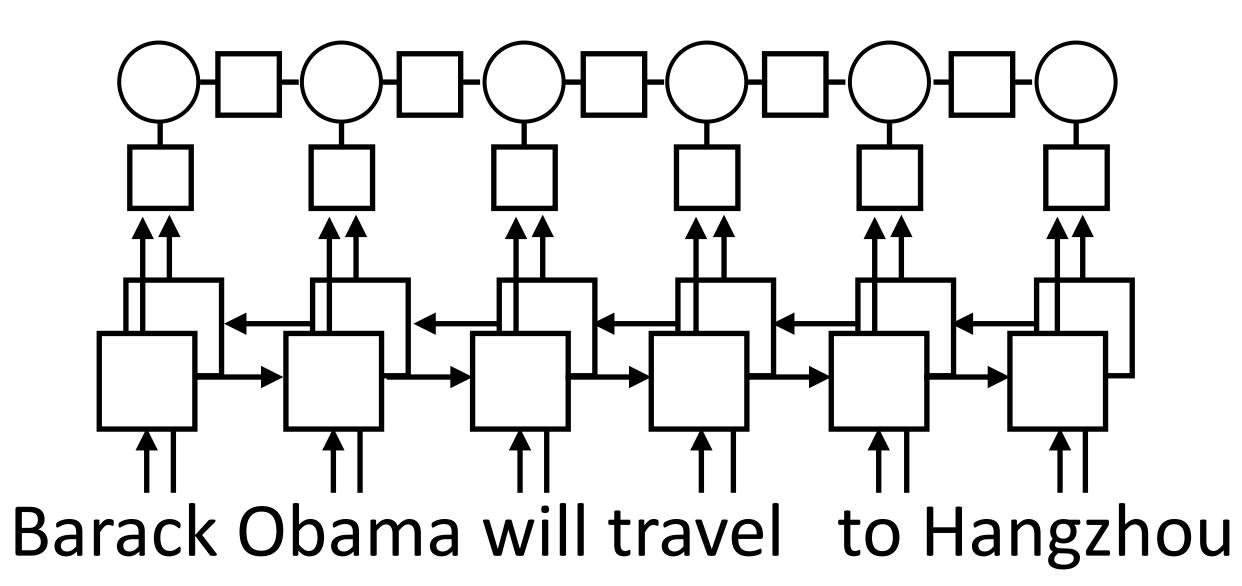
What are the strengths and weaknesses of this model compared to CRFs?



### 0 O O B-LOC O O B-ORG O 0 B-PER I-PER **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. **PERSON** LOC ORG



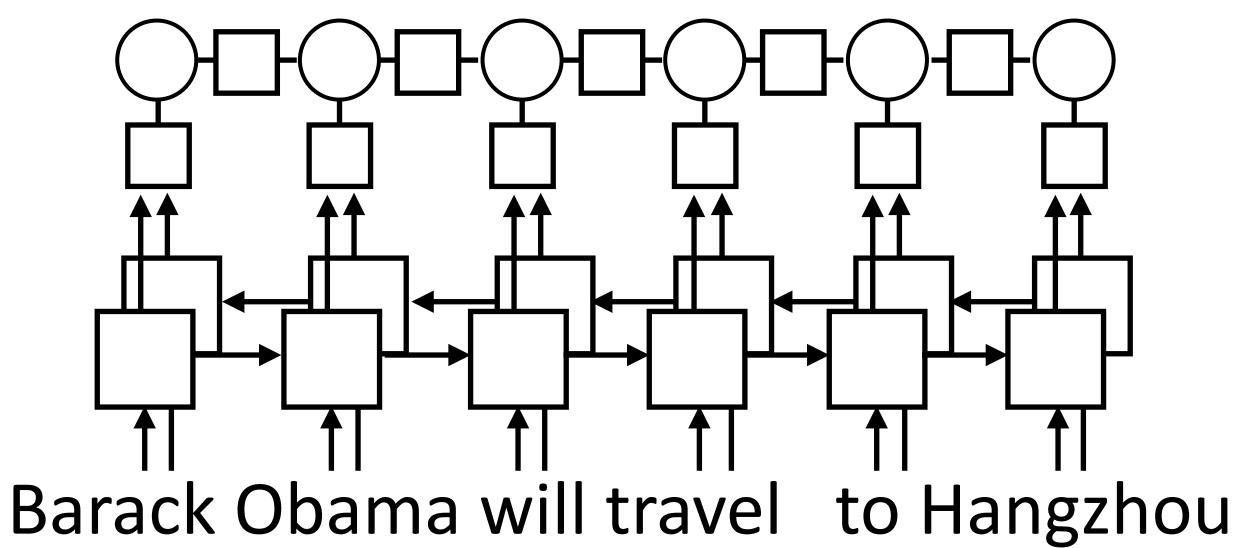
### 0 O O B-LOC O O B-ORG O 0 B-PER I-PER **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting.



- LOC ORG

### O O B-LOC O O B-ORG O 0 I-PER **B-PER Barack Obama** will travel to **Hangzhou** today for the **G20** meeting.

### PERSON

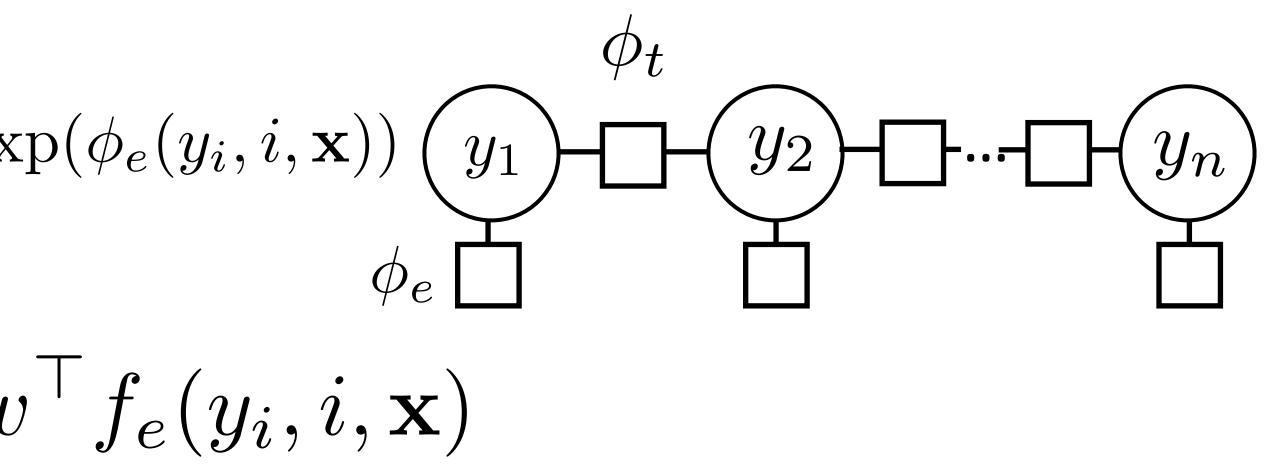


Neural CRFs: bidirectional LSTMs (or some NN) compute emission potentials, capture structural constraints in transition potentials

- LOC ORG

$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

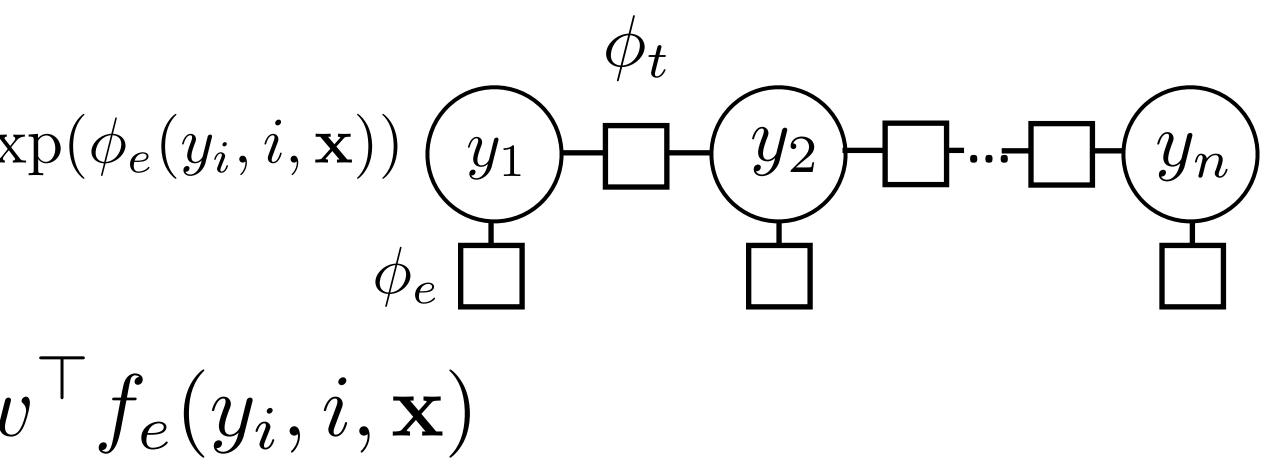
• Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$ 



$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

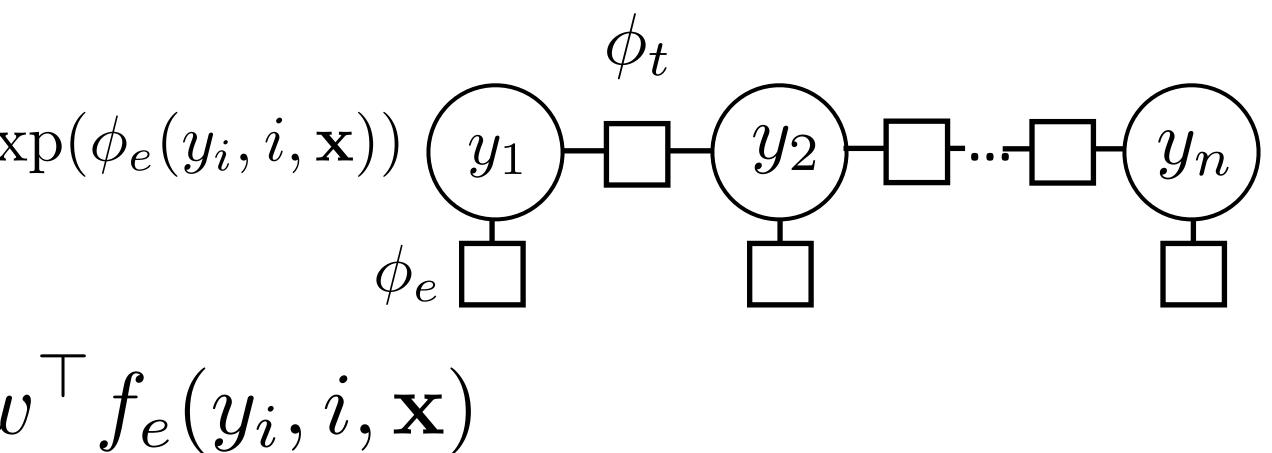
• Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$ 

• Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{y_i}^{\top} f(i, \mathbf{x})$  W is a num\_tags x len(f) matrix



$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

- Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$
- Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{u_i}^\top f(i, \mathbf{x})$  W is a num\_tags x len(f) matrix
- words around position *i*, or the *i*th output of an LSTM, ...

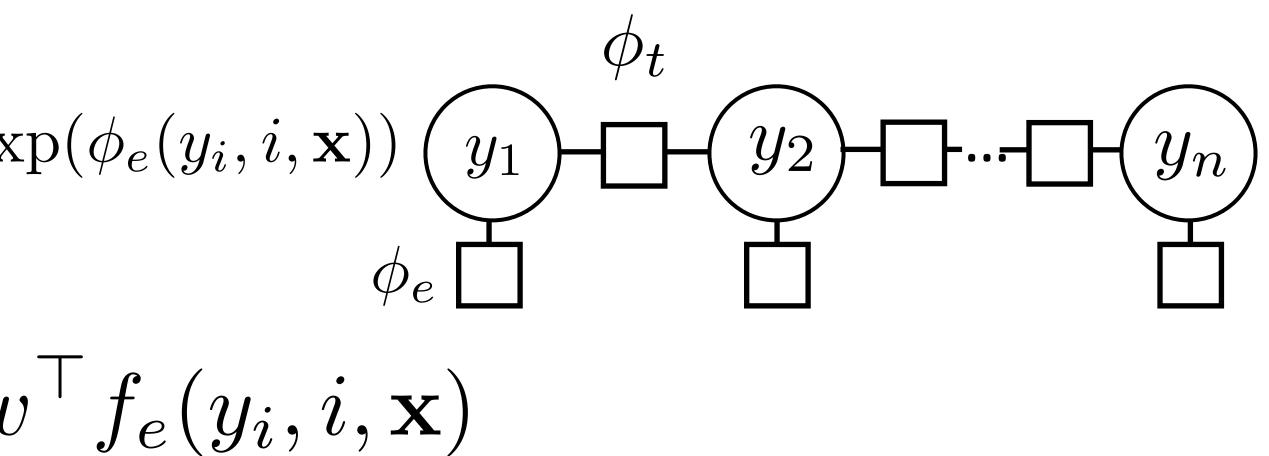


•  $f(i, \mathbf{x})$  could be the output of a feedforward neural network looking at the



$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

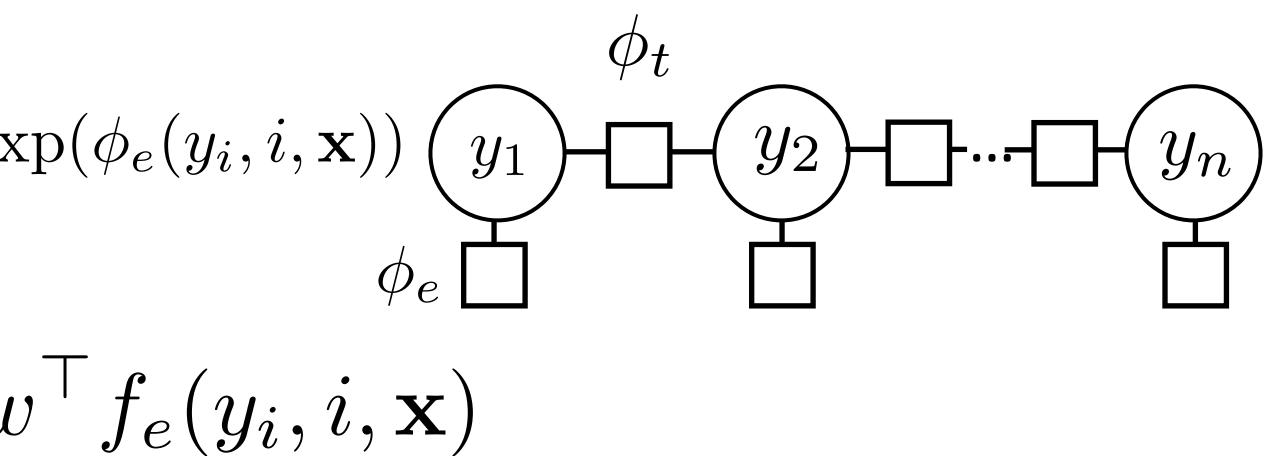
- Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$
- Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{u_i}^\top f(i, \mathbf{x})$  W is a num\_tags x len(f) matrix f(i, x) could be the output of a feedforward neural network looking at the words around position *i*, or the *i*th output of an LSTM, ...
- Neural network computes unnormalized potentials that are consumed and "normalized" by a structured model





$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

- Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$
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- Neural network computes unnormalized potentials that are consumed and "normalized" by a structured model
- Inference: compute f, use Viterbi

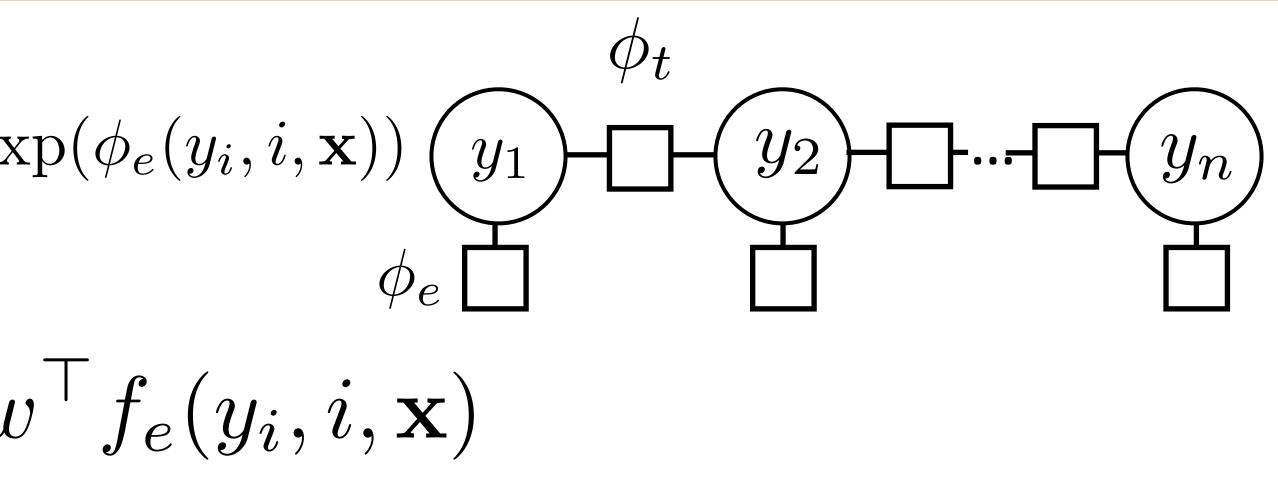




$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

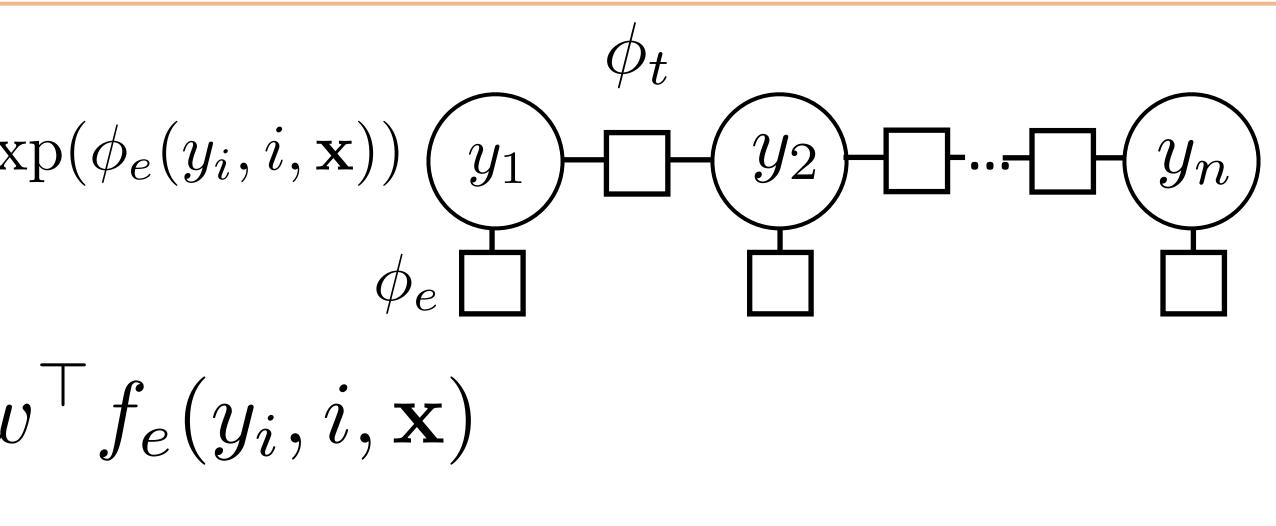
• Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$ 

Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{y_i}^{\top} f(i, \mathbf{x})$ 



$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

- Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$
- Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{y_i}^{\top} f(i, \mathbf{x})$  $\frac{\partial \mathcal{L}}{\partial \phi_{e,i}} = -P(y_i = s | \mathbf{x}) + I[s \text{ is gold}] \quad \text{``error signal'', compute with F-B}$



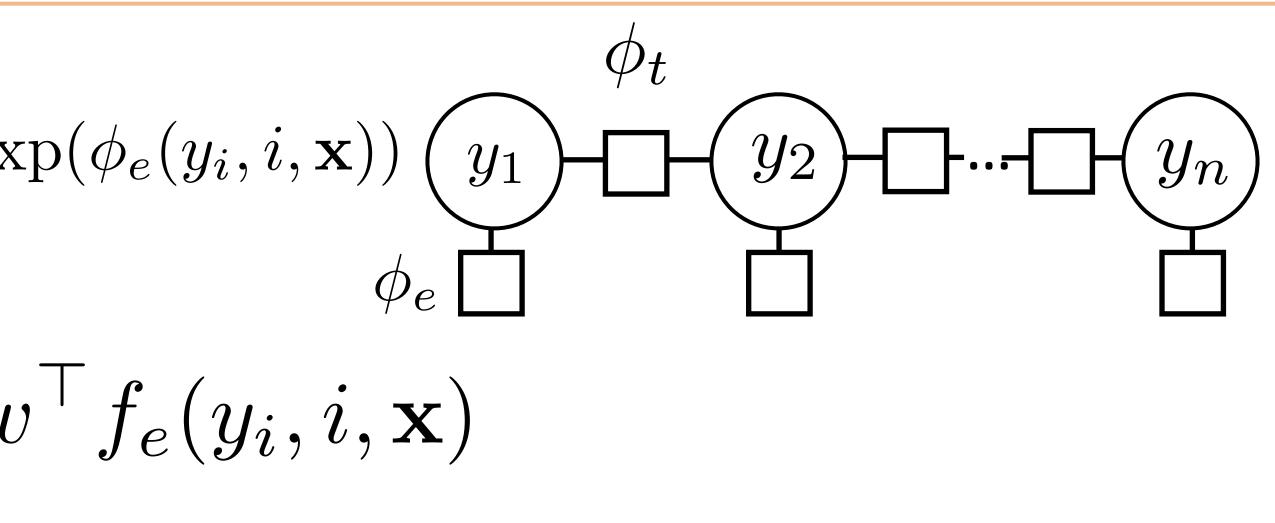


$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

- Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$
- Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{u_i}^{\top} f(i, \mathbf{x})$  $\frac{\partial \mathcal{L}}{\partial \phi_{e,i}} = -P(y_i = s | \mathbf{x}) + I[s \text{ is gold}] \quad \text{``error signal'', compute with F-B}$

 $w_i$ 

For linear model:  $\frac{\partial \phi_{e,i}}{\partial \phi_{e,i}} = f_{e,i}($ 



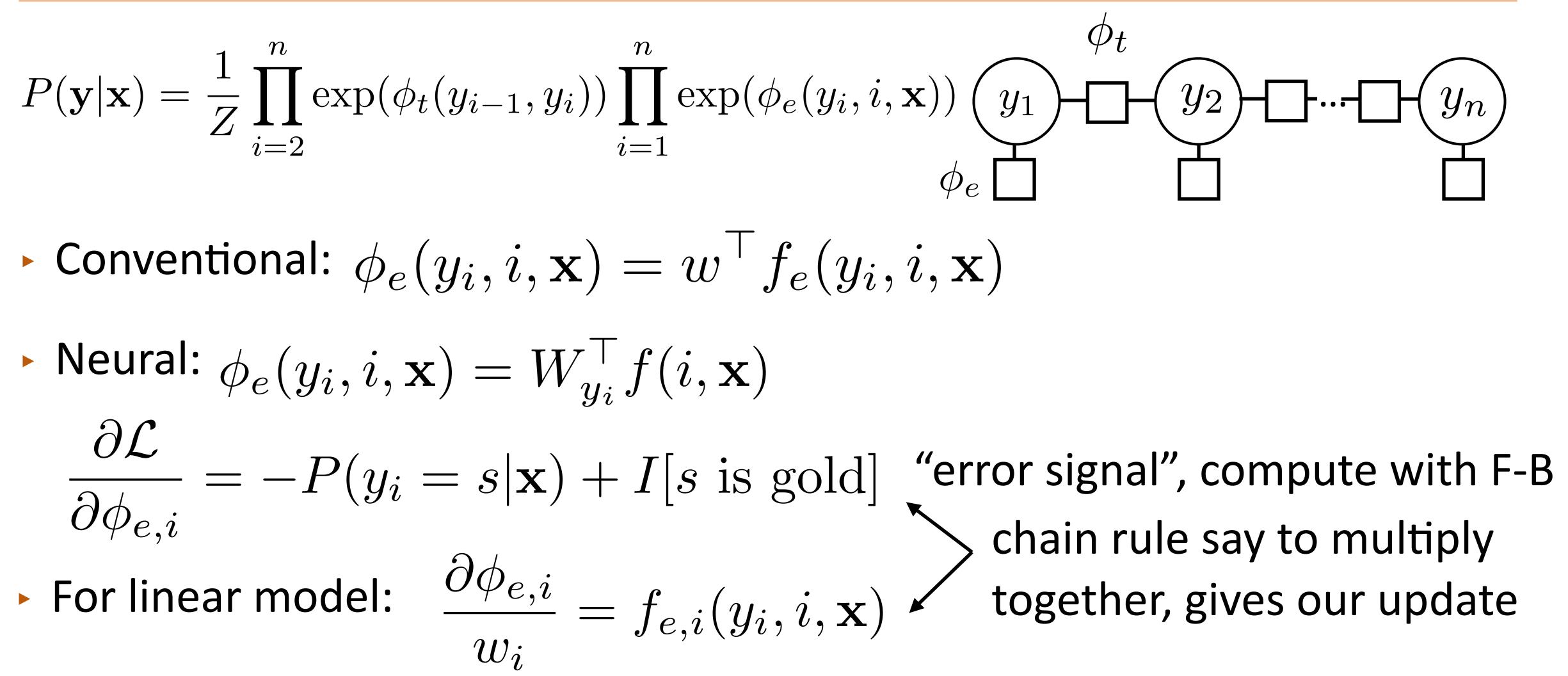
$$(y_i, i, \mathbf{x})$$



$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

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- Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{u_i}^{\top} f(i, \mathbf{x})$

 $w_i$ 

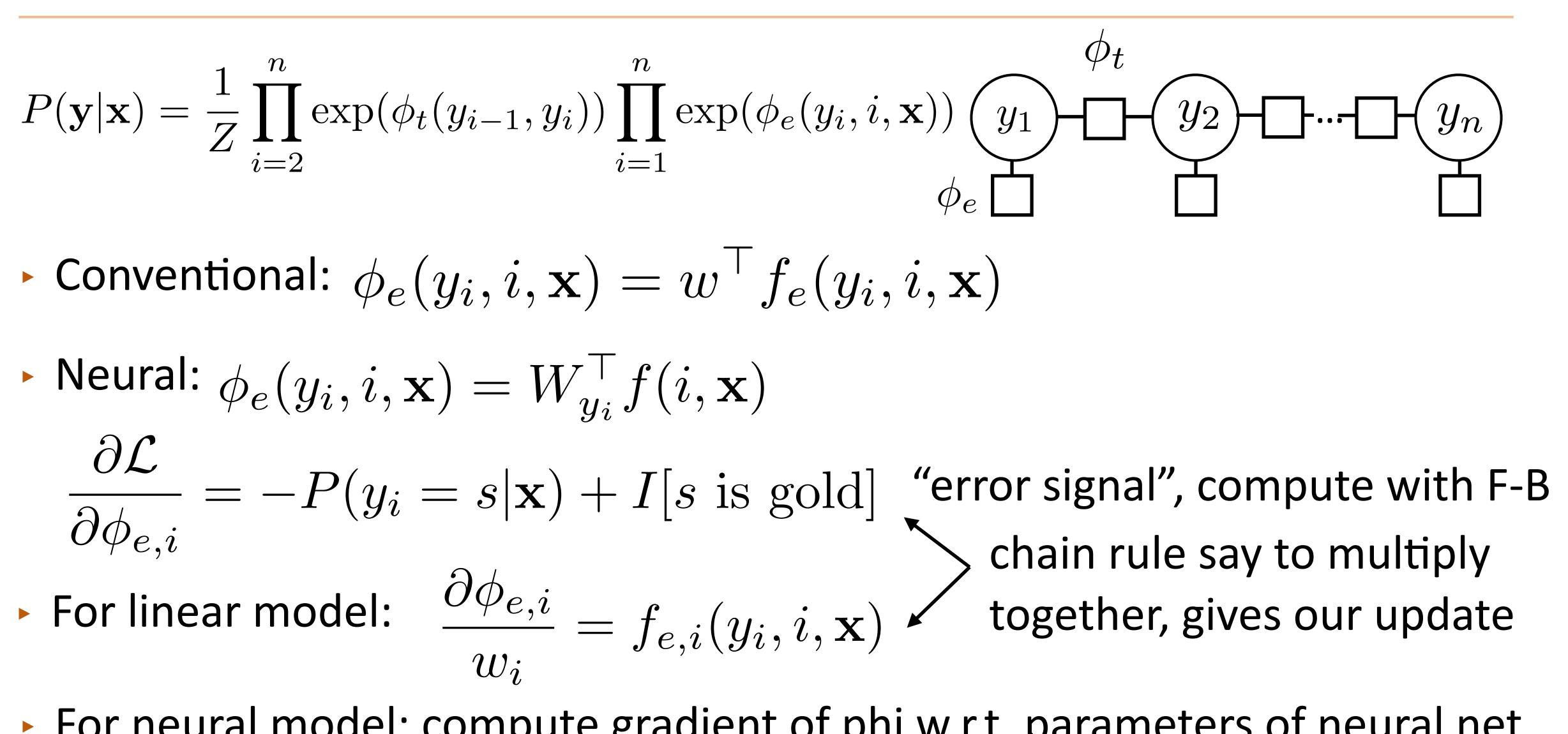




$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z} \prod_{i=2}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^{n} \exp(\phi_t(y_{i-1}, y_i)) \prod_{i=1}^$$

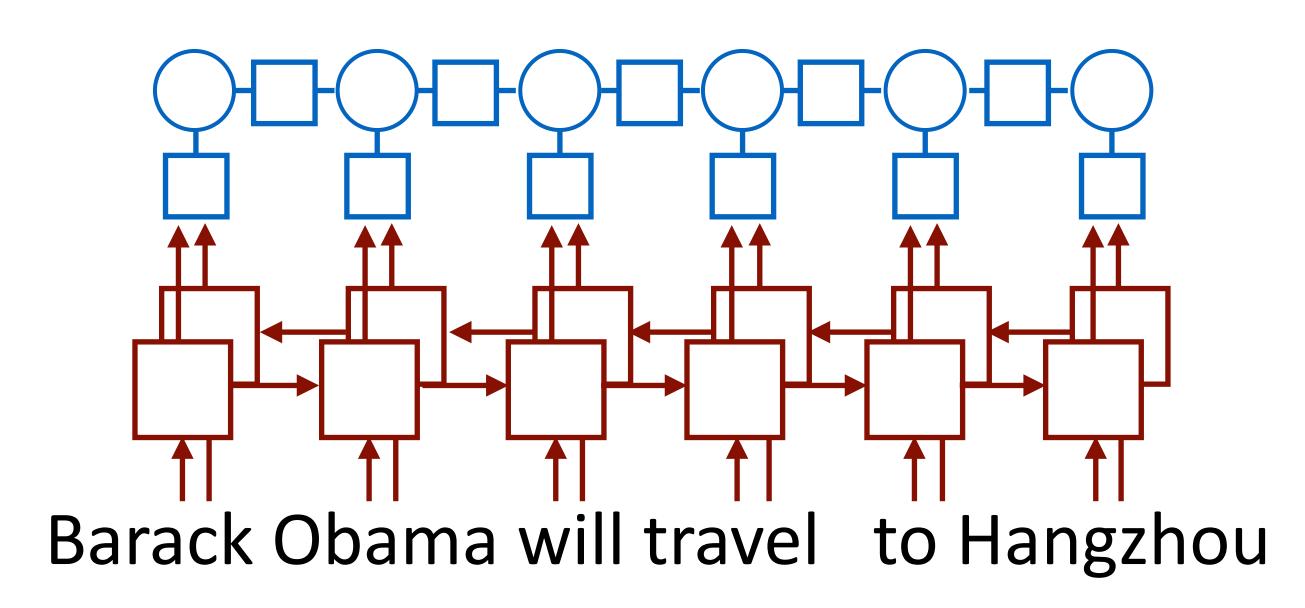
- Conventional:  $\phi_e(y_i, i, \mathbf{x}) = w^{\top} f_e(y_i, i, \mathbf{x})$
- Neural:  $\phi_e(y_i, i, \mathbf{x}) = W_{u_i}^{\top} f(i, \mathbf{x})$

 $W_i$ 

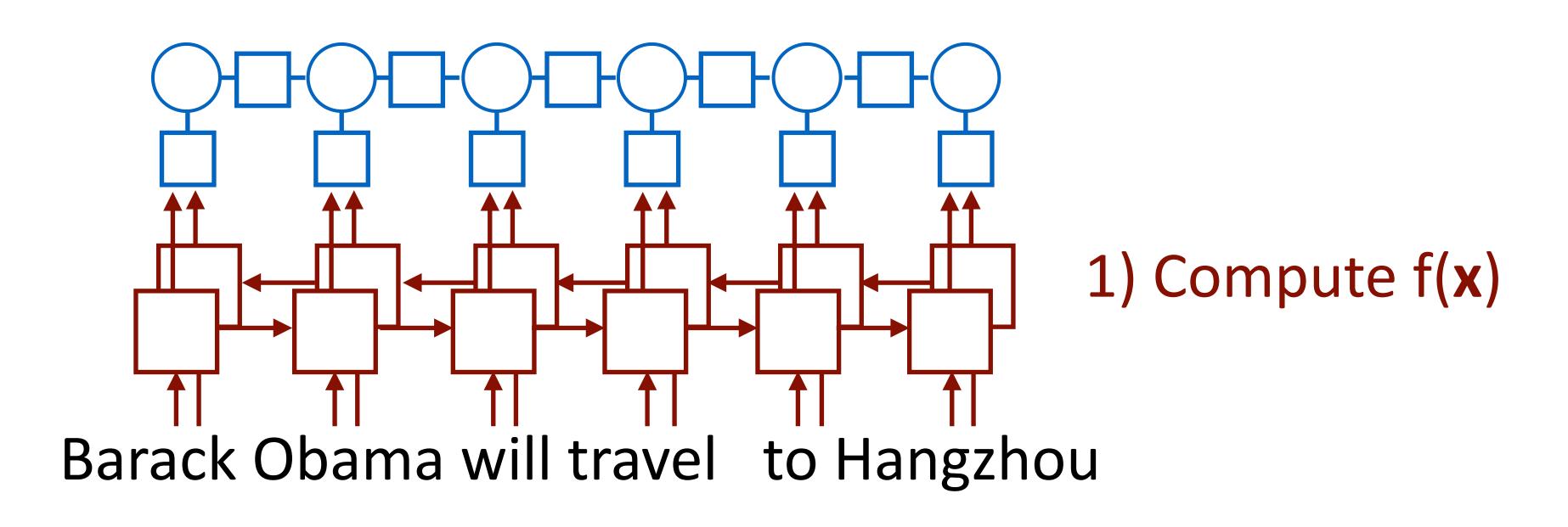


For neural model: compute gradient of phi w.r.t. parameters of neural net

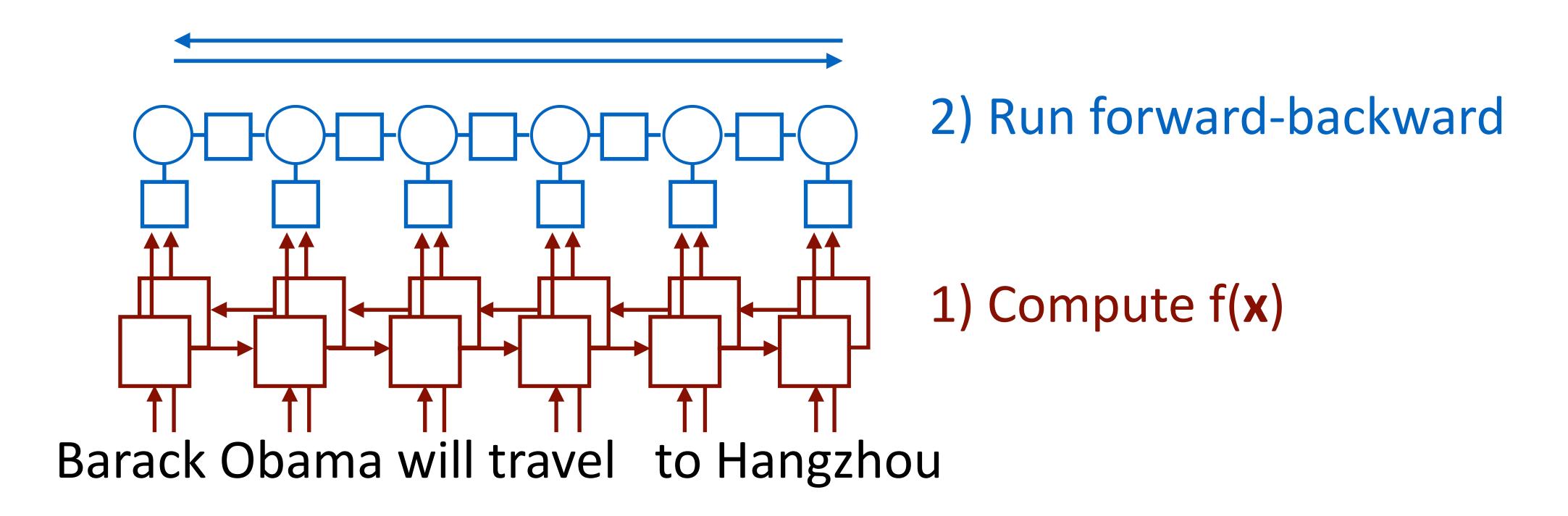
### 0 O O B-LOC O O B-ORG O O B-PER I-PER **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. LOC ORG



### O O B-LOC O O B-ORG O 0 B-PER I-PER $\mathbf{O}$ **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. LOC ORG

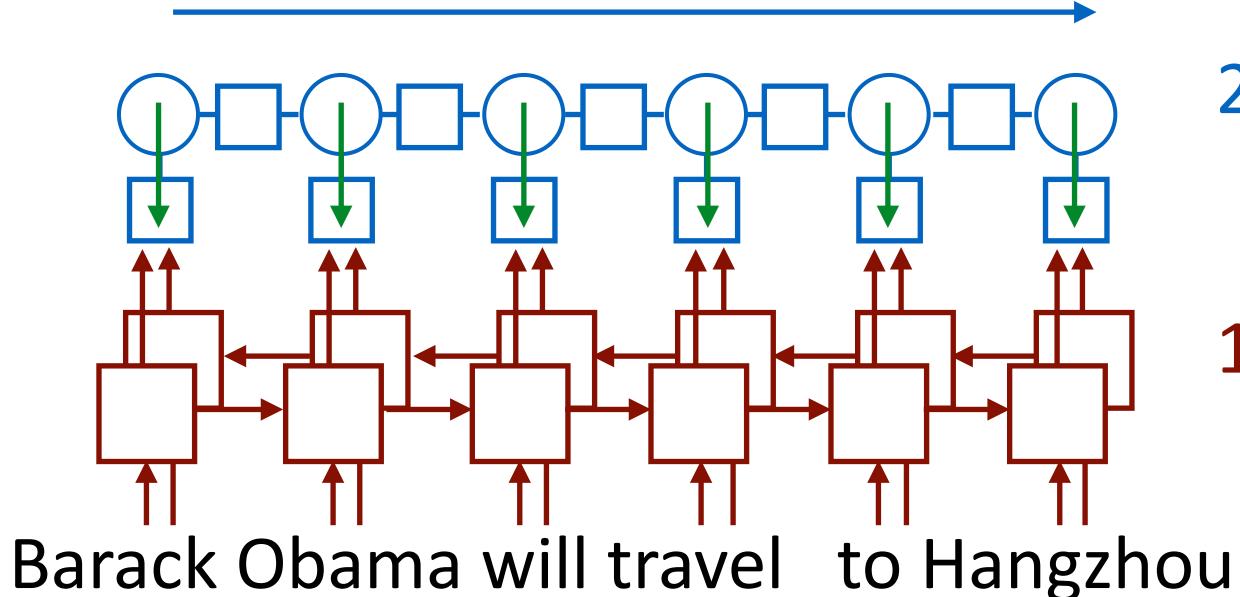


### **B-LOC** O O O B-ORG O 0 0 0 I-PER **B-PER** ()**Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. LOC ORG



### O O O B-ORG **B-LOC** 0 0 ( $\mathbf{O}$ I-PER **B-PER Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. LOC ORG

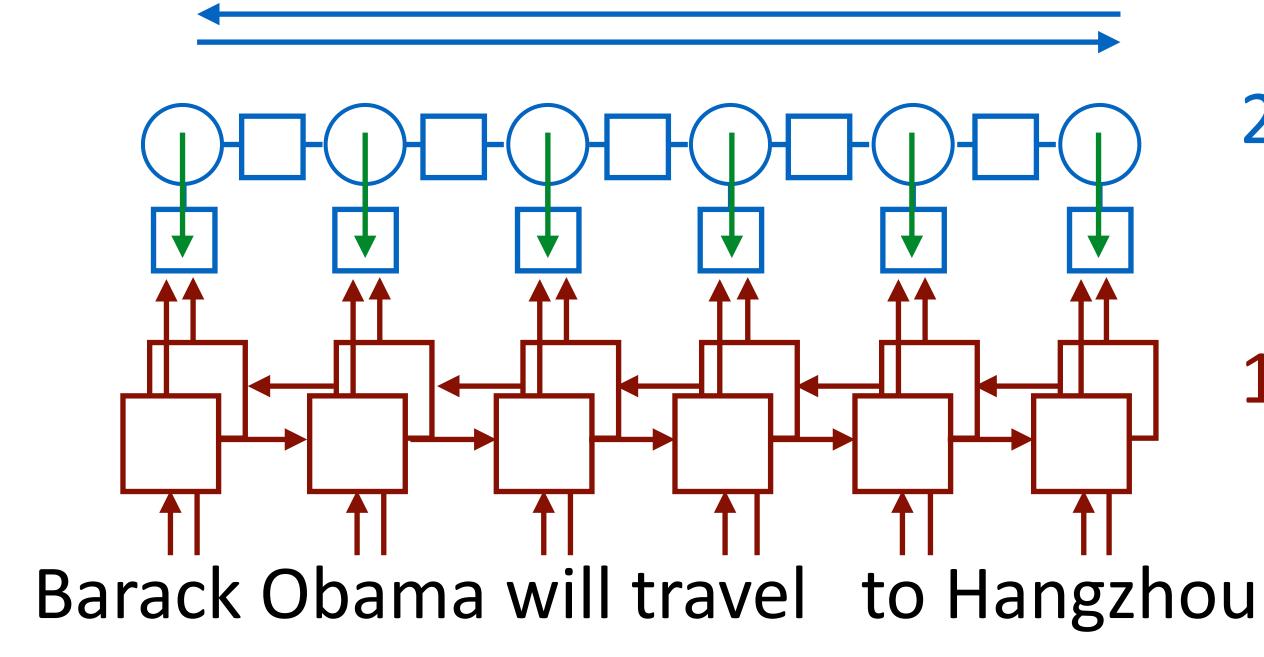
PERSON



### 2) Run forward-backward 3) Compute error signal 1) Compute f(x)

### **B-LOC** O O O B-ORG Ο ()()**B-PER** I-PER **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. LOC ORG

PERSON



## 2) Run forward-backward

3) Compute error signal

### 1) Compute f(x)

4) Backprop (no knowledge of sequential structure required)





## **FFNN Neural CRF for NER**

### O O B-LOC O O B-ORG O 0 0 B-PER I-PER

**PERSON** 

### **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting.

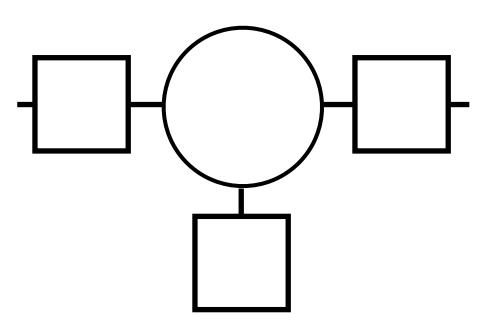
LOC

ORG

## FFNN Neural CRF for NER

### O O B-LOC O O B-ORG O 0 **B-PER** I-PER Ο

**PERSON** 



to **Hangzhou** today

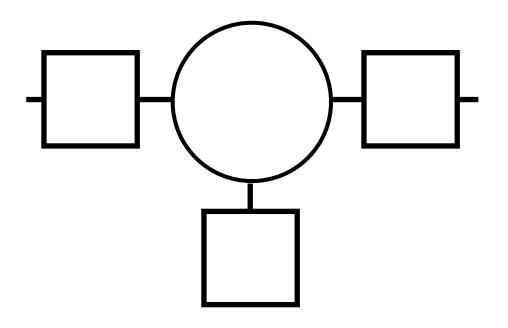
### **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting.

LOC

ORG

### O B-LOC O O B-ORG O 0 ()()LOC ORG

### FFNN Neural CRF for NER I-PER **B-PER Barack Obama** will travel to Hangzhou today for the G20 meeting. PERSON





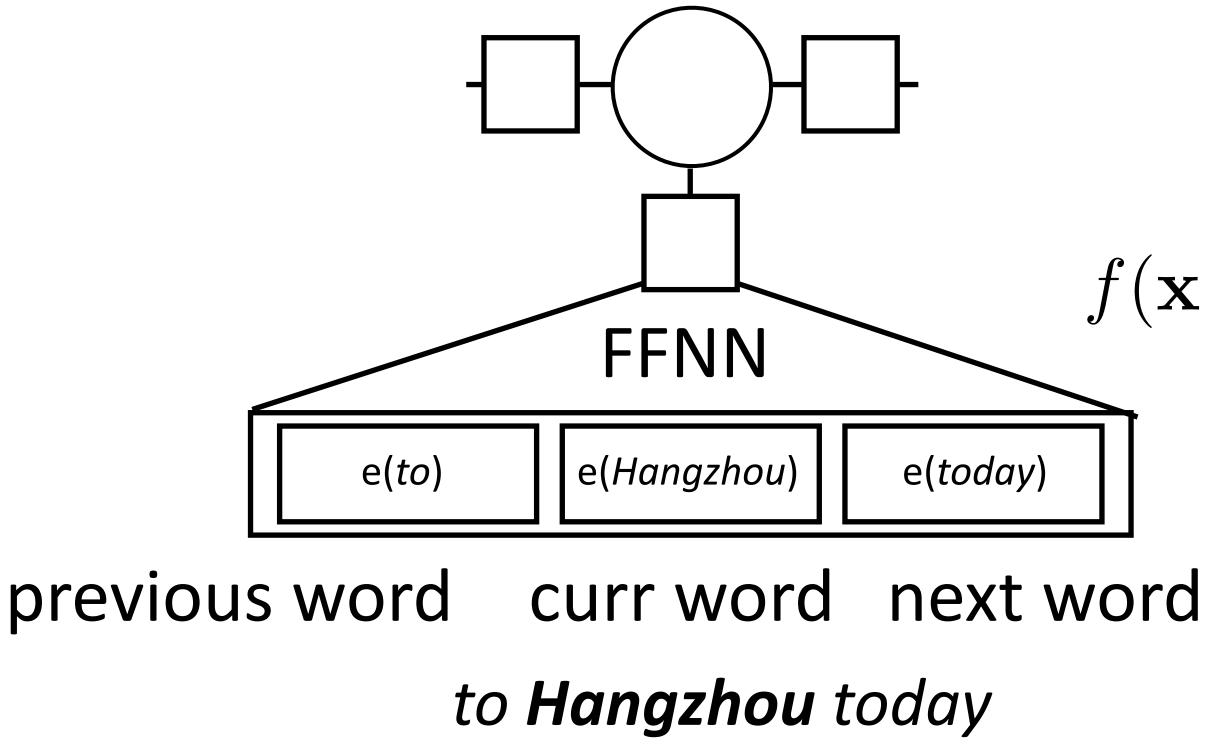
previous word curr word next word to **Hangzhou** today

### $f(\mathbf{x}, i) = [\operatorname{emb}(\mathbf{x}_{i-1}), \operatorname{emb}(\mathbf{x}_i), \operatorname{emb}(\mathbf{x}_{i+1})]$



### O B-LOC O O B-ORG O 0 $\mathbf{O}$ ()LOC ORG

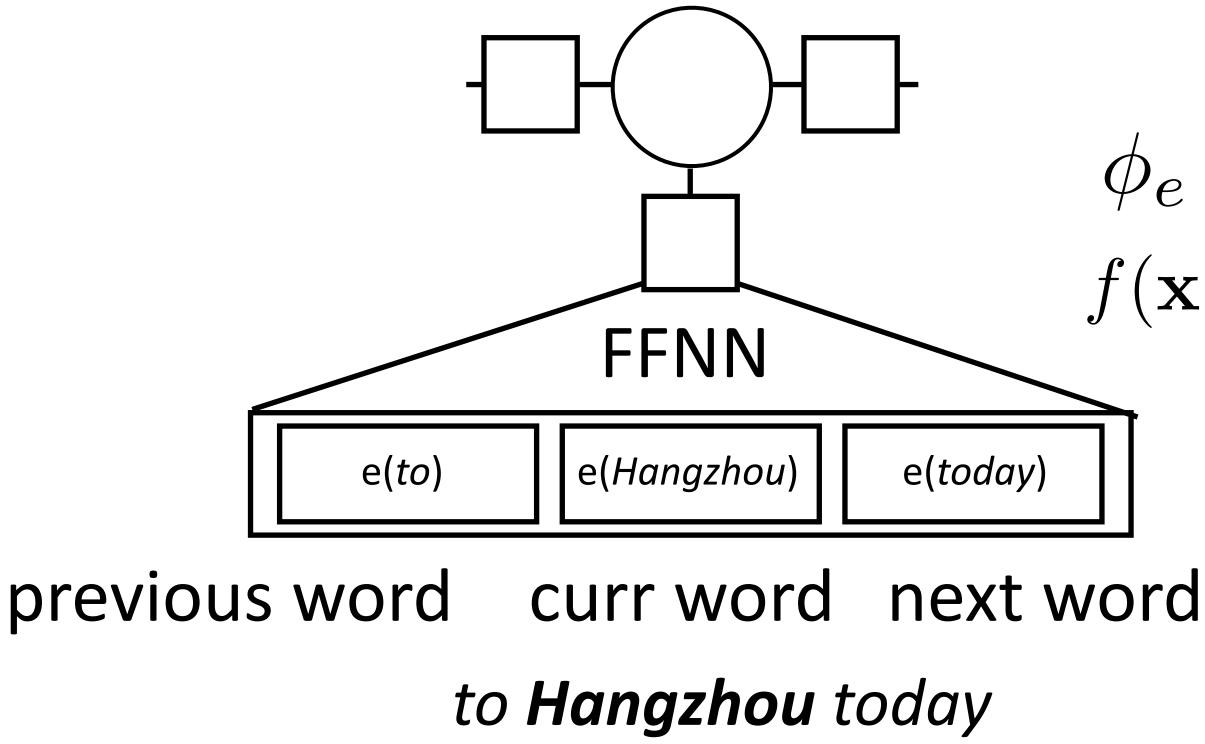
### FFNN Neural CRF for NER I-PER **B-PER Barack Obama** will travel to Hangzhou today for the G20 meeting. PERSON



### $f(\mathbf{x}, i) = [\operatorname{emb}(\mathbf{x}_{i-1}), \operatorname{emb}(\mathbf{x}_i), \operatorname{emb}(\mathbf{x}_{i+1})]$

### 0 B-LOC O O B-ORG $\mathbf{O}$ $\mathbf{O}$ LOC ORG

### FFNN Neural CRF for NER **B-PER** I-PER **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting. PERSON

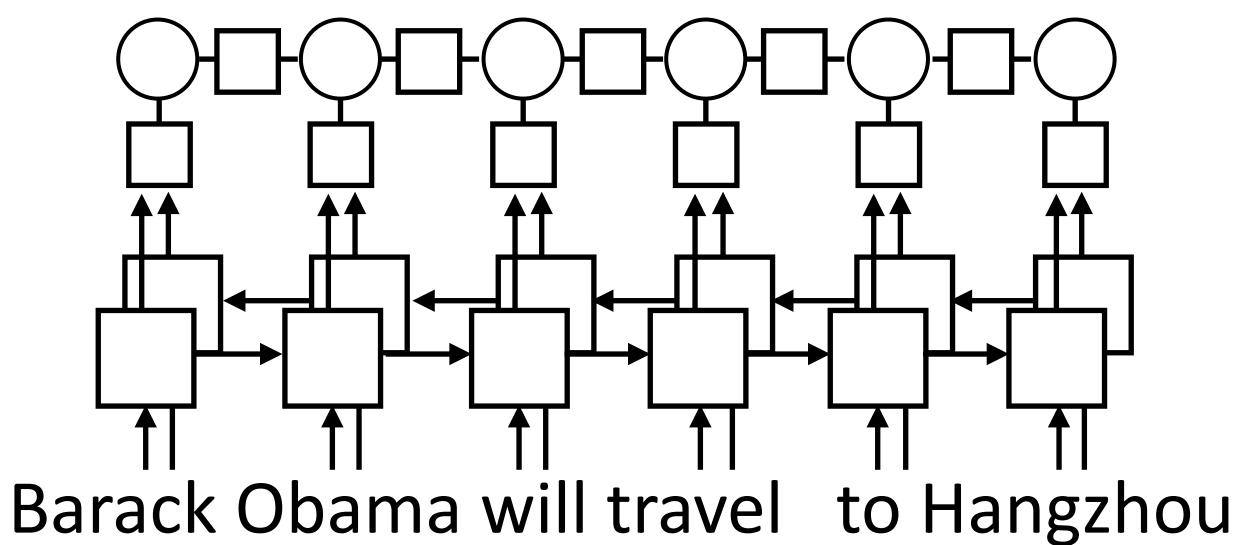


### $\phi_e = Wg(Vf(\mathbf{x}, i))$ $f(\mathbf{x}, i) = [\operatorname{emb}(\mathbf{x}_{i-1}), \operatorname{emb}(\mathbf{x}_i), \operatorname{emb}(\mathbf{x}_{i+1})]$

## LSTM Neural CRFs

### B-PER I-PER $\mathbf{O}$

### PERSON

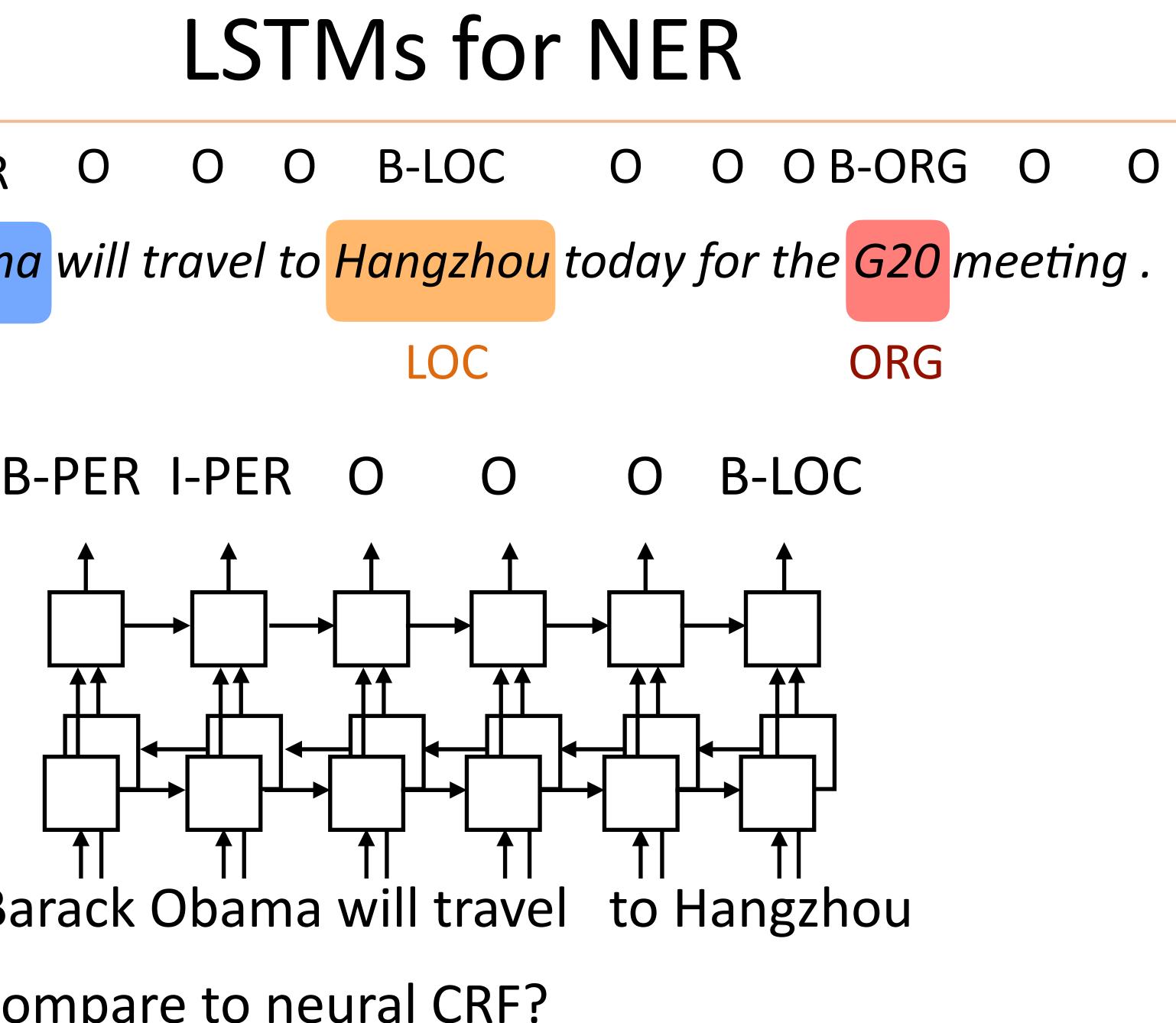


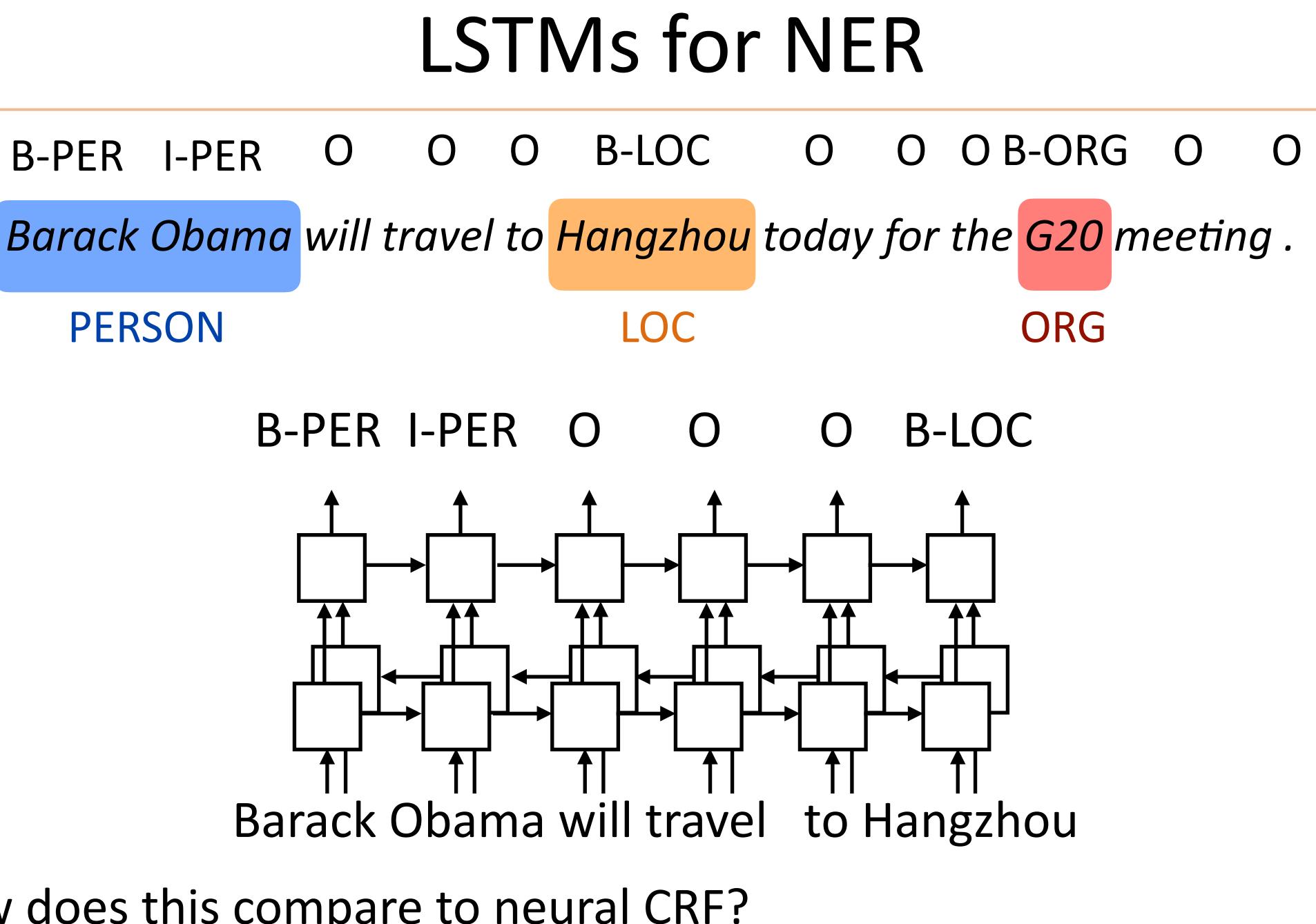
Bidirectional LSTMs compute emission (or transition) potentials

- O O B-LOC O O B-ORG O 0
- **Barack Obama** will travel to **Hangzhou** today for the **G20** meeting.
  - LOC ORG

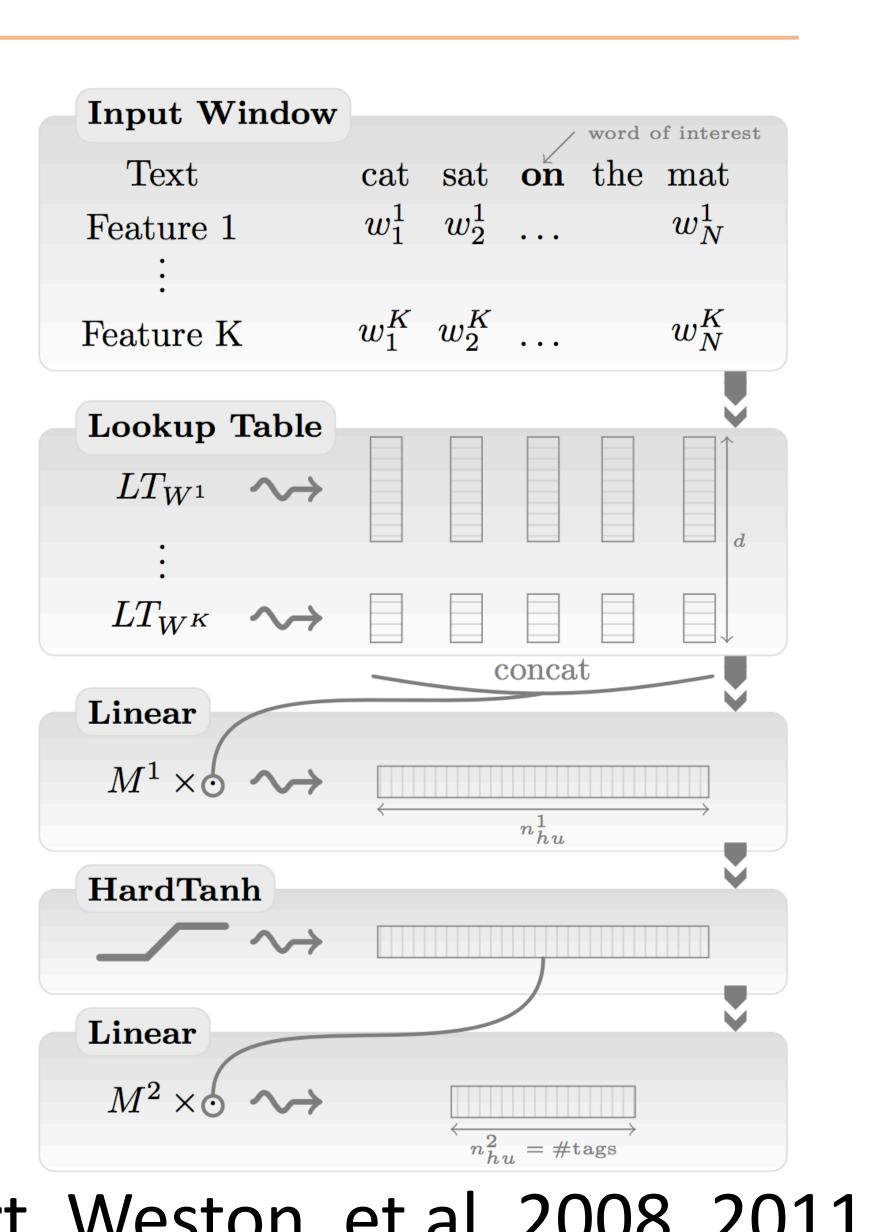
## B-PER I-PER

### PERSON

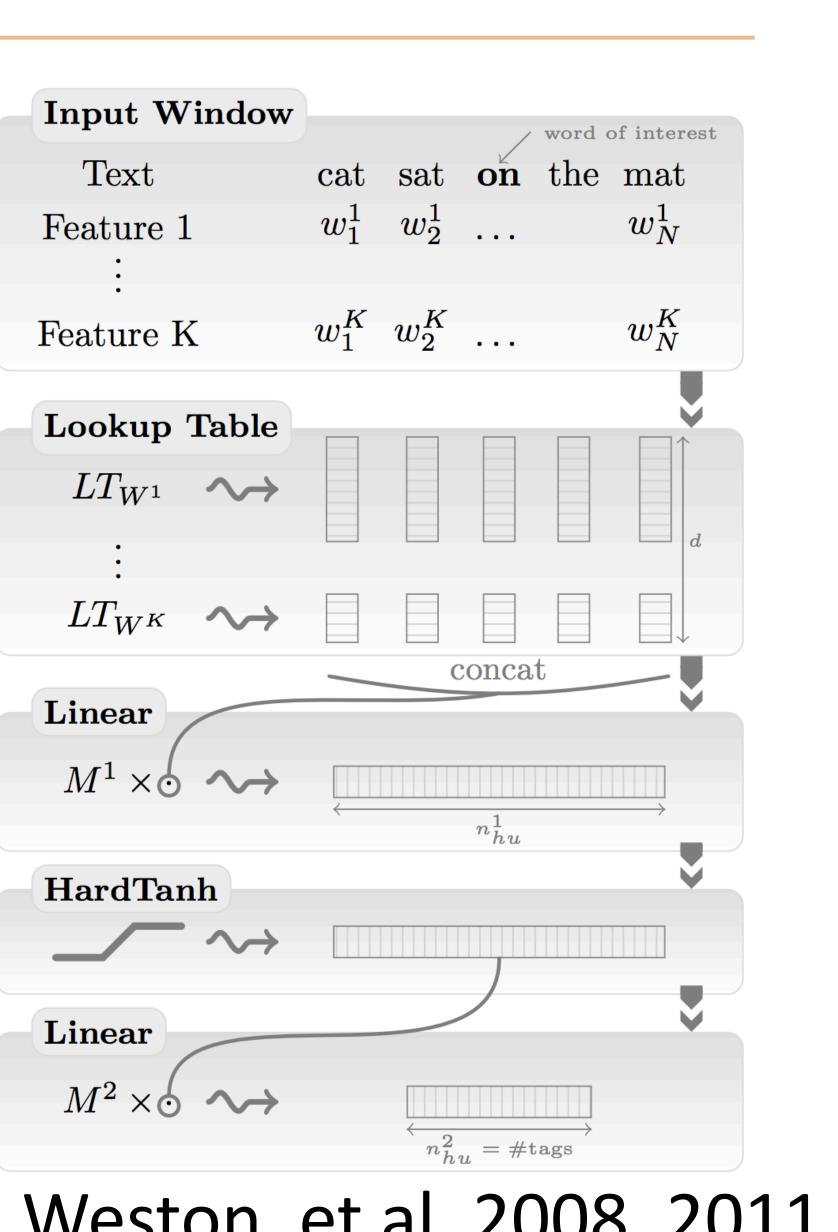




How does this compare to neural CRF?

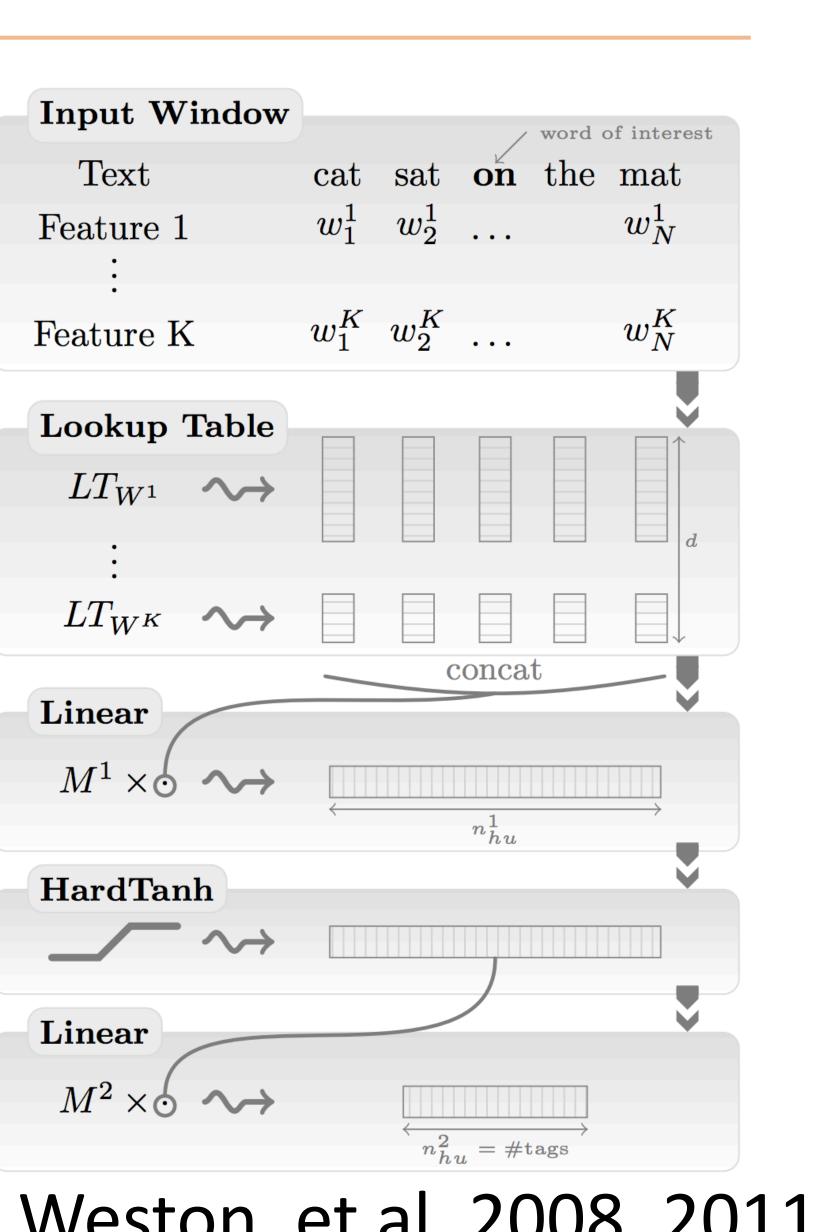


Approach	POS	CHUNK	NER	SRL
	(PWA)	(F1)	(F1)	(F1)
<b>Benchmark Systems</b>	97.24	94.29	89.31	77.92
NN+WLL	96.31	89.13	79.53	55.40
NN+SLL	96.37	90.33	81.47	70.99
NN+WLL+LM1	97.05	91.91	85.68	58.18
NN+SLL+LM1	97.10	93.65	87.58	73.84
NN+WLL+LM2	97.14	92.04	86.96	58.34
NN+SLL+LM2	97.20	93.63	88.67	74.15



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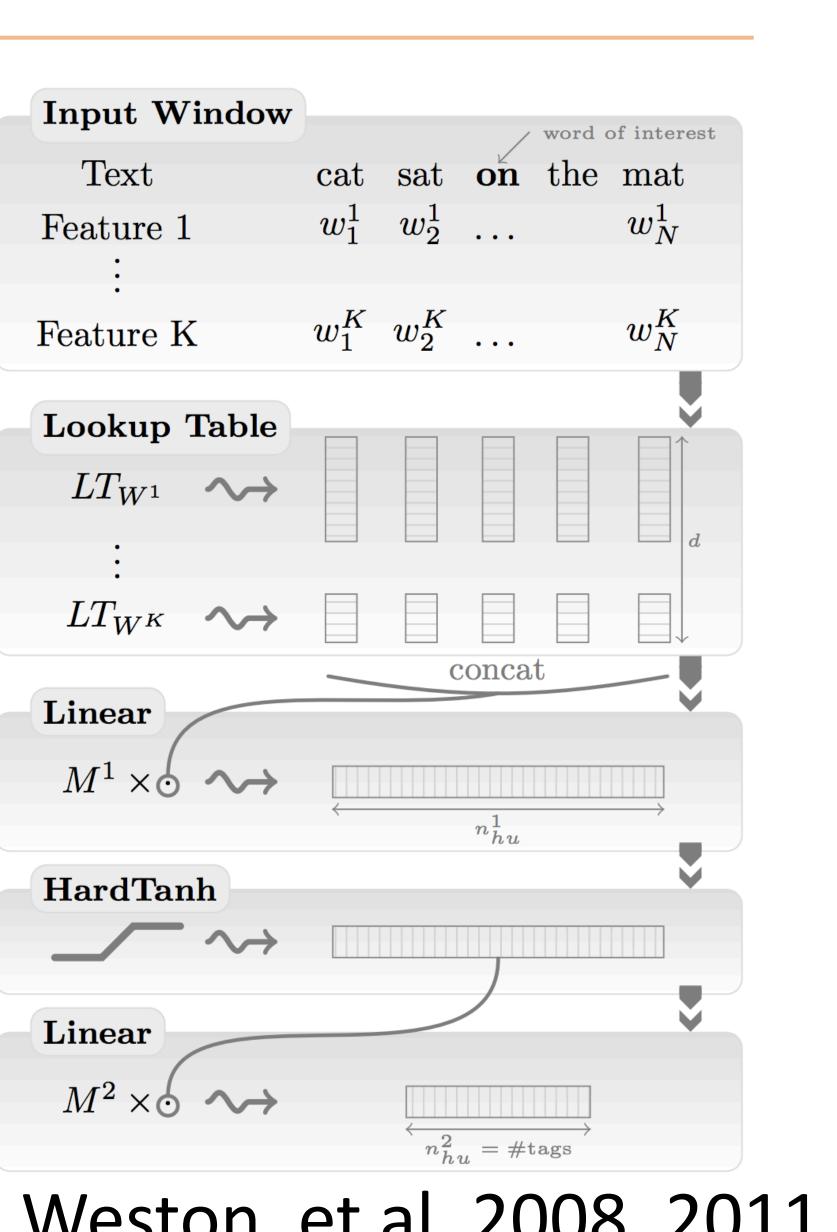
WLL: independent classification; SLL: neural CRF



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WLL: independent classification; SLL: neural CRF

 LM2: word vectors learned from a precursor to word2vec/GloVe, trained for 2 weeks (!) on Wikipedia

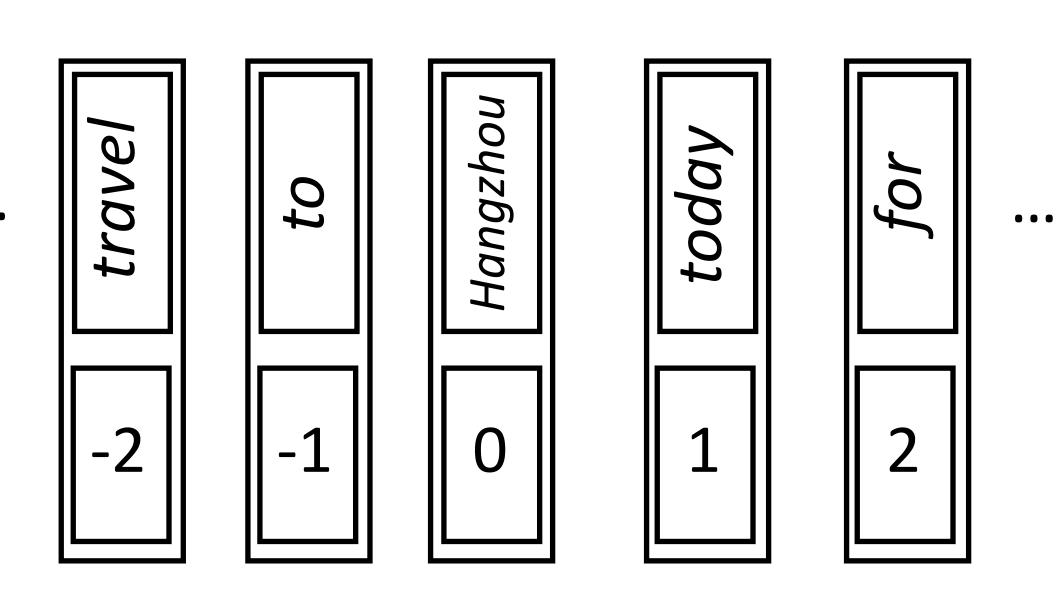


### travel to Hangzhou today for

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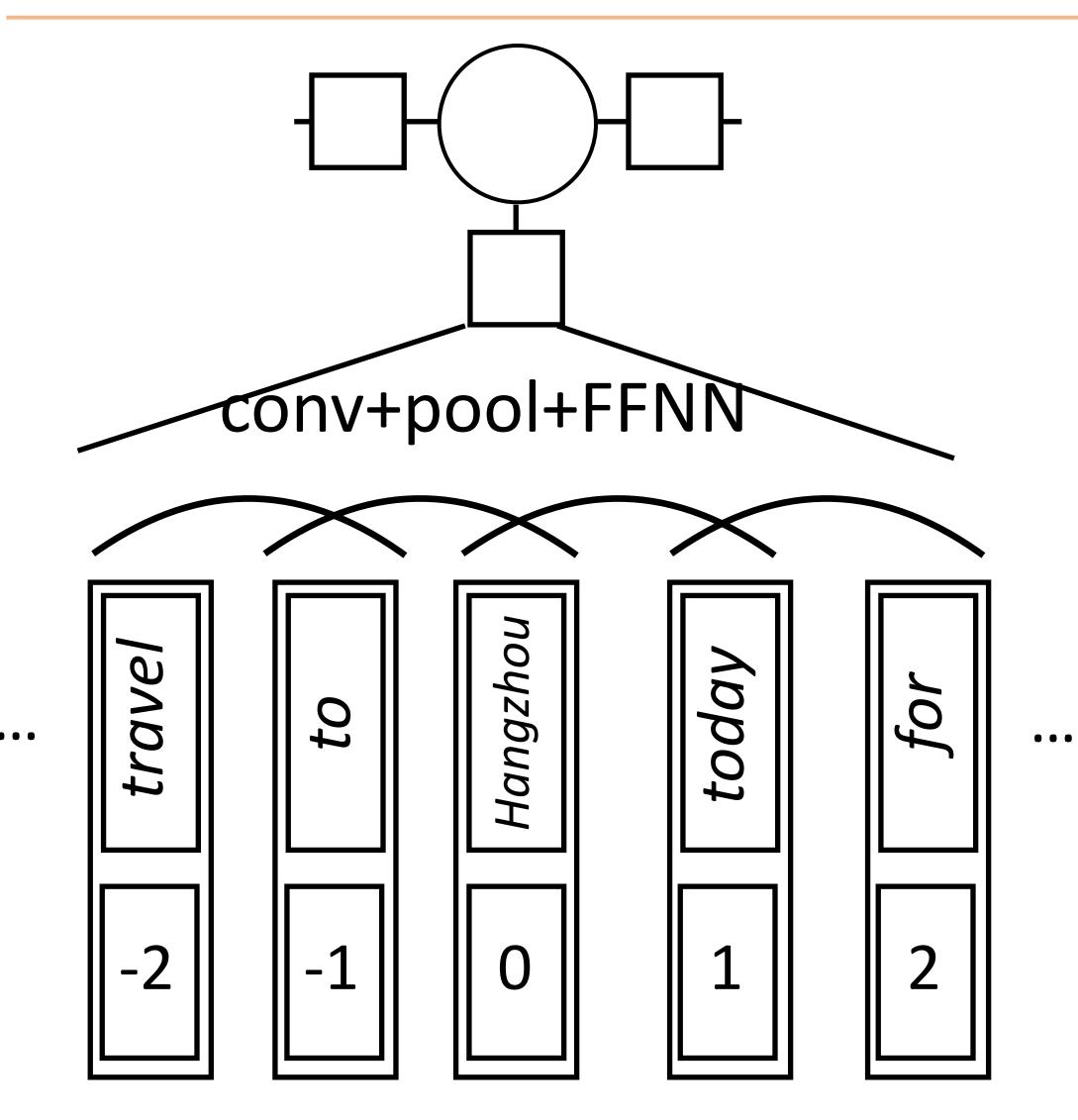
 Append to each word vector an embedding of the relative position of that word

f



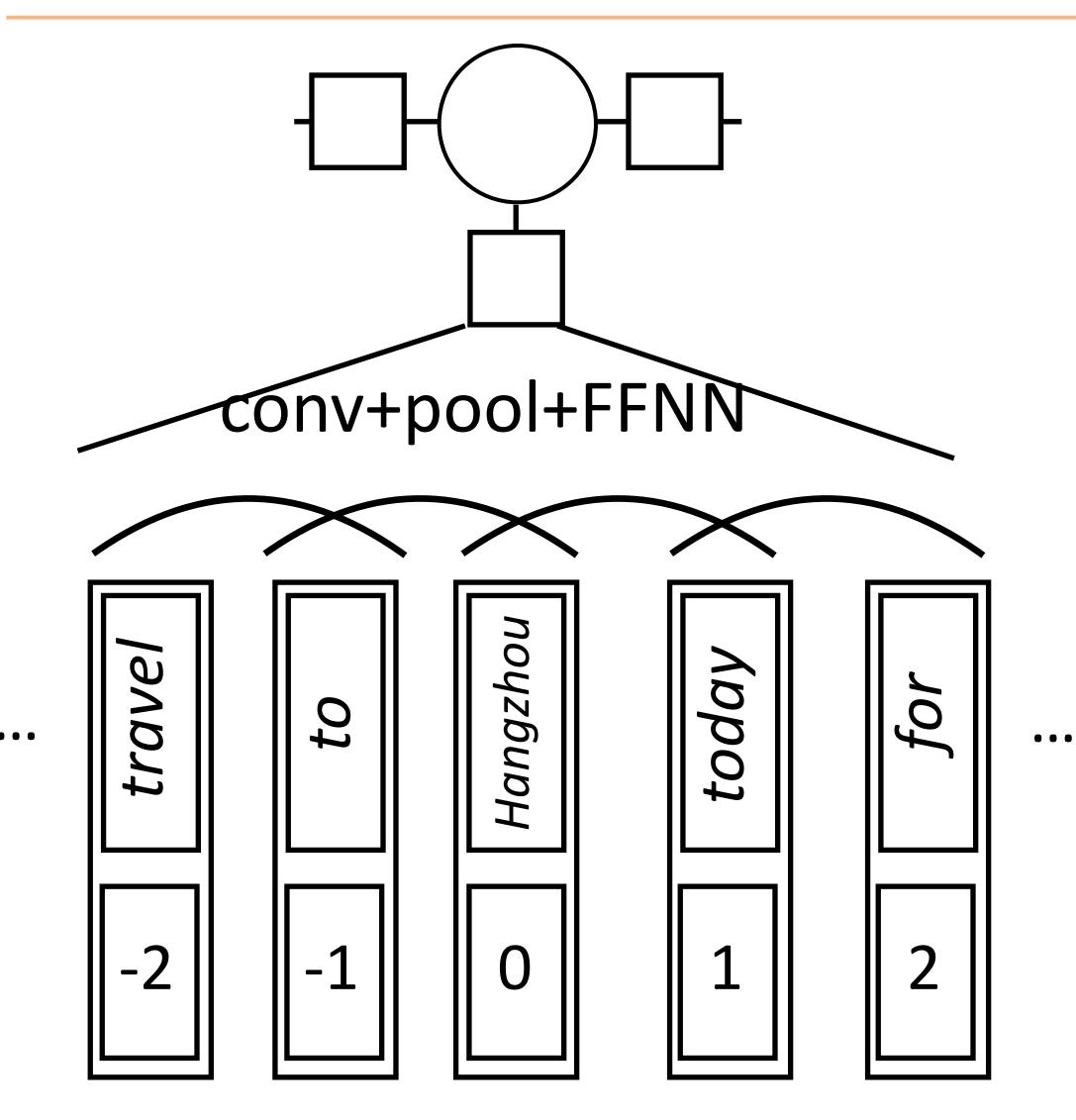
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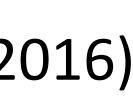
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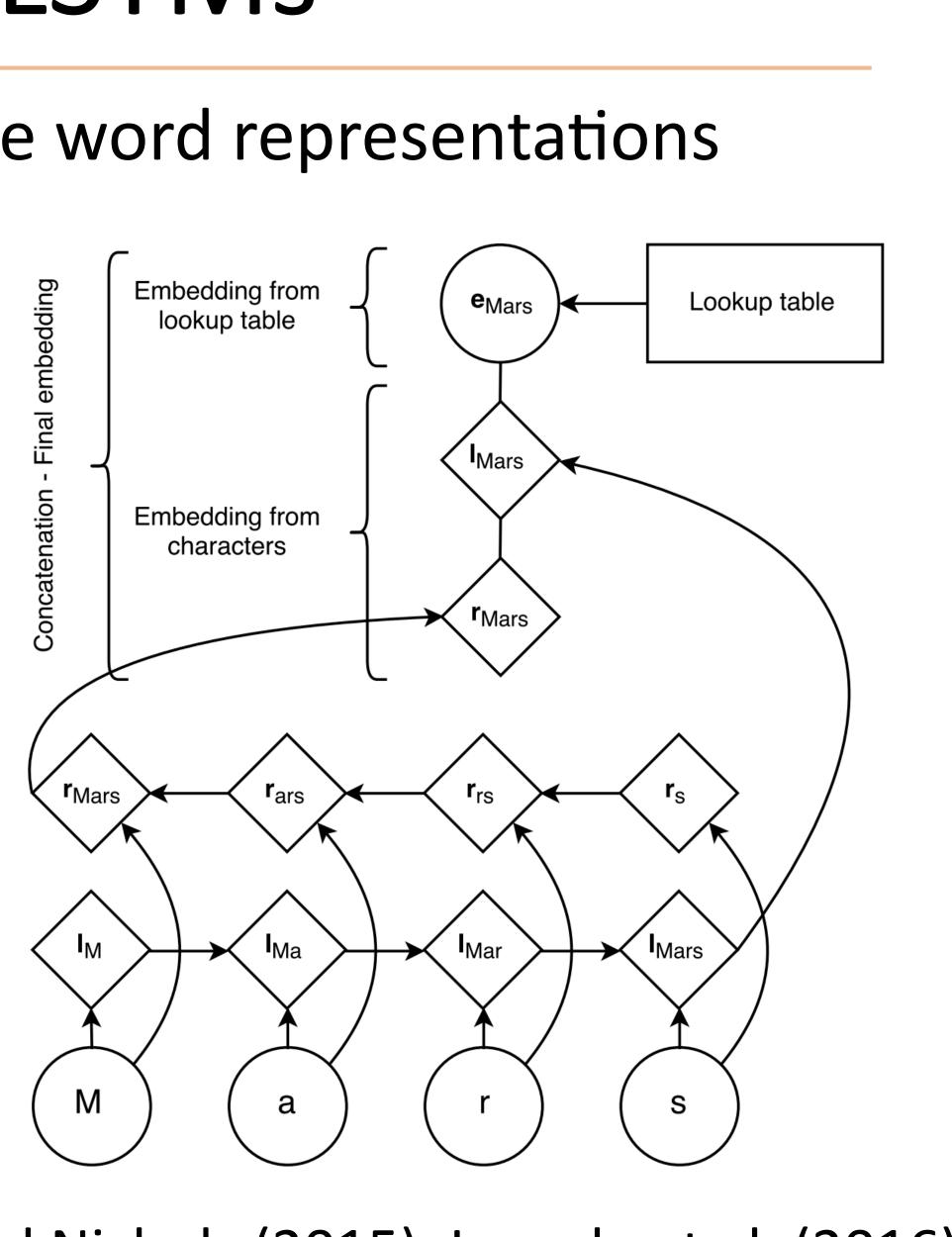
travel to Hangzhou today for

- Append to each word vector an embedding of the relative position of that word
- Convolution over the sentence produces a position-dependent representation

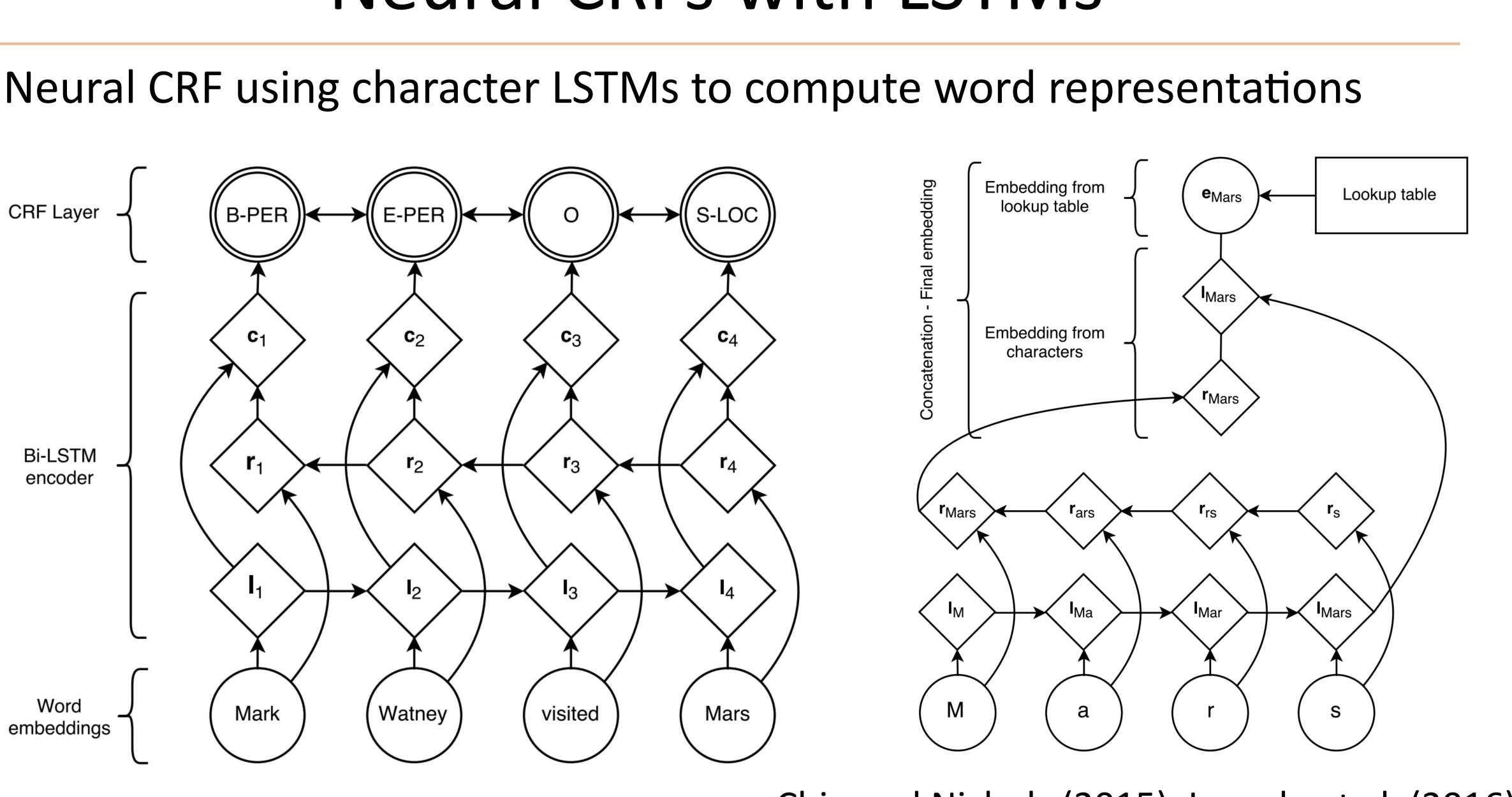
Neural CRF using character LSTMs to compute word representations



### Neural CRF using character LSTMs to compute word representations



### Neural CRF using character LSTMs to compute word representations



- Chiu+Nichols: character CNNs instead of LSTMs
- Lin/Passos/Luo: use external resources like Wikipedia
- LSTM-CRF captures the important aspects of NER: word context (LSTM), sub-word features (character LSTMs), outside knowledge (word embeddings)

Model	$\mathbf{F_1}$
Collobert et al. (2011)*	89.59
Lin and Wu (2009)	83.78
Lin and Wu (2009)*	90.90
Huang et al. (2015)*	90.10
Passos et al. (2014)	90.05
Passos et al. (2014)*	90.90
Luo et al. (2015)* + gaz	89.9
Luo et al. $(2015)^* + gaz + linking$	91.2
Chiu and Nichols (2015)	90.69
Chiu and Nichols (2015)*	90.77
LSTM-CRF (no char)	90.20
LSTM-CRF	90.94



## Takeaways

- CNNs are a flexible way of extracting features analogous to bag of ngrams, can also encode positional information
- All kinds of NNs can be integrated into CRFs for structured inference. Can be applied to NER, other tagging, parsing, ...